

CHARACTERISTIC SUBSURFACES AND DEHN FILLING

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ABSTRACT. Let M be a simple knot manifold. Using the characteristic submanifold theory and the combinatorics of graphs in surfaces, we develop a method for bounding the distance between the boundary slope of an essential surface in M which is not a fiber or a semi-fiber, and the boundary slope of a certain type of singular surface. Applications include bounds on the distances between exceptional Dehn surgery slopes. It is shown that if the fundamental group of $M(\alpha)$ has no non-abelian free subgroup, and if $M(\beta)$ is a reducible manifold which is not homeomorphic to $S^1 \times S^2$ or $P^3 \# P^3$, then $\Delta(\alpha, \beta) \leq 5$. Under the same condition on $M(\beta)$, it is shown that if $M(\alpha)$ is Seifert fibered, then $\Delta(\alpha, \beta) \leq 6$. Moreover, in the latter situation, character variety techniques are used to characterize the topological types of $M(\alpha)$ and $M(\beta)$ in case the bound of 6 is attained.

INTRODUCTION

Many results in the theory of Dehn surgery (see [Go1]) assert that if M is a compact, orientable, atoroidal, irreducible 3-manifold whose boundary is an incompressible torus, and if two Dehn fillings $M(\alpha)$ and $M(\beta)$ have specified properties, then the distance $\Delta(\alpha, \beta)$ of the slopes α and β is bounded by a suitable constant. (The reader is referred to the body of this paper for the definition of “slope” and “distance”, as well as for precise versions of many definitions, statements and proofs that are hinted at in this Introduction.)

In this paper, we define a closed 3-manifold to be *very small* if its fundamental group has no non-abelian free subgroup. The motivating result of the paper, Corollary 7.4.4, asserts that if $M(\alpha)$ is very small and $M(\beta)$ is a reducible manifold other than $S^2 \times S^1$ or $P^3 \# P^3$, then $\Delta(\alpha, \beta) \leq 5$. This follows from the following stronger result which deals with essential planar surfaces in M which are not semi-fibers (see 1.3).

Corollary 7.4.3. *Let M be a simple knot manifold, and let $F \subset M$ be an essential planar surface with boundary slope β which is not a semi-fiber. Let α be a slope in ∂M . If $M(\alpha)$ is very small, or more generally if $F \subset M \subset M(\alpha)$ is not π_1 -injective in $M(\alpha)$, then $\Delta(\alpha, \beta) \leq 5$.*

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Corollary 6.2.3 gives a qualitatively similar conclusion when $M(\alpha)$ is very small and β is the boundary slope of an essential bounded surface F of arbitrary genus which is not a semi-fiber. Here the upper bound for $\Delta(\alpha, \beta)$ is $15 + (20g - 15)/m$, where g is the genus of F and m is the number of components of ∂F . Note that, while this result does provide an upper bound in the case where F is planar, the bound given by Corollary 7.4.3 is much stronger. In a follow-up paper we will examine the case where $g = 1$ and show that in this situation, the bounds obtained in Corollary 6.2.3, and those described in the results mentioned below, can be significantly improved.

The proofs of these results begin with the observation that a bounded essential surface F with boundary slope β may be regarded as a non-properly embedded surface of negative Euler characteristic in $M(\alpha)$, and that if $M(\alpha)$ is very small, then the inclusion homomorphism from $\pi_1(F)$ to $\pi_1(M(\alpha))$ cannot be injective. From this one can deduce that there is a map of a disk into $M(\alpha)$ which maps the boundary of the disk into $M - F$ but cannot be homotoped rel boundary into $M - F$. After normalizing such a map and restricting it to the inverse image of M , one obtains a “singular surface” in M , “well positioned” with respect to F ; according to the precise definitions given in Section 2, such a singular surface is defined by a map h of a surface S into M having certain properties. In the case we are discussing here, S is planar, and each component of ∂S is either mapped into $M - F$ by h , or mapped homeomorphically onto a curve in ∂M of slope α . This last property is expressed by saying that the singular surface has boundary slope α .

The main results of the paper, Theorems 6.2.2 and 7.4.2, give bounds on the distance between two slopes α and β in terms of the data involving an essential surface F in M which is not a semi-fiber and has boundary slope β , and a singular surface which is well positioned with respect to F and has boundary slope α . Applying this in the case of a planar singular surface we obtain such results as Corollaries 6.2.3 and 7.4.3.

By applying Theorems 6.2.2 and 7.4.2 to other kinds of singular surfaces, we obtain different kinds of information about boundary slopes and Dehn filling. For instance we prove:

Corollary 7.4.5. *Let M be a simple knot manifold, and let $F \subset M$ be an essential planar surface with boundary slope β which is not a semi-fiber. Let α be a slope in ∂M . If $M(\alpha)$ is a Seifert fibered space or if there exists a π_1 -injective map from $S^1 \times S^1$ to $M(\alpha)$, then $\Delta(\alpha, \beta) \leq 6$.*

This implies Corollary 7.4.6, which asserts that if $M(\alpha)$ is a Seifert fibered space and $M(\beta)$ is a reducible manifold other than $S^2 \times S^1$ or $P^3 \# P^3$, then $\Delta(\alpha, \beta) \leq 6$. Corollary 7.4.5, like Corollary 7.4.3, has a high-genus analogue: Corollary 6.2.4 asserts that if $M(\alpha)$ is a Seifert fibered space and β is the boundary slope of an essential surface F in M which is not a semi-fiber, then $\Delta(\alpha, \beta) \leq 18 + (24g - 18)/m$, where g is the genus of F and m is the number of its boundary components. These results are proved by observing that if $M(\alpha)$ is Seifert fibered, then either it is very small, in which case the conclusions follow from Corollaries 6.2.3 and 7.4.3, or it contains a π_1 -injective singular torus. Such a torus can be used to construct a genus-1 singular surface in M having boundary slope α , to which Theorems 6.2.2 and 7.4.2 can be applied.

Still another type of application of Theorems 6.2.2 and 7.4.2 can be obtained by observing that an essential surface in M with boundary slope α is a special case of a singular surface with boundary slope α . This leads to upper bounds for the distance between boundary slopes of two essential surfaces (not both semi-fibers) in terms of the genera and numbers of boundary components of the surfaces. Such bounds are given in Corollary 6.2.5 in the general case, and Corollary 7.4.7, which recovers a result of Gordon and Litherland [GLi, Proposition 6.1] under the additional hypothesis that one of the surfaces is planar and is not a semi-fiber. Corollary 6.2.5, which is qualitatively similar to an unpublished result due to Cameron Gordon, strengthens a result due to Torisu [T], but in turn has been strengthened slightly by Agol [A], using results of Cao and Meyerhoff [CM].

The constructions of singular surfaces that are needed to pass from Theorems 6.2.2 and 7.4.2 to their various corollaries are given in detail in Section 2.

The statements of Theorems 6.2.2 and 7.4.2 involve an essential surface F which is not a semi-fiber. We shall sketch the proofs under the simplifying assumption that $M - F$ has two components, whose closures we shall denote by M_F^+ and M_F^- . The first step in the proofs, which is carried out in Section 3, involves graph-theoretical arguments. Suppose that we are given an essential surface $F \subset M$ with boundary slope β and a singular surface which is well positioned with respect to F and has boundary slope α . Such a singular surface is defined by a certain kind of map h of a compact 2-manifold S into M . We obtain a surface \hat{S} from S by identifying certain components of ∂S to points, and the images of the arc components of $h^{-1}(S)$ are the edges of a graph $G \subset \hat{S}$. Each vertex of G has valence $m\Delta(\alpha, \beta)$, where m is the number of boundary components of F . By using certain non-degeneracy properties of G we find a family of parallel edges in G whose size is bounded below in terms of topological data about F and the valence $m\Delta(\alpha, \beta)$.

A parallel family of edges in G gives 3-dimensional information about how the essential surface F sits in M . While the edges of G do not map to properly embedded arcs in F , each edge of G does give rise to an essential path in $(F, \partial F)$, which can be extended to a map of a “pair of glasses” (see Figure 3.3.1) into F that maps the rims homeomorphically to components of ∂F . A parallel family of $k + 1$ edges in G defines a sequence of $k + 1$ such “singular pairs of glasses” and k essential homotopies in M_F^+ and M_F^- between the successive pairs of glasses in the sequence. (Under the homotopies, the images of the rims of the glasses stay in ∂M .) Furthermore, these homotopies alternate strictly between homotopies in M_F^+ and homotopies in M_F^- . According to the precise definition given in Section 3 such a sequence of homotopies determines a *reduced homotopy of length k* . The graph-theoretical arguments that we have sketched here are used in Section 3 to show that upper bounds for the length of a reduced homotopy of singular pairs of glasses in M imply theorems of the type of 6.2.2 and 7.4.2. The rest of the paper is devoted to obtaining such bounds for the lengths of reduced homotopies, in the more general context of a map of a polyhedron into M which is “large” in the sense that the induced homomorphism of fundamental groups has a non-abelian image.

A reduced homotopy of length 1 is by definition an essential homotopy in M_F^+ or M_F^- whose time-0 and time-1 maps are maps of the domain into F . We are interested in reduced homotopies whose time-0 maps are large. Such homotopies can be understood in terms of the characteristic submanifold theory ([JS], [Jo]). This theory provides a (possibly disconnected) 2-manifold $\Phi^\pm \subset M_F^\pm$, which is

“large” in the sense that the fundamental group of each component of Φ^\pm is non-abelian and maps injectively into $\pi_1(F)$. Any large map of a polyhedron into F which is the time-0 map of an essential homotopy in M_F^\pm is homotopic in F to a map into Φ^\pm . Furthermore, the identity map of Φ^\pm is itself the time-0 map of an essential homotopy in M_F^\pm .

In Section 5 we generalize this to reduced homotopies of length k : we define large 2-dimensional submanifolds Φ_k^\pm of F for $k = 1, 2, \dots$. If a large map f of a polyhedron into F is the time-0 map of a length- k reduced homotopy in M which “begins” in M_F^+ (or M_F^-), then f is homotopic in F to a map into Φ_k^+ (respectively Φ_k^-). Furthermore, the identity map of Φ_k^\pm is itself the time-0 map of a reduced homotopy in M which begins in M_F^\pm . The Φ_k^\pm for $k > 1$ are defined inductively, using the notion of an essential intersection of subsurfaces of F , which is presented in [Ja]. In Section 4 we give a self-contained account of a version of the theory of essential intersections that is adapted to the study of large subsurfaces.

The Φ_k^\pm give a natural tool for bounding the length of a reduced homotopy: if n is a positive integer such that $\Phi_n^+ = \Phi_n^- = \emptyset$, it is clear that any reduced homotopy with large time-0 map has length $< n$. (Of course there can be no such bound in the case that F is a semi-fiber.)

The Φ_k^\pm may be taken to be nested: $\Phi_1^+ \supset \Phi_2^+ \supset \dots$, and similarly for the Φ_k^- . A crucial step in the argument is provided by Proposition 5.3.9, which asserts that when F is not a semi-fiber, and if Φ_k^+ (say) is non-empty for a given k , then Φ_{k+2}^+ is not isotopic to Φ_k^+ . Hence in the sequence $\Phi_1^+ \supset \Phi_3^+ \supset \Phi_5^+ \supset \dots$, the successive subsurfaces are always non-isotopic until one of them becomes empty. This means that to bound the length of a reduced homotopy whose time-0 map is large, it suffices to bound the length of a nested sequence of subsurfaces of F in which successive subsurfaces are non-isotopic. This is a matter of elementary surface topology, and the bound can be improved by a factor of 2 using Corollary 5.3.8, which asserts that for odd k the Φ_k^\pm all have even Euler characteristic. This leads to Theorem 5.4.1, which gives a bound of $8g + 3m - 8$ for the length of a reduced homotopy with a large time-0 map, where g is the genus of F and m , as above, denotes the number of its boundary components.

While Theorem 5.4.1 is significant for general large maps, it is far from optimal for the case of singular pairs of glasses arising from essential paths. In Section 6 we introduce a variant of Φ_k^\pm which we denote by $\check{\Phi}_k^\pm$; it is simply the union of the “outer components” of Φ_k^\pm , i.e. those components which have at least one boundary component which is homotopic to a component of ∂F . If a singular pair of glasses f arising from an essential path in F is the time-0 map of a length- k reduced homotopy in M which begins in M_F^+ (or M_F^-), then f is homotopic in F to a map into $\check{\Phi}_k^+$ (respectively $\check{\Phi}_k^-$). In Section 6, under the assumption that there exists a reduced homotopy of length m whose time-0 map is an essential path, we establish analogues for the $\check{\Phi}_k^\pm$ of all the properties of the Φ_k^\pm that are established in Section 4, including Corollary 6.1.10 and Proposition 6.1.11 which are the analogues of Corollary 5.3.8 and Proposition 5.3.9. By definition the $\check{\Phi}_k^\pm$ have the additional property that they are outer subsurfaces, in the sense that all their components are outer components. Hence to bound the length of a reduced homotopy whose time-0 map is an essential path, it suffices to bound the length of a nested sequence of outer subsurfaces of F in which successive subsurfaces are non-isotopic. The restriction to outer subsurfaces turns out to improve the bound,

almost by another factor of 2. The upshot is Theorem 6.2.1, which gives a bound of $4g + 3m - 4$ for the length of a reduced homotopy whose time-0 map is an essential path, where g and m are defined as above. Theorem 6.2.2 is proved by combining Theorem 6.2.1 with the results of Section 2.

In order to prove Theorem 7.4.2 we need to improve the conclusion of Theorem 6.2.1 in the special case where F is planar, i.e. $g = 0$.

Theorem 7.4.1. *Let F be an essential planar surface in a simple knot manifold M . Suppose that F is not a semi-fiber. Set $m = |\partial F|$ and let H be any reduced homotopy in the pair (M, F) such that H_0 is an essential path in F and $H_t(\partial I) \subset \partial M$ for each $t \in I$. Then the length of H is at most $m - 1$.*

The proof formally proceeds by contradiction, beginning with the assumption that there is a length- m reduced homotopy whose time-0 map is an essential path, and applying some machinery that is set up in Section 7. We shall sketch this machinery in the case where F is planar, although many of the results of Section 7 are stated more generally. We introduce yet another variant of Φ_k^\pm which we denote by $\check{\Phi}_k^\pm$. It differs from $\dot{\Phi}_k^\pm$ in that it contains ∂F , but may have annular components. Under the assumption that there is a length- m reduced homotopy whose time-0 map is an essential path, we again obtain analogues for the $\check{\Phi}_k^\pm$ of the properties that are established in the preceding sections for the Φ_k^\pm and the $\dot{\Phi}_k^\pm$, even though the surfaces $\check{\Phi}_k^\pm$ need not be large. In Proposition 7.2.10, which is the analogue of Propositions 5.3.9 and 6.1.11, the analogue of the conditions $\Phi_k^\pm = \emptyset$ or $\dot{\Phi}_k^\pm = \emptyset$ is that $\check{\Phi}_k^\pm$ is a regular neighborhood of ∂F , which is in fact equivalent to the condition $\dot{\Phi}_k^\pm = \emptyset$.

The planarity of F implies that if F is not a semi-fiber, then some component of $\check{\Phi}_1^\pm$ is *tight* in the sense that its frontier in F is a single simple closed curve. We define the *size* of a tight component of $\check{\Phi}_k^\pm$ to be the number of components of ∂F that it contains. We call a component of $\check{\Phi}_1^+$ or $\check{\Phi}_1^-$ *very tight* if its size is at most the minimum size of any tight component of $\check{\Phi}_1^+$ or $\check{\Phi}_1^-$. We may assume by symmetry that $\check{\Phi}_1^+$ has a very tight component. Lemma 7.3.1, the proof of which is based on the same ideas as that of Corollary 5.3.8, implies that the number $|VT(\check{\Phi}_k^+)|$ of very tight components of $\check{\Phi}_k^+$ is always even. A key step in proving Theorem 7.4.1 is Lemma 7.3.7, which implies that if F is not a semi-fiber, then increasing k by 2 always strictly increases $|VT(\check{\Phi}_k^+)|$, unless $\check{\Phi}_k^+$ is already a regular neighborhood of ∂F . From this it is not hard to deduce (cf. Proposition 7.3.8) that $\check{\Phi}_{m-1}^+$ is a regular neighborhood of ∂F ; this in turn easily implies that there is no length- m reduced homotopy whose time-0 map is an essential path, a contradiction which completes the proof of Theorem 7.4.1.

In Section 8 we further investigate the situation where M is a simple knot manifold and α and β are slopes such that $M(\alpha)$ is Seifert fibered while $M(\beta)$ is reducible. In Proposition 8.4 we establish restrictions on which Seifert fibered spaces can arise in this situation when $\Delta(\alpha, \beta) > 3$. The proof begins by applying Corollary 7.4.6 to deduce that $\Delta(\alpha, \beta)$ is equal to 4, 5 or 6. We then use the $PSL_2(\mathbb{C})$ character variety together with some observations from algebraic number theory to describe the Seifert fibered structure on $M(\alpha)$. For instance we prove:

Corollary 8.5. *Let M be a simple knot manifold and fix slopes α and β on ∂M . If $M(\beta)$ is reducible, though not $S^1 \times S^2$ or $P^3 \# P^3$, and $M(\alpha)$ is a Seifert fibered*

space, then $\Delta(\alpha, \beta) \leq 5$ unless perhaps $M(\beta) \cong P^3 \# L(p, q)$ and $M(\alpha)$ is a small Seifert manifold with base orbifold $S^2(a, b, c)$, where (a, b, c) is a hyperbolic triple and 6 divides $\text{lcm}(a, b, c)$.

Similar methods lead to restrictions, in Proposition 8.7, of the possible Seifert fibrations of $M(\alpha)$ when $M(\beta)$ is a Seifert fibered space containing an (embedded) incompressible torus and $5 < \Delta(\alpha, \beta) \leq 10$. The method of proof is similar to that used in Proposition 8.4, except that the role of Corollary 7.4.6 is played by a theorem due to Agol [A] and Lackenby [La] which implies that $\Delta(\alpha, \beta) \leq 10$ in this situation.

This paper had its origins in unpublished work done by M. Culler, C. MacA. Gordon and P. B. Shalen in 1984. This work established a preliminary version of the Cyclic Surgery Theorem [CGLS], giving an upper bound of 5 for the distance between two cyclic filling slopes for a simple knot manifold, which was afterwards superseded by the bound of 1 established in [CGLS]. The proof used character variety techniques to reduce the result to a complicated topological statement, which was in turn proved by combining the graph-theoretical construction of Section 3 and the use of the subsurfaces Φ_k^\pm in the same way as is done in the proof of Theorem 6.2.2. The techniques that were then available could have produced a result qualitatively similar to Theorem 6.2.2, but much weaker.

Independently and more recently, techniques similar to ours have been used in a related context by Cooper and Long [CL] and Li [Li]. While our main results bound $\Delta(\alpha, \beta)$ under the assumption that β is a boundary slope and $\pi_1(M(\alpha))$ does not contain a non-abelian free group, the results in [CL] and [Li] imply a weaker bound for $\Delta(\alpha, \beta)$ under the weaker assumption that β is a boundary slope and $\pi_1(M(\alpha))$ does not contain the fundamental group of a closed surface of genus > 1 . Li proves a result which is qualitatively similar to our Theorem 6.2.1, but with a bound of $6g + 4m - 6$ where Theorem 6.2.1 provides the stronger bound of $4g + 3m - 4$.

We are indebted to Cameron Gordon for his role in the development of the ideas in this paper.

1. TERMINOLOGY AND NOTATION

We describe here various notational conventions that will be used throughout the paper.

1.1. If X is a topological space, $|X|$ will denote the number of components of X .

A (continuous) map $f: X \rightarrow Y$ of topological spaces will be called π_1 -*injective* if for each $x_0 \in X$, the homomorphism $f_\#: \pi_1(X; x_0) \rightarrow \pi_1(Y; f(x_0))$ is injective. A subset A of a space Y will be called π_1 -*injective* if the inclusion map $A \rightarrow Y$ is π_1 -injective.

A *homotopy with domain X and target Y* is a map $H: X \times I \rightarrow Y$. For each $t \in [0, 1]$ we define $H_t: X \rightarrow Y$ by $H_t(x) = H(x, t)$. We shall sometimes refer to H_t as the *time- t map* of H .

Let H^1, \dots, H^n be homotopies with domain X and target Y . A homotopy H with domain X and target Y will be said to be a *composition* of H^1, \dots, H^n if there exist numbers $0 = x_0 < x_1 < \dots < x_n = 1$ and monotone increasing linear homeomorphisms $\alpha_i: [x_{i-1}, x_i] \rightarrow [0, 1]$ such that $H(x, t) = H^i(x, \alpha_i(t))$ whenever $t \in [x_{i-1}, x_i]$.

We shall say that a map $f: X \rightarrow Y$ between spaces is *homotopic into a subset B of Y* if f is homotopic to a map $g: X \rightarrow Y$ for which $g(X) \subset B$. A subset A of a space Y is said to be *homotopic into a subset B of Y* if the inclusion map from A to Y is homotopic into B .

Let $f: (X, Y) \rightarrow (Z, W)$ be a map of topological pairs, where Z is a connected n -manifold and $W \subset \partial Z$ is an $(n - 1)$ -manifold. In the case where X is pathwise connected, we shall say that f is *essential* if it is π_1 -injective as a map from X to Z and is not homotopic, as a map of pairs, to a map $f': (X, Y) \rightarrow (Z, W)$ where $f'(X) \subset W$. In general we shall say that f is *essential* if $X \neq \emptyset$ and f restricts to an essential map from $(C, C \cap Y)$ to (Z, W) for every component C of X . A map f from a space X to a manifold Z will be termed *essential* if $f: (X, \emptyset) \rightarrow (Z, \partial Z)$ is essential.

We will denote the unit interval $[0, 1]$ by I . By an *essential path* in a surface F with non-empty boundary we shall mean an essential map $f: (I, \partial I) \rightarrow (F, \partial F)$.

A manifold M is said to be *orientable* if all of its components are orientable. An *orientation* of M is defined by a choosing an orientation for each component; a manifold M is said to be *oriented* if an orientation of M has been fixed. Every codimension 0 submanifold of an oriented manifold M inherits an orientation.

Suppose that A is a codimension 0 submanifold of a manifold M and that $h: A \rightarrow M$ is an embedding. We say that h *preserves orientation* if it carries the orientation of A inherited from M to the orientation of $h(A)$ inherited from M ; we say that h *reverses orientation* if it carries the orientation of A inherited from M to the orientation of $h(A)$ which is the opposite of that inherited from M . In general, if A is disconnected, there may exist embeddings which neither preserve nor reverse orientation.

If S is a compact surface, then $\chi(S)$ denotes the Euler characteristic of S and $genus(S)$ denotes the total genus of S , i.e. the sum of the genera of the components of S .

1.2. A compact orientable 3-manifold M is said to be *irreducible* if it is connected and every 2-sphere in M bounds a ball. A compact orientable 3-manifold M is said to be *boundary irreducible* if it is connected and for any properly embedded disk D in M the curve ∂D bounds a disk in ∂M .

Let M be a compact, orientable, irreducible 3-manifold, and let $Q \subset \partial M$ be a compact π_1 -injective surface. We define an *essential surface* in (M, Q) to be a compact surface F in M such that (i) $\partial F = F \cap \partial M \subset Q$, and (ii) the inclusion map $(F, \partial F) \rightarrow (M, Q)$ is essential. Note that condition (ii) is equivalent to the condition that F is incompressible and not parallel to a subsurface of Q . By an *essential surface* in a 3-manifold M we mean an essential surface in $(M, \partial M)$.

Let M be a compact, orientable, irreducible 3-manifold and let Q be a π_1 -injective subsurface of ∂M . We will say that the pair (M, Q) is *acylindrical* if there does not exist any essential map from $(S^1 \times I, S^1 \times \partial I)$ to $(M, \partial M)$ which sends $S^1 \times \partial I$ into Q . By the Annulus Theorem [JS, IV.3.1], (M, Q) is acylindrical if and only if there is no essential annulus in (M, Q) .

We will say that a compact 3-manifold M is *atoroidal* if there exists no essential map from $(S^1 \times S^1, \emptyset)$ to $(M, \partial M)$.

A closed orientable 3-manifold will be said to be *very small* if its fundamental group contains no non-abelian free subgroup.

1.3. Given a compact orientable 3-manifold M and a connected, properly embedded, transversely oriented surface F in M , we will implicitly fix a regular neighborhood $N(F)$ of F and a homeomorphism f_F from $F \times [-1, 1]$ to $N(F)$ which sends the standard orientation of $[-1, 1]$ to the transverse orientation of F and maps $F \times \{0\}$ to F . The sets $f_F(F \times (-1, 0))$ and $f_F(F \times [0, 1))$ will be denoted $N_-(F)$ and $N_+(F)$, respectively.

We will use the notation M_F to denote the compact manifold

$$M - f_F(F \times (-1/2, 1/2)).$$

The boundary of M_F contains the two subsurfaces $F \times \{-1/2\}$ and $F \times \{1/2\}$ which will be denoted F_- and F_+ , respectively. By restricting the projection map $N(F) \rightarrow F$ we obtain two standard homeomorphisms $i_-: F_- \rightarrow F$ and $i_+: F_+ \rightarrow F$. Whenever it is convenient to do so we will identify the manifold M with the quotient of M_F obtained by gluing F_- to F_+ via the homeomorphism $i_+^{-1} \circ i_-$.

The surface F will be called a *semi-fiber* in M if the pair $(M_F, F_- \cup F_+)$ is an I -pair in the sense of [Ja]; that is, if there is an I -bundle E over a surface and a homeomorphism $h: M_F \rightarrow E$ such that $h(F_- \cup F_+)$ is the ∂I -bundle associated to E . (Note that E may be either a trivial I -bundle over a connected orientable surface, or a twisted I -bundle over a non-orientable surface of two components.)

1.4. Simple knot manifolds and slopes. We will say that a compact connected orientable 3-manifold M is *simple* provided that (1) M is irreducible and boundary irreducible, (2) M contains no essential surface of Euler characteristic 0, and (3) M is not Seifert-fibered. If in addition the boundary of M is a torus we will say that M is a *simple knot manifold*.

If M is a simple knot manifold, then an unoriented isotopy class of homotopically non-trivial simple closed curves on ∂M will be called a *slope*. We will write $\Delta(\alpha, \beta)$ for the geometric intersection number of two slopes α and β . We will denote by $M(\alpha)$ the Dehn filling of M determined by α . If F is a bounded essential surface in M , then the boundary curves of F all have the same slope, which will be called the *boundary slope* of F . A slope will be called a *boundary slope* if it is the boundary slope of some essential surface. A slope will be called a *strict boundary slope* if it is the boundary slope of some essential surface which is not a semi-fiber in M .

2. SINGULAR SURFACES

Let M be a simple knot manifold. By a *singular surface* in M we will mean a triple (S, X, h) , where S is a compact, connected, orientable surface, X is a non-empty union of components of ∂S , and $h: (S, X) \rightarrow (M, \partial M)$ is a map of pairs such that (i) $h(S - X) \subset \text{int } M$ and (ii) h maps the components of X homeomorphically onto disjoint, homotopically non-trivial simple closed curves in ∂M .

If (S, X, h) is a singular surface in M , the components of $h(X)$ are all simple closed curves with the same slope, which we shall call the *boundary slope* of (S, X, h) .

We shall say that two simple closed curves γ and γ' on a torus T are in *standard position* if there is a covering map $p: \mathbb{R}^2 \rightarrow T$ for which $p^{-1}(\gamma)$ and $p^{-1}(\gamma')$ are Euclidean lines.

Let F be a bounded essential surface in a simple knot manifold M . A singular surface (S, X, h) will be said to be *well positioned with respect to F* if (i) h is transverse to F , (ii) $h(\partial S - X) \cap F = \emptyset$, (iii) $h(X)$ is in standard position with respect to ∂F , and (iv) each component of $h^{-1}(F)$ is mapped by h to an essential

path or to a homotopically non-trivial (possibly singular) closed curve in F . It follows from (ii) that the arc components of $h^{-1}(F)$ have their endpoints in X . Note that (iv) implies in particular that no simple closed curve component of $h^{-1}(F)$ bounds a disk in S , and that no arc component of $h^{-1}(F)$ is parallel in S to an arc in X .

In this section we shall give several ways of constructing singular surfaces that are well positioned with respect to a given bounded essential surface in a simple knot manifold.

Proposition 2.1. *Suppose that F and S are bounded essential surfaces in a simple knot manifold M . Then the inclusion map from S to M is isotopic to an embedding $h : S \rightarrow M$ such that the singular surface $(S, \partial S, h)$ is well positioned with respect to F .*

Proof. After an isotopy we may assume that S and F meet transversely and that ∂S is in standard position with respect to F . We claim that every arc component of $S \cap F$ is essential in F . If this is not the case, then there is a disk $D \subset F$ whose frontier in F is an arc A such that $A = D \cap S$. Since ∂M is a torus, the essential surface S is boundary-incompressible; hence A is the frontier in S of a disk $E \subset S$. Now $D \cup E$ is a properly embedded disk in the simple knot manifold M and is therefore parallel in M to a disk $J \subset \partial M$. As ∂J is made up of an arc in ∂F and an arc in ∂S , we have a contradiction to standard position, and the claim is proved.

To prove the proposition it now suffices to show that if some component of $S \cap F$ is a homotopically trivial simple closed curve C in F , then S is isotopic rel boundary to a surface S' such that $|S' \cap F| < |S \cap F|$. We may suppose C to be chosen so that there is a disk $D \subset F$ such that $\partial D = C = D \cap S$. Since S is essential, C also bounds a disk $E \subset S$; since M is irreducible the disks D and E are isotopic by an isotopy that fixes C . We may thus obtain the required surface S' by moving $(S - \text{int } E) \cup D$ into general position with respect to F . \square

Proposition 2.2. *Let M be a simple knot manifold. Let F be a bounded essential surface in M , and let α be a slope on ∂M . Suppose that there exist a compact orientable surface T and a π_1 -injective map $f : T \rightarrow M(\alpha)$ such that*

- (1) $f(\partial T) \subset M - F \subset M \subset M(\alpha)$;
- (2) *there exists no map from T to M which agrees with f on ∂T and induces an injection from $\pi_1(T)$ to $\pi_1(M(\alpha))$.*

Then there exists a singular surface (S, X, h) in M which has boundary slope α and is well positioned with respect to F . Moreover, we have $\text{genus } S = \text{genus } T$, and $|\partial S - X| = |\partial T|$.

Proof. Let us write $M(\alpha) = M \cup V$, where V is a solid torus and a meridian curve of V is identified with a curve of slope α in ∂M .

By transversality and uniqueness of regular neighborhoods, there exists a map $h : T \rightarrow M(\alpha)$ such that

- (i) h is π_1 -injective and agrees with f on ∂T ;
- (ii) the components of $h^{-1}(V)$ are disks in the interior of T which are mapped homeomorphically by h to disjoint meridian disks of V , whose boundaries are all in standard position with respect to all of the components of ∂F ;
- (iii) each component of $h^{-1}(F)$ is a properly embedded 1-manifold in the bounded surface $h^{-1}(M)$.

Define the *complexity* of a map h satisfying conditions (i)—(iii) to be the ordered pair $(v(h), b(h))$, where $v(h)$ is the number of components of $h^{-1}(V)$ and $b(h)$ is the number of components of $h^{-1}(F)$. Note that hypothesis (2) and condition (i) imply that $v(h)$ must be strictly positive.

Among all maps satisfying (i)—(iii), we suppose h to be chosen so that the complexity of $h^{-1}(F)$ is minimal with respect to lexicographical order.

We set $S = T - h^{-1}(\text{int } V) = h^{-1}(M)$ and $X = \partial S - \partial T = h^{-1}(\partial M)$. By (ii), the components of $h(X)$ are simple closed curves of slope α .

We shall show that the map h satisfies the following additional condition:

(iv) Each component of $h^{-1}(F)$ is mapped by h to an essential path or to a homotopically non-trivial (possibly singular) closed curve in F .

It follows from the definitions that if h satisfies (i)—(iv), then the triple $(S, X, h|_S)$ is a singular surface, well positioned with respect to F and having boundary slope α . Furthermore, we have $\text{genus } S = \text{genus } T$ and $|\partial S - X| = |\partial T|$, since S was obtained from T by removing a collection of disjoint disks bounded by X . Hence the proof of the proposition will be complete when we have shown that h satisfies (iv).

To prove (iv), first suppose that some curve component C of $h^{-1}(F)$ is mapped by h to a homotopically trivial closed curve in F . Then, since h is π_1 -injective, the curve C bounds a disk D in T . Thus there is a map $h': T \rightarrow M(\alpha)$ which agrees with h on the complement of D , and maps D into F . Moving h' into general position would produce a map of lower complexity than h , giving a contradiction.

To complete the proof of (iv), we consider an arc component A of $h^{-1}(F)$, and let $p, q \in X$ be the endpoints of A . We must show that the path $h(A)$ is essential in F .

It will be convenient to work in the smooth category for this argument. Fix an orientation on the manifold M and give ∂M the induced orientation. Given an ordered pair (γ_1, γ_2) of oriented 1-manifolds on ∂M , intersecting transversely at a point, we define the sign of their intersection at that point to be the sign of the frame $(\mathbf{u}_1, \mathbf{u}_2)$ with respect to the orientation of ∂M , where \mathbf{u}_i is a tangent vector to γ_i which is positive with respect to its orientation.

Next we fix orientations of F and T . The orientation of T restricts to an orientation of S . Give the components of ∂F and X the orientations induced from those of F and S , and then push the orientation of X forward under h to obtain orientations of the meridian curves that make up $h(X)$. The points $h(p)$ and $h(q)$ are transverse intersection points of the oriented 1-manifolds ∂F and $h(X)$ on ∂M . A key step in the proof that $h(A)$ is an essential path is to show that the signs of these intersections are opposite.

The orientations of M and F define a transverse orientation of F . Because the map h is transverse to F , we can pull back the transverse orientation of F to a transverse orientation of A in S . Let \mathbf{u}_p and \mathbf{u}_q be tangent vectors to X at p and q which are positive with respect to the orientation of X . Let \mathbf{v}_p and \mathbf{v}_q be tangent vectors to ∂F at the points $h(p)$ and $h(q)$ which are positive with respect to the orientation of ∂F . Let \mathbf{w}_p and \mathbf{w}_q be tangent vectors to ∂M which are transverse to \mathbf{v}_p and \mathbf{v}_q and positive with respect to the transverse orientation of F . Observe first that, since A is a properly embedded arc in S , the transverse orientation of A is consistent with the orientation of X at p if and only if it is inconsistent with the orientation of X at q . Second, observe that the signs of $(\mathbf{v}_p, \mathbf{w}_p)$ and $(\mathbf{v}_q, \mathbf{w}_q)$

agree. It follows that the signs of $(Dh(\mathbf{u}_p), \mathbf{v}_p)$ and $(Dh(\mathbf{u}_q), \mathbf{v}_q)$ are opposite. In other words, the signs of the intersections of ∂F and $h(X)$ are opposite at $h(p)$ and $h(q)$.

Now assume that the path $h(A)$ is inessential in F . In particular the points $h(p)$ and $h(q)$ then lie on the same component of ∂F . But the signs of the intersections of ∂F and $h(X)$ are opposite at $h(p)$ and $h(q)$, and by (ii) the components of $h(X)$ are all in standard position with respect to all the components of ∂F . It follows that p and q lie on distinct components C_1 and C_2 of X , and that the orientations inherited from $h(X)$ by the meridian curves $h(C_1)$ and $h(C_2)$ are opposite on the torus ∂M . Let $D_1, D_2 \subset T$ be the disk components of $h^{-1}(V)$ bounded by C_1 and C_2 , and define D to be a regular neighborhood of $D_1 \cup A \cup D_2$ in T . Then $h(\partial D)$ is homotopic in M to a (possibly singular) closed curve on the torus ∂M which is the composition of conjugates of the oppositely oriented meridian curves $h(C_1)$ and $h(C_2)$. In short, $h(\partial D)$ is homotopically trivial in M . Hence there is a map $h': T \rightarrow M(\alpha)$ which agrees with h on the complement of D , and maps D into M . Then h' has lower complexity than h . This contradiction completes the proof that A is essential and hence that h satisfies (iv). \square

The following results are corollaries to Propositions 2.1 and 2.2.

Corollary 2.3. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface. Let α be a slope in ∂M . If $M(\alpha)$ is very small, or more generally if $F \subset M \subset M(\alpha)$ is not π_1 -injective in $M(\alpha)$, then there exists a singular surface (S, X, h) , well positioned with respect to F and having boundary slope α , such that S is planar and $\partial S - X$ is non-empty and connected.*

Proof. It follows from the definition of a simple manifold that if F is a bounded essential surface in a simple knot manifold M , then $\chi(F) < 0$, so that $\pi_1(F)$ is a non-abelian free group. Hence if $M(\alpha)$ is very small, then $F \subset M(\alpha)$ is not π_1 -injective in $M(\alpha)$. We must show that if $F \subset M(\alpha)$ is not π_1 -injective in $M(\alpha)$, then there exists a singular surface (S, X, h) with the stated properties. We will apply Proposition 2.2, taking T to be a disk and constructing the map $f: T \rightarrow M(\alpha)$ as follows. Since F is not π_1 -injective in $M(\alpha)$, there exists a homotopically non-trivial closed curve γ on the surface F which is null-homotopic in $M(\alpha)$. Deform the curve γ by a homotopy to a curve γ' which is disjoint from F . Let f be a null-homotopy of γ' in $M(\alpha)$. Then f is π_1 -injective since $\pi_1(T)$ is trivial, and condition (1) of Proposition 2.2 holds by construction. Since F is essential, there does not exist a null-homotopy of γ' in M , so condition (2) of Proposition 2.2 holds as well. \square

Corollary 2.4. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface. Let α be a slope in ∂M . If $M(\alpha)$ is reducible, then there exists a singular surface (S, X, h) , well positioned with respect to F and having boundary slope α , such that S is planar and $X = \partial S$.*

Proof. If $M(\alpha)$ is reducible, then there is an essential planar surface in M with boundary slope α . The assertion therefore follows from Proposition 2.1. \square

Corollary 2.5. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface. Let α be a slope in ∂M and let g be a positive integer. Suppose that $\pi_1(M(\alpha))$ contains a subgroup which is isomorphic to the fundamental group of a closed connected surface of genus g , and that $\pi_1(M)$ does not. Then there exists*

a singular surface (S, X, h) , well positioned with respect to F and having boundary slope α , such that genus $S = g$ and $X = \partial S$.

Proof. If $\pi_1(M(\alpha))$ contains a genus- g surface group, then there is a π_1 -injective map from a surface of genus g to $M(\alpha)$. Note that condition (1) of Proposition 2.2 holds vacuously, and condition (2) holds because of our hypothesis on $\pi_1(M(\alpha))$. The assertion therefore follows from Proposition 2.2. \square

Corollary 2.6. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface. Let α be a slope in ∂M . If $M(\alpha)$ is a Seifert fibered space, then there exists a singular surface (S, X, h) , well positioned with respect to F and having boundary slope α , such that either (i) genus $S = 1$ and $X = \partial S$, or (ii) S is planar and $\partial S - X$ is non-empty and connected.*

Proof. If $\pi_1(M(\alpha))$ is finite, or if $M(\alpha)$ is reducible and hence homeomorphic to $S^1 \times S^2$ or $P^3 \# P^3$, then $M(\alpha)$ is very small and conclusion (ii) holds by Corollary 2.3.

If $\pi_1(M(\alpha))$ is infinite and $M(\alpha)$ is irreducible, then there exists a π_1 -injective map $f : T \rightarrow M(\alpha)$, where T is a torus. Since M is atoroidal, any π_1 -injective map from T to M is homotopic to a map into ∂M . But such a map cannot be π_1 -injective as a map from T to $M(\alpha) \supset M$, since ∂M bounds a solid torus in $M(\alpha)$. It follows that f is not homotopic to a map whose image is contained in M . Therefore f satisfies the hypotheses of Proposition 2.2, which asserts the existence of a singular surface satisfying condition (i) of the statement. \square

3. REDUCED HOMOTOPIES

3.1. Basic homotopies. Let M be a simple knot manifold and let F be a transversely oriented essential surface in M . A *homotopy* in (M, F) with domain K is a homotopy H with domain K and target M such that $H(K \times \partial I) \subset F$. A homotopy H in (M, F) is a *basic homotopy* if $H^{-1}(F) = K \times \partial I$.

We shall say that a basic homotopy $H : (K \times I, K \times \partial I) \rightarrow (M, F)$ *starts on the + side (or the - side)* if $H(K \times [0, \delta])$ is contained in $N_+(F)$ (or in $N_-(F)$) for sufficiently small $\delta > 0$. Similarly, H will be said to *end on the + side (or the - side)* if $H(K \times [1 - \delta, 1])$ is contained in N_+ (or in N_-) for sufficiently small $\delta > 0$. Of course in the case where F separates M , a basic homotopy starts on the + side (or, respectively, the - side) if and only if it ends on the + side (or the - side). In this case we shall simply refer to it as a homotopy on the + side (or - side).

As a notational convention we will treat the symbols + and - as abbreviations for 1 and -1, respectively. Thus if $\epsilon \in \{\pm 1\}$ we may say that a homotopy H starts on the ϵ -side, meaning that it starts on the + side if $\epsilon = 1$ or that it starts on the - side if $\epsilon = -1$.

There is a natural one-to-one correspondence between basic homotopies H in (M, F) with domain K which start on the ϵ side, and homotopies H' in $(M_F, F_- \cup F_+)$ with domain K such that $H'^{-1}(F_- \cup F_+) = K \times \partial I$ and $H'_0(K) \subset F_\epsilon$. A basic homotopy H is said to be *essential* if the corresponding homotopy

$$H' : (K \times I, K \times \partial I) \rightarrow (M, F_- \cup F_+)$$

is an essential map of pairs.

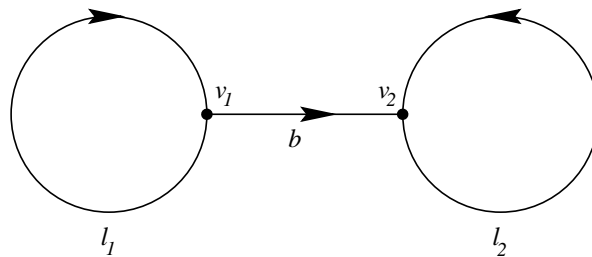


FIGURE 3.3.1

3.2. Reduced homotopies. Let M be a simple knot manifold and F an essential surface in M . Let K be a finite polyhedron. Suppose that n is a positive integer. A homotopy $H: (K \times I, K \times \partial I) \rightarrow (M, F)$ is said to be a *reduced homotopy of length n in (M, F)* if we may write H as a composition of n essential basic homotopies H^1, \dots, H^n in such a way that, for $i = 1, \dots, n-1$, if ϵ_i denotes the element of $\{\pm 1\}$ such that H^{i+1} starts on the ϵ_i side, then we have that H^i ends on the $-\epsilon_i$ side. If ϵ_0 denotes the element of $\{\pm 1\}$ such that H^1 starts on the ϵ_0 side, then we shall also say that the reduced homotopy H starts on the ϵ_0 side.

We define a *reduced homotopy of length 0* in (M, F) to be a map H from K to F . The *time-0 and time-1 maps* of H are defined to be H itself. If H is a reduced homotopy of length 0 and H' is a reduced homotopy of length ≥ 0 whose time-1 (or time-0) map is equal to H , we define the *composition* of H with H' (or of H' with H) to be H' .

3.3. Let Γ denote the 1-complex shown in Figure 3.3.1, consisting of two vertices v_1 and v_2 , and three oriented edges l_1, l_2 and b . By an *admissible pair of glasses* in a surface F we will mean a map $\gamma: \Gamma \rightarrow F$ such that the restriction of γ to \bar{b} is an essential path, and, for $i = 1, 2$, the restriction of γ to \bar{l}_i is a homeomorphism onto a boundary component of F . It is easy to show that if γ is an admissible pair of glasses in a surface F of negative Euler characteristic, then $\gamma: (\Gamma, \bar{l}_1 \cup \bar{l}_2) \rightarrow (F, \partial F)$ is an essential map of pairs; and furthermore that if α is any map from S^1 to Γ which is not homotopic into l_1 or l_2 , then $g = \gamma \circ \alpha: S^1 \rightarrow F$ is essential. In particular this remark applies when F is an essential surface in a simple knot manifold, since the definition of simplicity then implies that $\chi(F) < 0$.

3.4. Let F be an essential surface in a simple knot manifold M . Suppose that $f: (I, \partial I) \rightarrow (F, \partial F)$ is an essential path and that

$$H: (I \times I, I \times \partial I) \rightarrow (M, F)$$

is a reduced homotopy of length n such that $H_0 = f$ and $H_t(\partial I) \subset \partial M$ for all $t \in I$. Let us identify the set $\bar{b} \subset \Gamma$ with I , respecting the orientations, so that f becomes a map from \bar{b} to F . Let us fix a product structure on $\partial M \cong S^1 \times S^1$ such that each simple closed curve in ∂F has the form $\{x\} \times S^1$ for some $x \in S^1$, and for $i = 1, 2$ let us fix orientation-respecting identifications of \bar{l}_i with S^1 . In this situation we shall describe a canonical way to extend f to an admissible pair of glasses $\hat{f}: \Gamma \rightarrow F$, and to extend H to a reduced homotopy \hat{H} of length n in the pair (M, F) such that $\hat{H}_0 = \hat{f}$. The reduced homotopy \hat{H} will have the additional

property that for all $t \in [0, 1]$ the two closed curves $H_t|_{\bar{l}_i}$, $i = 1, 2$, are homotopic to boundary components of F .

For $i = 1, 2$ the point $f(v_i)$ lies in a component $\{x_i\} \times S^1$ of ∂F . As we have identified l_i with S^1 , there is a unique rotation ρ_i of S^1 such that $f(v_i) = (x_i, \rho_i(v_i))$. We extend f to a map $\hat{f}: \Gamma \rightarrow F$ by sending $\theta \in \bar{l}_i$ to $(x_i, \rho_i(\theta))$ for $i = 1, 2$. Since the map f is an essential path, it follows that \hat{f} is an admissible pair of glasses. Similarly, we extend H to a homotopy \hat{H} as follows. For $i = 1, 2$ we map each $(\theta, t) \in \bar{l}_i \times I$ to $(x_{i,t}, \rho_{i,t}(\theta))$, where $x_{i,t}$ is chosen so that $H(v_i, t) \in \{x_{i,t}\} \times S^1$, and $\rho_{i,t}$ is the unique rotation of S^1 such that $H(v_i, t) = (x_{i,t}, \rho_{i,t}(v_i))$. Since H is a reduced homotopy of length n , it is clear that \hat{H} is also a reduced homotopy of length n .

3.5. Suppose that F is an essential surface in a simple knot manifold M and that $\gamma: \Gamma \rightarrow F$ is an admissible pair of glasses. Any length- n reduced homotopy \hat{H} in (M, F) with domain Γ and time-0 map γ can be used to produce a length- n reduced homotopy in (M, F) whose domain is S^1 , and whose time-0 map is an essential map of S^1 into F . We map S^1 to the circuit in Γ corresponding to the edge path $l_1 b l_2 b^{-1}$. Composing this map with γ we obtain a map $g: S^1 \rightarrow F$. The map g is essential by the remark in Subsection 3.3. Composing \hat{H} with $g \times \text{id}$ we obtain a reduced homotopy of length n whose time-0 map is g .

Definition 3.6. Let G be a (possibly disconnected) graph in the interior of a compact surface S , and let E and E' be distinct edges of G . We shall say that E and E' are *adjacent parallel edges* if there exists a topological disk D , whose boundary is a union of two arcs A_1 and A_2 with $A_1 \cap A_2 = \partial A_1 = \partial A_2$, and a map $i: D \rightarrow S$, such that $i|(D - \partial A_1)$ is one-to-one, $i(A_j) = E_j$ for $j = 1, 2$, and $i(\text{int } D) \cap G = \emptyset$. We shall say that E and E' are *parallel edges* if there exist edges $E = E_1, \dots, E_n = E'$ such that E_i and E_{i+1} are adjacent parallel edges for $i = 1, \dots, n-1$. Note that parallelism is an equivalence relation on the set of edges of a graph.

3.7. For the statement of the next lemma we introduce the following notation, which will be used throughout the rest of the paper. If $s \geq 0$, $n \geq 0$ and $v > 0$ are integers, we define

$$N(s, n, v) = \max\left(1, 6 + \left\lceil \frac{12s + 6n - 12}{v} \right\rceil\right).$$

Lemma 3.8. *Let S be a compact, connected orientable surface having genus $s \geq 0$ and $n \geq 0$ boundary components. Let $G \subset \text{int } S$ be a non-empty (but possibly disconnected) graph with $v > 0$ vertices. Assume that no two (distinct) edges of G are parallel, and that no loop in G bounds a disk whose interior is disjoint from G . Then G has a vertex of valence at most $N(s, n, v)$.*

Proof. We may assume without loss of generality that G has no vertex of valence 0 or 1.

Let ϕ be any component of $S - G$. Since G has no valence-0 vertices, there exist a compact surface (with boundary) $\hat{\phi}$ and a map $i_\phi: \hat{\phi} \rightarrow S$, such that i_ϕ maps $\text{int } \hat{\phi}$ homeomorphically onto ϕ , and $\partial \hat{\phi}$ has a cell decomposition in which every edge or vertex is mapped homeomorphically by i_ϕ onto an edge or vertex of G . We denote by $o(\phi)$ the number of edges in the cell decomposition of $\partial \hat{\phi}$.

We claim that

$$(*) \quad o(\phi) \geq 3\chi(\hat{\phi})$$

for every component ϕ of $S - G$. This is clear if $\bar{\phi}$ is not a disk, as in that case $\chi(\hat{\phi}) \leq 0$. Now suppose that $\bar{\phi}$ is a disk; we need to show that $o(\phi) \geq 3$. If $o(\phi) = 1$, then there is a loop in G bounding a disk whose interior is disjoint from G ; this contradicts the hypothesis. If $o(\phi) = 2$, and i_ϕ maps the edges of $\hat{\phi}$ to distinct edges E_1 and E_2 of G , then E_1 and E_2 are parallel, and again the hypothesis is contradicted. If $o(\phi) = 2$, and i_ϕ maps the edges of $\hat{\phi}$ to the same edge of G , then $S \cong S^2$ and the graph G has one edge and two vertices. This contradicts our assumption that G has no vertices of valence 1. Thus $(*)$ is proved in all cases.

Summing $(*)$ over the components of $S - G$, we find that

$$2e = \sum_{\phi} o(\phi) \geq 3t,$$

where e denotes the number of edges of G and

$$t = \sum_{\phi} \chi(\hat{\phi}).$$

Now

$$2 - 2s - n = \chi(S) = v - e + t \leq v - \frac{e}{3}.$$

If k denotes the minimum valence of any vertex of G , then we have $2e \geq kv$, and so

$$2 - 2s - n \leq v - \frac{kv}{6}.$$

Since k is an integer it follows that $k \leq N(s, n, v)$. □

Proposition 3.9. *Let M be a simple knot manifold. Let F be a bounded connected essential surface in M with boundary slope β and m boundary components. Let (S, X, h) be a singular surface in M which has boundary slope $\alpha \neq \beta$ and is well positioned with respect to F . Set $s = \text{genus } S$, $n = |\partial S - X|$, $v = |X|$.*

Then there exists an essential homotopy $H : I \times I \rightarrow M$ having length at least

$$\frac{m\Delta(\alpha, \beta)}{N(s, n, v)} - 1$$

such that H_0 is an essential path in F and $H_t(\partial I) \subset \partial M$ for all $t \in I$.

Proof. The definition of a singular surface gives $X \neq \emptyset$, so that $v > 0$. Let \hat{S} denote the surface obtained from S by identifying each component of X to a point. The surface \hat{S} contains a non-empty graph whose vertices are the v points in the image of X , and whose edges are the images of the arc components of $h^{-1}(F)$. Each component of $h(X)$ is a curve on ∂M of slope α , and each component of ∂F is a curve of slope β . Thus it follows from standard position that each component of X meets $h^{-1}(F)$ in $m\Delta(\alpha, \beta)$ points. In other words, each vertex of the graph G has valence $m\Delta(\alpha, \beta)$, which is strictly positive since $\alpha \neq \beta$. Since (S, X, h) is well positioned with respect to F , there is no loop in G bounding a disk whose interior is disjoint from G .

We may apply Lemma 3.8 to a subgraph of G containing exactly one edge from each class of parallel edges. We conclude that the edges emanating from some vertex of G fall into at most $N(s, n, v)$ parallel classes. Thus there must exist some class

of parallel edges containing at least $m\Delta(\alpha, \beta)/N(s, n, v)$ edges. Label the edges of this class E_1, \dots, E_k , where $k \geq m\Delta(\alpha, \beta)/N(s, n, v)$. For each $i = 1, \dots, k$ let A_i be the arc component of $h^{-1}(F)$ which maps to E_i under the quotient map from S to \hat{S} . For each $i = 1, \dots, k-1$ there is a disk Q_i in S bounded by two subarcs of X together with A_i and A_{i+1} . Because (S, X, h) is well positioned with respect to F , the interior of Q_i is disjoint from $f^{-1}(F)$. The restriction of h to this quadrilateral disk defines a basic homotopy H^i whose time-0 map is the path $h(A_i)$ and whose time-1 map is the path $h(A_{i+1})$. The paths $h(A_i)$ are essential because (S, X, h) is well positioned with respect to F . It is an immediate consequence of standard position that each of the basic homotopies H^i is essential; since h is transverse to F , the composition of $H^1 \dots H^{k-1}$ is a reduced homotopy of length $k-1$. The time-0 map of this reduced homotopy is the essential path $h(A_1)$. Since $k \geq m\Delta(\alpha, \beta)/N(s, n, v)$, this completes the proof of the proposition. \square

Corollary 3.10. *Let M be a simple knot manifold that contains an essential surface F with boundary slope β . Suppose that the pair $(M_F, F_- \cup F_+)$ is acylindrical. Let (S, X, h) be a singular surface with boundary slope α which is well positioned with respect to F . Set $s = \text{genus } S$, $n = |\partial S - X|$, $v = |X|$, and $m = |\partial F|$. Then*

$$\Delta(\alpha, \beta) \leq \frac{N(s, n, v)}{m}.$$

Proof. We may assume $\alpha \neq \beta$. According to Proposition 3.9, there exist an essential path $\gamma : I \rightarrow F$ and a reduced homotopy in (M, F) which has time-0 map γ and length at least

$$l \geq \frac{m\Delta(\alpha, \beta)}{N(s, n, v)} - 1.$$

It therefore follows from Subsections 3.4 and 3.5 that there exists a reduced homotopy of length l in (M, F) whose time-0 map is a (possibly singular) essential curve in M . But since $(M_F, F_- \cup F_+)$ contains no properly embedded essential annuli, the Annulus Theorem implies that there can exist no essential basic homotopy in M whose time-0 map is an essential curve in F . Hence we must have

$$\frac{m\Delta(\alpha, \beta)}{N(s, n, v)} - 1 \leq 0,$$

which is equivalent to the conclusion of the corollary. \square

Corollary 3.11. *Let M be a simple knot manifold that contains an essential surface F with boundary slope β . Suppose that the pair $(M_F, F_- \cup F_+)$ is acylindrical. Let α be a slope on ∂M .*

- (1) *If $M(\alpha)$ is a very small manifold, then $\Delta(\alpha, \beta) \leq 5$.*
- (2) *If $M(\alpha)$ is a Seifert fibered space, then $\Delta(\alpha, \beta) \leq 6$.*

Proof. To prove (1) we invoke Corollary 2.3 to obtain a singular surface (S, X, h) , well positioned with respect to F , such that $\text{genus } S = 0$ and $|\partial S - X| = 1$. The conclusion now follows from Corollary 3.10 because for any $v \geq 1$ we have $N(0, 1, v) \leq 5$. To prove (2) we invoke Corollary 2.6 to obtain a singular surface (S, X, h) , well positioned with respect to F , such that either $\text{genus } S = 0$ and $|\partial S - X| = 1$, or $\text{genus } S = 1$ and $|\partial S - X| = 0$. The conclusion now follows from Corollary 3.10 because for any $v \geq 1$ we have $N(0, 1, v) \leq 5$ and $N(1, 0, v) = 6$. \square

4. ESSENTIAL INTERSECTIONS

This section introduces a version of the notion of essential intersection for subsurfaces of a 2-manifold, a notion which has appeared implicitly in much of the literature on the characteristic submanifold of a Haken manifold. The version we present here is adapted to the case of “large” subsurfaces, which we now define.

Let S be a compact orientable surface. We say that a subsurface A of S is *large* if each component of A is π_1 -injective and has negative Euler characteristic. Note that the empty set is considered to be a large subsurface according to this definition. If the components of S have Euler characteristic ≥ 0 , then the empty set is the only large subsurface.

The *large part* of a π_1 -injective subsurface A of S , denoted by $\mathcal{L}(A)$, is the union of all the large components of A .

The next lemma is preliminary to the proof of Proposition 4.2, which will provide the definition of the “large intersection” of two large subsurfaces.

Lemma 4.1. *Let A and B be large subsurfaces of a compact orientable surface S , and suppose that A is homotopic into B .*

- (1) *A is isotopic in S to a subsurface of B .*
- (2) *If B is homeomorphic to a large subsurface of A , then A and B are isotopic subsurfaces of S .*
- (3) *If B is homotopic into A , then A and B are isotopic subsurfaces of S .*

Proof. Without loss of generality we may assume that S is connected.

We begin with the proof of (1). We may assume that A has been chosen within its isotopy class so that ∂A meets ∂B transversely and in the minimal number of points. Moreover, we may assume that A has been chosen, among all surfaces in its isotopy class which minimize $|\partial A \cap \partial B|$, to minimize the number components of ∂A which are not contained in B . Under these assumptions we will show that $A \subset B$, proving (1).

Let A_0 be any component of A . By hypothesis, A_0 is homotopic into a component B_0 of B . We will prove that $A_0 \subset B_0$. As A_0 is an arbitrary component of A , the assertion will follow.

Fix a base point in B_0 , and consider the covering $p: \tilde{S} \rightarrow S$ determined by $\text{im}(\pi_1(B_0) \rightarrow \pi_1(S))$. There is a subsurface \tilde{B}_0 of \tilde{S} which is mapped homeomorphically onto B_0 by p . Since B_0 is large, ∂B_0 is π_1 -injective in S , and hence each component of $X = \tilde{S} - \text{int } \tilde{B}_0$ is a half-open annulus. Since A_0 is homotopic into B_0 , the inclusion $i: A_0 \rightarrow S$ is homotopic to a map which admits a lift to \tilde{S} . Hence i itself admits a lift to \tilde{S} ; that is, we have a subsurface \tilde{A}_0 of \tilde{S} which is mapped homeomorphically onto A_0 by p . In order to show that $A_0 \subset B_0$, it suffices to show that $\tilde{A}_0 \subset \tilde{B}_0$.

As a preliminary, we will prove that $\partial \tilde{A}_0$ is disjoint from $\partial \tilde{B}_0$. Assume this is false. Then $\partial \tilde{A}_0$ contains a properly embedded arc $\tilde{\alpha} \subset X$. Since the component X_0 of X containing $\tilde{\alpha}$ is a half-open annulus, $\partial \tilde{\alpha}$ is the boundary of an arc $\tilde{\beta} \subset \partial X_0 \subset \tilde{B}_0$, and $\tilde{\alpha} \cup \tilde{\beta}$ bounds a disk $\tilde{D} \subset \tilde{S}$. Among all disks in \tilde{S} whose boundaries are made up of an arc in $p^{-1}(\partial A)$ and an arc in $p^{-1}(\partial B)$, choose one, say \tilde{D}_0 , which is minimal with respect to inclusion. Write $\partial \tilde{D}_0 = \tilde{\alpha}_0 \cup \tilde{\beta}_0$, where $\tilde{\alpha}_0 \subset p^{-1}(\partial A)$ and $\tilde{\beta}_0 \subset p^{-1}(\partial B)$ are arcs with $\partial \tilde{\alpha}_0 = \partial \tilde{\beta}_0$. We claim that $p|_{\partial \tilde{D}_0}$ is one-to-one. It is clear from the minimality of \tilde{D}_0 that $p(\text{int } \tilde{\alpha}_0) \cap p(\text{int } \tilde{\beta}_0) = \emptyset$. If $p|_{\text{int } \tilde{\alpha}_0}$ is not one-to-one, then $\alpha = p(\text{int } \tilde{\alpha}_0)$ is an entire component of ∂A , which contains

$p(\partial\tilde{\alpha}_0)$ and therefore meets B ; hence $\text{int } \tilde{\alpha}_0$ meets $p^{-1}(B)$, and the minimality of \tilde{D}_0 is contradicted. Thus $p|\text{int } \tilde{\alpha}_0$ is one-to-one, and similarly $p|\text{int } \tilde{\beta}_0$ is one-to-one. Hence if $p|\partial\tilde{D}_0$ is not one-to-one, then $\alpha_0 = p(\tilde{\alpha}_0)$ and $\beta_0 = p(\tilde{\beta}_0)$ are simple closed curves meeting in a single point; as these curves must be components, the intersection is transverse. But this is impossible, as the hypothesis that A is homotopic into B implies that α_0 and β_0 are homotopic to disjoint curves. Thus $p|\partial D_0$ must be one-to-one.

According to [E, Lemma 1.6], it follows that $p|\tilde{D}_0$ is one-to-one; hence $D_0 = p(\tilde{D}_0)$ is a disk in S whose boundary consists of two arcs, one in B and one in A , and $\text{int } D_0$ is disjoint from ∂A and from ∂B . It follows that ∂B is isotopic to a curve system that meets ∂A transversely in fewer points than ∂B , a contradiction to our choice of B . This proves that $\partial\tilde{A}_0 \cap \partial\tilde{B}_0 = \emptyset$.

We are now ready to prove that $\tilde{A}_0 \subset \tilde{B}_0$. If this is false, then either $\tilde{A}_0 \subset X$ or $\tilde{A}_0 \cap \partial X \neq \emptyset$. If $\tilde{A}_0 \subset X$, then since the components of X are half-open annuli, $\text{im}(\pi_1(A_0) \rightarrow \pi_1(S))$ is cyclic, a contradiction since A is a large subsurface of S . There remains the possibility that \tilde{A}_0 meets the boundary of some component X_1 of X . Since $\partial\tilde{A}_0 \cap \partial\tilde{B}_0 = \emptyset$, the compact subsurface $\tilde{Z} = \tilde{A}_0 \cap X_1$ must have $\tilde{\gamma}_1 = \partial X_1$ as one boundary component. If $\tilde{\gamma}$ is any other component of $\partial\tilde{Z}$, then $\tilde{\gamma}$ lies in the interior of the half-open annulus X_1 ; furthermore, $\tilde{\gamma}$ is a component of $\partial\tilde{A}_0$, and is therefore homotopically non-trivial (since the large subsurface A_0 of S is in particular π_1 -injective). It follows that \tilde{Z} is an annulus bounded by $\tilde{\gamma}_1$ and a single component $\tilde{\gamma}_2$ of $\partial\tilde{A}_0$. Since p maps \tilde{A}_0 homeomorphically onto A_0 , it in particular maps \tilde{Z} homeomorphically onto an annulus $Z \subset A_0$. There is an isotopy supported on a small neighborhood W of Z in S which carries $\gamma_1 = p(\tilde{\gamma}_1)$ into $\text{int } B_0$. Since W may be taken to meet ∂A only in γ_1 , it is clear that the image of A under the isotopy has the same intersection with B as A has, and has fewer components ∂A which are not contained in B than A has. This contradiction to the minimality of A completes the proof of (1).

We now turn to the proof of (2). By part (1) we may assume that A is a subsurface of $\text{int } B$. Let B' be a π_1 -injective subsurface of $\text{int } A$ which is homeomorphic to B . Any disk component of $\overline{B - A}$ would also be a component of $\overline{S - A}$. Since A is large it follows that no component of $\overline{B - A}$ is a disk. Hence $\chi(B) \leq \chi(A)$. Similarly, $\chi(A) \leq \chi(B') = \chi(B)$. Thus each component of $\overline{B - A}$ is an annulus, and each component of $\overline{A - B'}$ is an annulus. Since A and B are large it follows that each component of B contains at least one component of A and that each component of A contains at least one component of B' . Since B is homeomorphic to B' , a given component of B can contain only one component of B' . Hence each component of B contains exactly one component of A .

We may therefore index the components of A as A_1, \dots, A_n , and index the components of B as B_1, \dots, B_n , in such a way that A_i is a subsurface of B_i for $i = 1, \dots, n$, and each component of $\overline{B_i - A_i}$ is an annulus.

To complete the proof of (2) it suffices to show that there is no annulus component of $\overline{B_i - A_i}$ whose boundary is contained in A_i . If such an annulus component did exist the genus of B_i would be strictly greater than the genus of A_i . In particular we would have $\text{genus } B = \sum \text{genus } B_i > \sum \text{genus } A_i = \text{genus } A$. (Recall that $\text{genus } B$ denotes the total genus of B .) But since B is homeomorphic to the subsurface B' of A , we have $\text{genus } B = \text{genus } B' \leq \text{genus } A$. This contradiction completes the proof of (2).

To prove (3), note that if B is homotopic into A , then by (1) it is isotopic into A . The time-1 map of the isotopy is a homeomorphism onto a subsurface of A which is clearly large since it is isotopic to B . It now follows from (2) that A and B are isotopic. \square

A map f from a finite polyhedron K to a surface S is called *large* if for each component K_0 of K , the subgroup $f_{\#}(\pi_1(K_0))$ of $\pi_1(S)$ is non-abelian.

Proposition 4.2. *Suppose that A and B are large subsurfaces of a compact orientable surface S . Then up to non-ambient isotopy there is a unique large subsurface C of S with the following property:*

(*) *Any large map from a polyhedron into S is homotopic into C if and only if it is homotopic into A and homotopic into B .*

Furthermore, if $C \subset \text{int } S$ is a large subsurface satisfying (*), then there are subsurfaces $A_0 \subset \text{int } S$ and $B_0 \subset \text{int } S$, isotopic to A and B , such that ∂A_0 and ∂B_0 meet transversely and $C = \mathcal{L}(A_0 \cap B_0)$.

Proof. We may assume without loss of generality that $A, B \subset \text{int } S$. We prove uniqueness first. Suppose that C and C' are large subsurfaces of S satisfying (*). Then the inclusion $C \rightarrow S$ is homotopic into C' , and vice versa. Lemma 4.1(3) now implies that C and C' are isotopic in S .

To complete the proof of the proposition, it suffices to show that there is a subsurface B_0 of $\text{int } S$ isotopic to B , such that ∂A and ∂B_0 meet transversely and such that $\mathcal{L}(A \cap B_0)$ satisfies (*). We define B_0 as follows: among all subsurfaces of $\text{int } S$ which are isotopic to B , and whose boundaries meet ∂A transversely, we choose B_0 so that the number of points of $\partial A \cap \partial B_0$ is as small as possible. We set $C = \mathcal{L}(A \cap B_0)$.

It is clear that if a large map from a connected polyhedron K into S is homotopic into C , then it is homotopic into A and homotopic into B . The proof of (*) will be completed by showing that, conversely, if a large map $f : K \rightarrow S$ is homotopic into A and homotopic into B , then it is homotopic into C . We may assume without loss of generality that K is non-empty and connected. We fix a component A_1 of A such that f is homotopic into A_1 .

Let \tilde{S} denote the covering space of $\text{int } S$ corresponding to the subgroup

$$\text{im}(\pi_1(A_1) \rightarrow \pi_1(\text{int } S)).$$

Then \tilde{S} has a subsurface \tilde{A} such that the covering projection $p : \tilde{S} \rightarrow \text{int } S$ maps \tilde{A} homeomorphically onto A_1 . Set $X = \tilde{S} - \text{int } \tilde{A}$. Since A is π_1 -injective, each component of X is a half-open annulus meeting \tilde{A} in a component of $\partial \tilde{A}$.

Since $f : K \rightarrow S$ is homotopic into A_1 it admits a lift \tilde{f} to the covering space \tilde{S} . Since f is also homotopic into B_0 , there is a homotopy from \tilde{f} to a map $g : K \rightarrow \tilde{S}$ such that $g(K)$ is contained in a component \tilde{B}_0 of $p^{-1}(B_0)$.

We claim that $\tilde{B}_0 \cap \tilde{A} \neq \emptyset$. Suppose not; then $g(K) \subset \tilde{B}_0 \subset X$. But $g_{\#}(\pi_1(K)) \subset \pi_1(\tilde{S})$ is non-abelian since f is a large map. Since each component of X is a half-open annulus, we have a contradiction, and the claim is proved.

We next claim that if Z is any component of $\tilde{B}_0 \cap X$, then Z deforms into $W = Z \cap \partial X \subset \partial \tilde{A}$. (This means that the identity map of Z is homotopic in Z , rel W , to a map whose image is contained in W .) To prove the claim, first note that W is a 1-manifold in the boundary of the 2-manifold Z . Furthermore, since $\tilde{B}_0 \cap \tilde{A} \neq \emptyset$, we have $W \neq \emptyset$. Hence, in order to prove that Z deforms into W ,

it suffices to show that if $\alpha \subset Z$ is an arc with endpoints in W , then α is parallel in Z to an arc in W . Since X is a half-open annulus, α is parallel in X to an arc $\beta \subset \partial X$. We must show that the disk $D \subset X$ bounded by $\alpha \cup \beta$ is contained in Z .

If $D \not\subset Z$, then D contains a component γ of the frontier of Z relative to X . Note that $\gamma \subset \partial \tilde{B}_0$, and that γ is a properly embedded 1-manifold in X . But γ cannot be a simple closed curve, since B_0 is π_1 -injective in S ; hence γ is an arc whose endpoints lie in β . Thus there is a disk in \tilde{S} whose boundary is the union of the arc $\gamma \subset p^{-1}(\partial B_0)$ and a sub-arc of $\beta \subset p^{-1}(\partial A)$. Among all disks in \tilde{S} bounded by the union of an arc in $p^{-1}(\partial A)$ with an arc in $p^{-1}(\partial B_0)$, choose one, say D' , which is minimal with respect to inclusion. According to [E, Lemma 1.6], $p|_{D'}$ is one-to-one and hence $p(D')$ is a disk in S whose boundary consists of two arcs, one in B_0 and one in A , which meet at their endpoints. Since B_0 is large we have $\text{int } p(D') \cap B_0 = \emptyset$. We may therefore isotope B_0 across the disk $p(D')$ to obtain a surface whose boundary meets ∂A in fewer points than ∂B_0 . This contradicts our choice of B_0 , and the claim is proved.

We have shown that $\tilde{B}_0 \cap \tilde{A} \neq \emptyset$ and that every component of $\tilde{B}_0 \cap X$ deforms into its intersection with $\partial X = \partial \tilde{A}$. It follows that \tilde{B}_0 deforms into $\tilde{B}_0 \cap \tilde{A}$. Since \tilde{f} is homotopic to g and $g(K) \subset \tilde{B}_0$, it follows that \tilde{f} is homotopic in \tilde{S} to a map of K into $\tilde{B}_0 \cap \tilde{A}$. In particular, f is homotopic in S to a map f' whose image is contained in $B_0 \cap A_1 \subset B_0 \cap A$. As f is large it follows that $f(K) \subset \mathcal{L}(B_0 \cap A) = C$. \square

Definition 4.3. If A and B are large subsurfaces of a compact orientable surface S , then the subsurface provided by Proposition 4.2, which is well defined up to non-ambient isotopy, will be called the *large intersection* of A and B and will be denoted $A \wedge_{\mathcal{L}} B$. Clearly $A \wedge_{\mathcal{L}} B$ is isotopic to $B \wedge_{\mathcal{L}} A$, and $A \wedge_{\mathcal{L}} (B \wedge_{\mathcal{L}} C)$ is isotopic to $(A \wedge_{\mathcal{L}} B) \wedge_{\mathcal{L}} C$.

The following result will be needed in the next two sections.

Proposition 4.4. *Suppose that A is a large subsurface of a compact orientable surface S , and that f and g are large maps of a polyhedron K into A . If f and g are homotopic in S , then they are homotopic in A .*

Proof. We may assume that K and S are connected. Let A_0 denote the component of A containing $f(K)$, and let $p: \tilde{S} \rightarrow S$ denote the largest covering space of S to which the inclusion map $i: A_0 \rightarrow S$ lifts. If $\tilde{i}: A_0 \rightarrow \tilde{S}$ is the lift of i , then $\tilde{A}_0 = \tilde{i}(A_0)$ is a deformation retract of \tilde{S} , and each component of $\tilde{S} - \tilde{A}_0$ has cyclic (and possibly trivial) fundamental group. Let $\tilde{f}: K \rightarrow \tilde{S}$ be a lift of f with $\tilde{f}(K) \subset \tilde{A}_0$, and let $\tilde{g}: K \rightarrow \tilde{S}$ be a lift of g which is homotopic to \tilde{f} in \tilde{S} . Since g is large, $\tilde{g}(\pi_1(K))$ is not cyclic; thus $\tilde{g}(K)$ cannot be contained in a component $\tilde{A}'_0 \neq \tilde{A}_0$ of $p^{-1}(A_0)$. Hence $\tilde{g}(K) \subset \tilde{A}_0$, and \tilde{f} and \tilde{g} are homotopic in \tilde{A}_0 . The conclusion follows. \square

Lemma 4.5. *Let A be a large subsurface of a compact orientable surface B , and suppose that B admits an involution τ such that $\tau(A)$ is isotopic to A in B . Then A is isotopic to a subsurface A' of B such that $\tau(A') = A'$.*

Proof. Choose a negatively curved metric on B which is invariant under the involution τ and has the property that the boundary components of B are geodesics. Given a large subsurface C of B we divide its boundary components into two types:

Type 1: those which are not isotopic to any other boundary component of C .

Type 2: those which are isotopic to some other boundary component of C .

There is a small positive real number t_0 such that A can be isotoped in B to a surface A' whose type 1 boundary components are geodesics and whose type 2 boundary components form the boundary of a t_0 -bicollar of a finite union of geodesics. Then $\partial A'$ is invariant under the involution τ . To see that $\tau(A') = A'$ let A'_0 be a component of A' . If $\tau(A'_0) \not\subset A'$, then the interior of $\tau(A'_0)$ is disjoint from A' and hence we may isotope $\tau(A'_0)$ into the complement of A' . Let $p : \tilde{B} \rightarrow B$ be the maximal connected cover for which the inclusion map $i : \tau(A'_0) \rightarrow B$ lifts to a map $\tilde{i} : \tau(A'_0) \rightarrow \tilde{B}$ and define $Y = \tilde{i}(\tau(A'_0))$. Then $X = \tilde{B} - \text{int } Y$ is a disjoint union of half-open annuli. By hypothesis \tilde{i} is homotopic to a map with image in X so that in particular Y may be homotoped into an annulus. It follows from Lemma 4.1 that Y is isotopic to a subsurface of an annulus. Since Y is π_1 -injective and homeomorphic to A_0 , this contradicts our assumption that A_0 is large. Thus $\tau(A'_0) \subset A'$ and we deduce that $\tau(A') = A'$. \square

4.6. Let A be a subsurface of a compact orientable surface S . By an *outer component* of A we will mean a component of A which contains a simple closed curve that is isotopic to a boundary component of S . We will say that A is *outer* if every component of A is outer. We define the *outer part* of A , denoted \dot{A} , to be the union of all outer components of A , i.e. the largest outer subsurface of A . Thus A is an outer subsurface if and only if $A = \dot{A}$.

If A and B are subsurfaces of S with $A \subset B$, note that $\dot{A} \subset \dot{B}$. If A and B are large subsurfaces of S , we define $A \hat{\wedge}_{\mathcal{L}} B$ to be the outer part of $A \wedge_{\mathcal{L}} B$. It is a formal consequence of this definition that a large outer subsurface of S is homotopic into both A and B if and only if it is homotopic into $A \hat{\wedge}_{\mathcal{L}} B$. It follows from this, together with Lemma 4.1, that if A, B and C are large subsurfaces of S , then $A \hat{\wedge}_{\mathcal{L}} B$ is homotopic to $B \hat{\wedge}_{\mathcal{L}} A$ and $(A \hat{\wedge}_{\mathcal{L}} B) \hat{\wedge}_{\mathcal{L}} C$ is isotopic to $A \hat{\wedge}_{\mathcal{L}} (B \hat{\wedge}_{\mathcal{L}} C)$.

Lemma 4.7. *Suppose that A and B are large subsurfaces of a compact orientable surface S . Then $A \hat{\wedge}_{\mathcal{L}} B$ is isotopic in S to $\dot{A} \hat{\wedge}_{\mathcal{L}} \dot{B}$.*

Proof. Since each component of $\dot{A} \hat{\wedge}_{\mathcal{L}} \dot{B}$ contains a simple closed curve that is isotopic to a boundary component of S , it is clear that $A \hat{\wedge}_{\mathcal{L}} B \supset \dot{A} \hat{\wedge}_{\mathcal{L}} \dot{B}$. To prove the reverse inclusion, let C be a component of $A \hat{\wedge}_{\mathcal{L}} B$. We have that C is isotopic into $X \wedge_{\mathcal{L}} Y$, where X and Y are components of A and B respectively. Since C contains a simple closed curve isotopic to a boundary component of S , so do X and Y . Thus X and Y are in fact components of \dot{A} and \dot{B} , respectively. This shows that C is isotopic into a component of $\dot{A} \wedge_{\mathcal{L}} \dot{B}$. But, since C contains a simple closed curve isotopic to a boundary component of S , it is isotopic into a component of $\dot{A} \hat{\wedge}_{\mathcal{L}} \dot{B}$. Since C was an arbitrary component of $A \hat{\wedge}_{\mathcal{L}} B$, we have shown that $A \hat{\wedge}_{\mathcal{L}} B$ is homotopic into $\dot{A} \hat{\wedge}_{\mathcal{L}} \dot{B}$. The lemma now follows from Lemma 4.1. \square

5. REDUCED HOMOTOPIES AND THE CHARACTERISTIC PAIR

The final result of this section, Theorem 5.4.1, concerns a pair (M, F) , where M is a simple knot manifold and $F \subset M$ is an essential surface in M which is not semi-fiber. The theorem provides an upper bound, in terms of the genus and the number of boundary components of F , for the length of a reduced homotopy in (M, F) having a large time-0 map.

5.1. Splitting surfaces.

Definition 5.1.1. Let M be simple knot manifold. A *splitting surface* in M is a transversely oriented essential surface $\tilde{F} \subset M$ such that $M_{\tilde{F}}$ is a disjoint union of two compact submanifolds $M_{\tilde{F}}^+$ and $M_{\tilde{F}}^-$ with the property that $N_\epsilon(\tilde{F}) \subset M_{\tilde{F}}^\epsilon$ for $\epsilon = \pm 1$.

It is easy to see that $M_{\tilde{F}}^+$ and $M_{\tilde{F}}^-$ are uniquely determined by \tilde{F} . Note that any transversely oriented, separating, connected, essential surface in M is a splitting surface. In general, however, a splitting surface need not be connected.

Since \tilde{F} comes equipped with a transverse orientation, any orientation of M induces an orientation of \tilde{F} . An orientation of \tilde{F} will be called *consistent* if it is induced from an orientation of M in this way. If \tilde{F} has n components, then it has 2^n possible orientations; but since M is connected, only two of these orientations are consistent.

If \tilde{F} is a splitting surface, then for $\epsilon = \pm 1$ the natural map from $M_{\tilde{F}}^\epsilon$ to M is injective and we shall identify $M_{\tilde{F}}^+$ and $M_{\tilde{F}}^-$ with submanifolds of M . In particular \tilde{F}_ϵ is identified with \tilde{F} via the homeomorphism i_ϵ (see Subsection 1.3). Furthermore we shall identify basic homotopies in (M, F) with the corresponding homotopies in $(M_{\tilde{F}}, \tilde{F}_- \cup \tilde{F}_+)$ (see Subsection 3.1).

An orientation of M determines an orientation of $M_{\tilde{F}}^\epsilon$ by restriction, and this orientation of $M_{\tilde{F}}^\epsilon$ induces an orientation of \tilde{F}_ϵ . The two orientations of \tilde{F}_ϵ which arise in this way are identified with the two consistent orientations of \tilde{F} .

5.2. Supports of reduced homotopies. Throughout this subsection we shall assume that M is a simple knot manifold, and that \tilde{F} is a splitting surface in M .

5.2.1. It follows from the characteristic submanifold theory of Jaco-Shalen [JS] and Johannson [Jo] that for each $\epsilon \in \{\pm 1\}$ there is an $(I, \partial I)$ -bundle pair $(\Sigma^\epsilon, \Phi^\epsilon) \subset (M_{\tilde{F}}^\epsilon, \tilde{F})$, well defined up to ambient isotopy in $(M_{\tilde{F}}^\epsilon, \tilde{F})$, such that

- (1) the frontier of Σ^ϵ in $M_{\tilde{F}}^\epsilon$ consists of essential annuli in $(M_{\tilde{F}}^\epsilon, \tilde{F})$;
- (2) no component (σ, ϕ) of $(\Sigma^\epsilon, \Phi^\epsilon)$ is homotopic (as a pair) into $(\Sigma^\epsilon - \sigma, \Phi^\epsilon - \phi)$;

and

- (3) if K is a polyhedron and $H: (K \times I, K \times \partial I) \rightarrow (M_{\tilde{F}}^\epsilon, \tilde{F})$ is an essential basic homotopy such that $H_0: K \rightarrow \tilde{F}$ is a large map, then H is homotopic as a map of pairs to a homotopy whose image lies in Σ^ϵ .

The I -fibers of the I -bundle structure on Σ^ϵ can be used to build an essential basic homotopy of Φ^ϵ in Σ^ϵ . Indeed, define a *fundamental homotopy* of Φ^ϵ to be any essential basic homotopy

$$H_{\Sigma^\epsilon}: (\Phi^\epsilon \times I, \Phi^\epsilon \times \partial I) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon) \subset (M_{\tilde{F}}^\epsilon, \tilde{F})$$

satisfying the following conditions:

- (1) The time-0 map of H_{Σ^ϵ} is the identity map of Φ^ϵ .
- (2) For each $x \in \Phi^\epsilon$, $H_{\Sigma^\epsilon}(\{x\} \times I)$ is an I -fiber of Σ^ϵ .
- (3) For each component ϕ of Φ^ϵ which is contained in a trivial I -bundle component σ of Σ^ϵ , the map H_{Σ^ϵ} restricts to a homeomorphism of $\phi \times I$ onto σ .
- (4) For each component ϕ of Φ^ϵ which is contained in a non-trivial I -bundle component σ of Σ^ϵ , the map H_{Σ^ϵ} restricts to a 2-fold covering map from $\phi \times I$ to σ .

It is clear that a fundamental homotopy exists and is unique up to composition with a fiber-preserving homeomorphism of Σ^ϵ which restricts to the identity on Φ^ϵ . Note also that a fundamental homotopy is a two-sheeted covering map from $\Phi^\epsilon \times I$ to Σ^ϵ . The involution of Φ^ϵ induced by its ∂I -bundle structure is the restriction of the deck transformation of this two-sheeted covering map. This involution will be denoted by τ_ϵ . Thus

$$H_{\Sigma^\epsilon}(x, 1) = \tau_\epsilon(x)$$

for every $x \in \Phi^\epsilon$.

The notation Σ^ϵ , Φ^ϵ and τ_ϵ will be used throughout this section.

Lemma 5.2.2. *Let \tilde{F} be given a consistent orientation. Then the embedding $\tau_\epsilon : \Phi^\epsilon \rightarrow \tilde{F}$ reverses orientation. (See Subsection 1.1.)*

Proof. By Subsection 5.1, the orientation of Φ^ϵ is induced from an orientation of $M_{\tilde{F}}^\epsilon$. Hence, if we orient Σ^ϵ by restricting the orientation of $M_{\tilde{F}}^\epsilon$, then the orientation of Φ^ϵ is induced by the orientation of Σ^ϵ . The involution τ_ϵ extends to an involution σ of Σ^ϵ which leaves each I -fiber invariant while reversing its orientation. Since σ clearly reverses the orientation of Σ^ϵ , it follows that τ_ϵ reverses the orientation of Φ^ϵ . \square

Definition 5.2.3. An essential basic homotopy $H : (K \times I, K \times \partial I) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon)$ is said to be *standard* if it is of the form $H(x, t) = H_{\Sigma^\epsilon}(f(x), t)$, where H_{Σ^ϵ} is a fundamental homotopy and f is some map from K to Φ^ϵ . Note that we then have $H_0 = f$. Note also that if $f' : K \rightarrow \Phi^\epsilon$ is homotopic to f in Φ^ϵ , then the standard homotopies $H(x, t) = H_{\Sigma^\epsilon}(f(x), t)$ and $H'(x, t) = H_{\Sigma^\epsilon}(f'(x), t)$ are homotopic as maps of pairs $(K \times I, K \times \partial I) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon)$.

Lemma 5.2.4. *If $H : (K \times I, K \times \partial I) \rightarrow (M_{\tilde{F}}^\epsilon, \tilde{F})$ is an essential basic homotopy such that $H_0 : K \rightarrow \tilde{F}$ is a large map, then H is homotopic as a map of pairs to a standard essential basic homotopy.*

Proof. Appealing to the characteristic submanifold theory [JS], [Jo], we may assume, without loss of generality, that $H(K \times I) \subset \Sigma^\epsilon$ and $H(K \times \partial I) \subset \Phi^\epsilon$. It is not hard to see that H lifts to a map $\tilde{H} : (K \times I, K \times \partial I) \rightarrow (\Phi^\epsilon \times I, \Phi^\epsilon \times \{0, 1\})$ such that $H = H_{\Sigma^\epsilon} \circ \tilde{H}$. Write $\tilde{H}(x, t) = (H'(x, t), T(x, t)) \in \Phi^\epsilon \times I$ and observe that $T(x, 0) = 0$ for each $x \in K$, while the essentiality of H implies that $T(x, 1) = 1$ for each x .

Let $J : ((K \times I) \times I, (K \times I) \times \{0, 1\}) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon)$ be given by

$$J((x, t), s) = H_{\Sigma^\epsilon}(H'(x, (1 - s)t), (1 - s)T(x, t) + st).$$

Then

$$\begin{aligned} J((x, t), 0) &= (H_{\Sigma^\epsilon} \circ \tilde{H})(x, t) = H(x, t), \text{ and} \\ J((x, t), 1) &= H_{\Sigma^\epsilon}(H'(x, 0), t) = H_{\Sigma^\epsilon}(H_0(x), t), \end{aligned}$$

while for each $x \in K$,

$$\begin{aligned} J((x, 0), s) &= H(x, 0) \in \Phi^\epsilon, \text{ and} \\ J((x, 1), s) &= H_{\Sigma^\epsilon}(H'(x, 1 - s), 1) \in \Phi^\epsilon. \end{aligned}$$

Thus $H = J_0$ is homotopic as a map of pairs to the standard essential basic homotopy J_1 . \square

5.2.5. We define $\Phi_1^\epsilon = \mathcal{L}(\Phi^\epsilon) \subset \tilde{F}$. Note that the free involution τ_ϵ restricts to a free involution of Φ_1^ϵ . We shall denote this restriction by τ_ϵ as well.

Lemma 5.2.6. *The surface Φ_1^ϵ has the following property.*

For any large map $f: K \rightarrow \tilde{F}$, there exists an essential basic homotopy H in the pair (M, \tilde{F}) on the ϵ -side with $H_0 = f$ if and only if f is homotopic in \tilde{F} to a map with image in Φ_1^ϵ .

Furthermore, any large subsurface of F with this property is isotopic to Φ_1^ϵ .

Proof. If $f: K \rightarrow \tilde{F}$ is a large map homotopic in \tilde{F} to some f' for which $f'(K) \subset \Phi_1^\epsilon$ and $H_{\Sigma^\epsilon}: (\Phi^\epsilon \times [0, 1], \Phi^\epsilon \times \{0, 1\}) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon)$ is a fundamental homotopy, then $H: (K \times [0, 1], K \times \{0, 1\}) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon) \subset (M_{\tilde{F}}^\epsilon, \tilde{F})$ defined by

$$H(x, t) = H_{\Sigma^\epsilon}(f'(x), t)$$

is an essential basic homotopy in (M, \tilde{F}) on the ϵ -side, with $H_0 = f'$. The desired essential basic homotopy with time-0 map f is now readily constructed.

Conversely let $H: (K \times [0, 1], K \times \{0, 1\}) \rightarrow (M, \tilde{F})$ be an essential basic homotopy in (M, \tilde{F}) on the ϵ -side with $H_0 = f$. According to Subsection 3.1, any essential basic homotopy in (M, \tilde{F}) which starts on the ϵ -side corresponds to an essential homotopy in the pair $(M_{\tilde{F}}^\epsilon, \tilde{F})$. So it follows from Lemma 5.2.4 that H is homotopic as a map of pairs to a standard essential basic homotopy H' . It follows from Subsection 5.2.1 and Definition 5.2.3 that $H'_t(K) \subset \Phi^\epsilon$ for $t = 0, 1$, that H'_0 is homotopic to f and that $H'_1 = \tau_\epsilon \circ H'_0$. Since f , and hence H'_0 , is large, the image of H'_0 is contained in Φ_1^ϵ .

Finally suppose that $\Psi_1^\epsilon \subset \tilde{F}$ is another large subsurface of \tilde{F} which has the stated property. Then the inclusion $\Phi_1^\epsilon \rightarrow \tilde{F}$ is homotopic into Ψ_1^ϵ and vice versa. Thus by Lemma 4.1, Ψ_1^ϵ is isotopic to Φ_1^ϵ in \tilde{F} . \square

Lemma 5.2.7. *Let $H: (K \times I, K \times \partial I) \rightarrow (M, \tilde{F})$ be an essential basic homotopy on the ϵ -side such that H_0 is a large map from K to \tilde{F} . If $f: K \rightarrow \Phi_1^\epsilon$ is any map which is homotopic in \tilde{F} to H_0 , then H_1 is homotopic in \tilde{F} to $\tau_\epsilon \circ f$.*

Proof. By Lemma 5.2.4 the homotopy H is homotopic as a map of pairs to a standard essential basic homotopy H' . By Proposition 4.4 H'_0 is homotopic to f in Φ_1^ϵ and so by the remark at the end of Definition 5.2.3 we may assume that $H'_0 = f$. Thus H_1 is homotopic in \tilde{F} to $H'_1 = \tau_\epsilon \circ f$. \square

Our next goal is to extend Lemma 5.2.6 to reduced homotopies of length n in (M, \tilde{F}) .

Proposition 5.2.8. *For each fixed $\epsilon \in \{\pm 1\}$, there is a sequence of large (possibly empty) subsurfaces $(\Phi_k^\epsilon)_{k \geq 0}$ of \tilde{F} , such that $\Phi_0^\epsilon = \tilde{F}$, Φ_1^ϵ is the surface defined in Subsection 5.2.5, and for each $k \geq 0$ we have:*

- (1) $\Phi_k^\epsilon \supset \Phi_{k+1}^\epsilon$; and
- (2) a large map $f: K \rightarrow \tilde{F}$ is homotopic in \tilde{F} to a map with image in Φ_k^ϵ if and only if there exists a reduced homotopy H of length k starting on the ϵ -side with $H_0 = f$.

Furthermore condition (2) determines Φ_k^ϵ , up to isotopy, among the class of large subsurfaces of \tilde{F} .

Proof. We construct the surfaces inductively in such a way that (1) and (2) hold. Set $\Phi_0^\epsilon = \tilde{F}$ and let Φ_1^ϵ be defined as in Subsection 5.2.5. According to Lemma 5.2.6, condition (2) holds for $k = 1$. Let $m \geq 2$ be given, and suppose that for $\epsilon = \pm 1$ we have defined large subsurfaces

$$\tilde{F} = \Phi_0^\epsilon \supset \Phi_1^\epsilon \supset \Phi_2^\epsilon \supset \cdots \supset \Phi_{m-1}^\epsilon$$

such that condition (2) holds for $k < m$ and for $\epsilon = \pm 1$. As we observed in Definition 4.3, there is a surface $A_m^\epsilon \subset \Phi_1^\epsilon$ which is isotopic to the large intersection $\Phi_1^\epsilon \wedge_{\mathcal{L}} \Phi_{m-1}^{-\epsilon}$. For $\epsilon = \pm 1$ we define

$$\Psi_m^\epsilon = \tau_\epsilon(A_m^\epsilon).$$

Note that by Subsection 5.2.5, Φ_1^ϵ is invariant under the map τ_ϵ and so we have

$$\Psi_m^\epsilon \subset \Phi_1^\epsilon.$$

For $\epsilon = \pm 1$, we claim that:

- (*) a large map $f: K \rightarrow \tilde{F}$ is homotopic in \tilde{F} to a map with image in Ψ_m^ϵ if and only if there exists a reduced homotopy H of length m starting on the ϵ -side with $H_0 = f$.

To prove this, we first consider a large map $f: K \rightarrow \tilde{F}$ and assume that there exists a reduced homotopy $H: K \times I \rightarrow (M, \tilde{F})$ of length m starting on the ϵ -side with $H_0 = f$. Write H as a composition of m essential basic homotopies H^1, \dots, H^m , where H^i starts on the $(-1)^{i-1}\epsilon$ side for $i = 1, \dots, m$. Define $f_1: K \rightarrow \tilde{F}$ by $f_1 = H_1^1 = H_0^2$ and let H' be the composition of H^2, \dots, H^m . Then f_1 is large and H' is a reduced homotopy of length $m - 1$ starting on the $-\epsilon$ -side, with $H'_0 = f_1$. Our inductive hypothesis implies that f_1 is homotopic to a map with image in $\Phi_{m-1}^{-\epsilon}$. On the other hand, H^1 is an essential basic homotopy on the ϵ -side with $H_0^1 = f$ and $H_1^1 = f_1$; hence by Lemma 5.2.7 we see that f_1 is homotopic in \tilde{F} to a map f'_1 whose image lies in Φ_1^ϵ , and that f is homotopic in \tilde{F} to $\tau_\epsilon \circ f'_1$. Proposition 4.2 now implies that f'_1 is homotopic in \tilde{F} to a map f''_1 whose image lies in A_m^ϵ . Proposition 4.4 implies that f'_1 is homotopic to f''_1 in Φ_1^ϵ . Composing this homotopy with τ_ϵ we see that f is homotopic to a map with image in $\tau_\epsilon(A_m^\epsilon) = \Psi_m^\epsilon$.

To prove the converse observe that the fundamental homotopy

$$H = H_{\Sigma^\epsilon}: (\Phi^\epsilon \times [0, 1], \Phi^\epsilon \times \{0, 1\}) \rightarrow (\Sigma^\epsilon, \Phi^\epsilon)$$

is an essential basic homotopy H in (M, \tilde{F}) on the ϵ -side such that H_1 is the inclusion $i_0: \Phi_1^\epsilon \rightarrow \tilde{F}$, and $H_1 = \tau_\epsilon|_{\Phi_1^\epsilon}$. Since $\Psi_m^\epsilon \subset \Phi_1^\epsilon$, we may restrict H to $\Psi_m^\epsilon \times I$ to obtain an essential basic homotopy H^1 in (M, \tilde{F}) on the ϵ -side. The time-0 map of H^1 is the inclusion $\Psi_m^\epsilon \rightarrow \tilde{F}$ and the time-1 map of H^1 is a homeomorphism $\psi: \Psi_m^\epsilon \rightarrow A_m^\epsilon$. By Proposition 4.2 and Definition 4.3, A_m^ϵ is isotopic to a subsurface of $\Phi_{m-1}^{-\epsilon}$. Since our induction hypothesis implies that the inclusion $\Phi_{m-1}^{-\epsilon} \rightarrow \tilde{F}$ is the time-0 map of a reduced homotopy of length $m - 1$ starting on the $-\epsilon$ side, it follows that ψ is also the time-0 map of a reduced homotopy H' in (M, \tilde{F}) of length $m - 1$ starting on the $-\epsilon$ -side. The composition of the two homotopies H_1 and H' is a reduced homotopy of length m starting on the ϵ -side whose time-0 map is the inclusion $\Psi_m^\epsilon \rightarrow \tilde{F}$. This completes the proof of (*).

It follows from (*) that there is a reduced homotopy of length m starting on the ϵ -side with time-0 map equal to the inclusion map of Ψ_m^ϵ into \tilde{F} . Clearly there also exists a reduced homotopy of length $m - 1$ starting on the same side and having

the same time-0 map. Thus we may apply property (2) again to conclude that the inclusion map of Ψ_m^ϵ is homotopic to a map with image in Φ_{m-1}^ϵ . By Lemma 4.1, Ψ_m^ϵ is isotopic to a subsurface Φ_m^ϵ of Φ_{m-1}^ϵ . It follows from (*) that condition (2) holds for $k = m$. The induction is now complete.

To prove the last assertion of the proposition, suppose that $\Psi_k^\epsilon \subset \tilde{F}$ is another large surface in \tilde{F} which satisfies condition (2) of the theorem. Taking f to be the inclusion map of either surface into \tilde{F} , we see that Φ_k^ϵ is homotopic into Ψ_k^ϵ and vice versa. Thus by Lemma 4.1, Ψ_k^ϵ is isotopic to Φ_k^ϵ in \tilde{F} . \square

5.3. Time-1 maps of reduced homotopies. Throughout this section M will denote a simple knot manifold and \tilde{F} will denote a splitting surface in M . We will define Φ^ϵ and τ_ϵ as in Subsection 5.2. We shall also fix subsurfaces Φ_k^ϵ of \tilde{F} for which the conclusions of Proposition 5.2.8 hold. A crucial ingredient in obtaining a bound of the type given by Theorem 5.4.1 is provided by Proposition 5.3.9, which asserts that if the inclusion $\Phi_{k+2}^\epsilon \subseteq \Phi_k^\epsilon$ is a homotopy equivalence, then \tilde{F} is a semi-fiber. The estimate is strengthened by using Proposition 5.3.7, which asserts that for each odd k , Φ_k^ϵ admits a fixed-point free involution.

Proposition 5.3.1. *For each $\epsilon \in \{\pm 1\}$ and each $k \geq 0$ there exists a homeomorphism $h_k^\epsilon : \Phi_k^\epsilon \rightarrow \Phi_k^{(-1)^{k+1}\epsilon}$ which has the following property:*

- (*) *For any reduced homotopy H of length k with domain K which starts on the ϵ side and has a large time-0 map, there exists a map $f : K \rightarrow \Phi_k^\epsilon$ such that H_0 is homotopic in \tilde{F} to f and H_1 is homotopic in \tilde{F} to $h_k^\epsilon \circ f$.*

The homeomorphism h_k^ϵ is unique up to isotopy. Furthermore, if \tilde{F} is given a consistent orientation, then the embedding $h_k^\epsilon : \Phi_k^\epsilon \rightarrow \tilde{F}$ reverses orientation if k is odd and preserves orientation if k is even. (See Subsection 1.1.) We may take h_1^ϵ to be the map $\tau_\epsilon|_{\Phi_1^\epsilon}$ described in Subsection 5.2.5.

Proof. We construct the maps h_k^ϵ by induction on k . For each $\epsilon \in \{\pm 1\}$ define h_0^ϵ to be the identity map of \tilde{F} and h_1^ϵ to be the map τ_ϵ . It is clear that property (*) holds for h_0^ϵ and Lemmas 5.2.6 and 5.2.7 imply that it holds for h_1^ϵ .

Suppose that for $\epsilon = \pm 1$ we have constructed a homeomorphism $h_k^\epsilon : \Phi_k^\epsilon \rightarrow \Phi_k^{(-1)^{k+1}\epsilon}$ with property (*). In particular, since Φ_k^ϵ is a π_1 -injective subsurface, h_k^ϵ is a π_1 -injective map. By Proposition 5.2.8, for $\epsilon = \pm 1$, we may choose a reduced homotopy \mathcal{H} of length $k + 1$ starting on the ϵ side such that \mathcal{H}_0 is the inclusion $\Phi_{k+1}^\epsilon \rightarrow \tilde{F}$. Write \mathcal{H} as the composition of a reduced homotopy \mathcal{H}' of length k and an essential basic homotopy \mathcal{H}'' . The induction hypothesis implies that the time-1 map of \mathcal{H}' is homotopic to the embedding $h_k^\epsilon|_{\Phi_{k+1}^\epsilon}$. By reversing the time variable of \mathcal{H}' and applying Proposition 5.2.8 we see that $h_k^\epsilon|_{\Phi_{k+1}^\epsilon}$ is homotopic to an embedding $h : \Phi_{k+1}^\epsilon \rightarrow \Phi_k^{(-1)^{k+1}\epsilon} \subset \Phi_1^{(-1)^{k+1}\epsilon}$. We define $\theta^\epsilon : \Phi_{k+1}^\epsilon \rightarrow \tilde{F}$ to be $\tau_{(-1)^{k+1}\epsilon} \circ h$. Note that h is π_1 -injective since Φ_{k+1}^ϵ is a π_1 -injective subsurface and since h_k^ϵ is a π_1 -injective map. Furthermore since $\tau_{(-1)^{k+1}\epsilon}$ is an involution of a π_1 -injective subsurface, it follows that θ^ϵ is a π_1 -injective map for $\epsilon = \pm 1$.

Since $\tau_{(-1)^{k+1}\epsilon}$ is an involution of $\Phi_1^{(-1)^{k+1}\epsilon}$ we know that θ^ϵ is the time-0 map of a standard basic essential homotopy whose time-1 map is $\tau_{(-1)^{k+1}\epsilon} \circ \theta^\epsilon = h$. Since h is in turn the time-0 map of a reduced homotopy of length k starting on the $(-1)^{k+1}\epsilon$ -side, it follows that θ^ϵ is the time-0 map of a length $k + 1$ homotopy starting on

the $(-1)^k\epsilon$ -side. It thus follows from Proposition 5.2.8 that the embedding θ^ϵ is homotopic into $\Phi_{k+1}^{(-1)^k\epsilon}$, i.e. that the surface $\theta^\epsilon(\Phi_{k+1}^\epsilon)$ is homotopic into $\Phi_{k+1}^{(-1)^k\epsilon}$.

Replacing ϵ by $(-1)^k\epsilon$ we find that $\theta^{(-1)^k\epsilon}(\Phi_{k+1}^{(-1)^k\epsilon})$ is homotopic into Φ_{k+1}^ϵ . By Lemma 4.1(1), $\theta^{(-1)^k\epsilon}(\Phi_{k+1}^{(-1)^k\epsilon})$ is isotopic to a subsurface of Φ_{k+1}^ϵ , which is π_1 -injective since $\theta^{(-1)^k\epsilon}$ is a π_1 -injective map. In particular $\Phi_{k+1}^{(-1)^k\epsilon}$ is homeomorphic to a π_1 -injective subsurface of Φ_{k+1}^ϵ , and hence to a π_1 -injective subsurface of $\theta^\epsilon(\Phi_{k+1}^\epsilon)$. Apply Lemma 4.1(2), taking $A = \theta^\epsilon(\Phi_{k+1}^\epsilon)$ and $B = \Phi_{k+1}^{(-1)^k\epsilon}$. It follows that A and B are isotopic and hence that θ^ϵ is isotopic in \tilde{F} to a homeomorphism $h_{k+1}^\epsilon : \Phi_{k+1}^\epsilon \rightarrow \Phi_{k+1}^{(-1)^k\epsilon}$.

We now show that h_{k+1}^ϵ has property (*). Let H be any reduced homotopy of length $k + 1$ starting on the ϵ side such that H_0 is a large map. By Proposition 5.2.8, H_0 is homotopic in \tilde{F} to a map $f : K \rightarrow \Phi_{k+1}^\epsilon$. Write H as the composition of a reduced homotopy H' of length k and a basic essential homotopy H'' . Since h_k^ϵ has property (*), the map $H''_0 = H'_1$ is homotopic in \tilde{F} to $h_k^\epsilon \circ f$, which is in turn homotopic to $h \circ f$. Then Lemma 5.2.7 implies that $H_1 = H''_1$ is homotopic to $\tau_{(-1)^k\epsilon} \circ h \circ f = \theta^\epsilon \circ f$, and hence to $h_{k+1}^\epsilon \circ f$. This establishes (*) and completes the inductive definition of the h_j^ϵ .

By Lemma 5.2.2, if \tilde{F} is given a consistent orientation, the involutions $\tau_{\pm 1}$ are orientation reversing embeddings of $\phi_{\pm 1}$ into \tilde{F} . It follows from the inductive construction that $h_k^{\pm 1}$ reverses orientation if k is odd and preserves orientation if k is even.

It remains to prove that a homeomorphism satisfying (*) is unique up to isotopy. Suppose that $h, h' : \Phi_k^\epsilon \rightarrow \Phi_k^{(-1)^{k+1}\epsilon}$ both satisfy (*). We apply Proposition 5.2.8, taking $K = \Phi_k^\epsilon$ and taking $f : \Phi_k^\epsilon \rightarrow \tilde{F}$ to be the inclusion. This gives a length- k reduced homotopy H starting on the ϵ side with time-0 map f . By property (*), h and h' are both homotopic in \tilde{F} to H_1 , and hence to each other. By Proposition 4.4, h and h' are homotopic as maps from $h, h' : \Phi_k^\epsilon$ to $\Phi_k^{(-1)^{k+1}\epsilon}$. It follows from Theorem 6.4 and Theorem A.4 of [E] that they are isotopic. \square

For the rest of this section, it will be understood that for each k and each ϵ we have fixed homeomorphisms $h_k^\epsilon : \Phi_k^\epsilon \rightarrow \Phi_k^{(-1)^{k+1}\epsilon}$ for which condition (*) of Proposition 5.3.1 holds.

Lemma 5.3.2. *Let $\epsilon \in \{\pm 1\}$ and $k \geq 0$ be given. Suppose that H is a reduced homotopy in (M, \tilde{F}) of length k with domain K which starts on the ϵ side. Suppose that $f = H_0$ is large and that $f(K) \subset \Phi_k^\epsilon$. Then H_1 is homotopic in \tilde{F} to $h_k^\epsilon \circ f$.*

Proof. By condition (*) of 5.3.1 there is a map $f' : K \rightarrow \Phi_k^\epsilon$ such that $H_0 = f$ is homotopic in \tilde{F} to f' and such that H_1 is homotopic in \tilde{F} to $h_k^\epsilon \circ f'$. It follows from Proposition 4.4 that f is homotopic to f' in Φ_k^ϵ . Thus $h_k^\epsilon \circ f$ is homotopic in \tilde{F} to $h_k^\epsilon \circ f'$, and hence to H_1 . \square

Proposition 5.3.3. *Let $\epsilon \in \{\pm 1\}$ and $k \geq 0$ be given. Then the homeomorphism $h_k^{(-1)^{k+1}\epsilon} : \Phi_k^{(-1)^{k+1}\epsilon} \rightarrow \Phi_k^\epsilon$ is isotopic to the inverse of $h_k^\epsilon : \Phi_k^\epsilon \rightarrow \Phi_k^{(-1)^{k+1}\epsilon}$.*

Proof. It follows from Proposition 5.2.8 that there is a reduced homotopy H of length k starting on the ϵ -side such that H_0 is the inclusion $\iota : \Phi_k^\epsilon \rightarrow \tilde{F}$. By Lemma

5.3.2 we have that H_1 is homotopic in \tilde{F} to h_k^ϵ . Applying Lemma 5.3.2 to the homotopy H' obtained by reversing the time variable of H , we see that $\iota = H_0 = H'_1$ is homotopic in \tilde{F} to the composition $h_k^{(-1)^{k+1}\epsilon} \circ H'_0$. Since $H'_0 = H_1 \sim h_k^\epsilon$ we have that $h_k^{(-1)^{k+1}\epsilon} \circ h_k^\epsilon$ is homotopic in \tilde{F} to the inclusion ι . It now follows from Proposition 4.4 that the self-homeomorphism $h_k^{(-1)^{k+1}\epsilon} \circ h_k^\epsilon$ of Φ_k^ϵ is homotopic to the identity in Φ_k^ϵ , and therefore isotopic to the identity by Theorem 6.4 and Theorem A.4 of [E]. \square

Proposition 5.3.4. *Let i and j be non-negative integers, and set $k = i + j$. Then for each $\epsilon \in \{\pm 1\}$, the map $h_i^\epsilon | \Phi_k^\epsilon$ is homotopic in \tilde{F} to an embedding $g_i^\epsilon: \Phi_i^\epsilon \rightarrow \Phi_j^{(-1)^i\epsilon}$ such that $h_j^{(-1)^i\epsilon} \circ g_i^\epsilon$ is homotopic in \tilde{F} to h_k^ϵ .*

Proof. Let H be a reduced homotopy of length k starting on the ϵ side such that H_0 is the inclusion $\Phi_k^\epsilon \rightarrow \tilde{F}$. Write H as the composition of a reduced homotopy H' of length i starting on the ϵ side and a reduced homotopy H'' of length j starting on the $(-1)^i\epsilon$ side. Applying Lemma 5.3.2, with the roles of k , H and f played respectively by i , H' and the inclusion map $\Phi_k^\epsilon \rightarrow \Phi_i^\epsilon$, we find that $H'_1 = H''_0$ is homotopic to the embedding $h_i^\epsilon | \Phi_k^\epsilon$.

On the other hand it follows from Proposition 5.3.1 that H''_0 is homotopic in \tilde{F} to a map $g_i^\epsilon: \Phi_i^\epsilon \rightarrow \Phi_j^{(-1)^i\epsilon}$. Since g_i^ϵ is homotopic to the embedding $h_i^\epsilon | \Phi_k^\epsilon$ it follows from part (1) of Lemma 4.1 that we may take g_i^ϵ to be an embedding. After modifying the homotopy H we may assume that $H'_1 = H''_0 = g_i^\epsilon$.

Applying Lemma 5.3.2 again, with j , H'' and g_i^ϵ playing the roles of k , H and f , we conclude that $H_1 = H''_1$ is homotopic in \tilde{F} to $h_j^{(-1)^i\epsilon} \circ g_i^\epsilon$.

Finally, applying Lemma 5.3.2 directly to the homotopy H , we see that H_1 is homotopic in \tilde{F} to h_k^ϵ . The conclusion of the proposition follows. \square

Proposition 5.3.5. *Let i and j be non-negative integers, and set $k = i + j$. Then for each $\epsilon \in \{\pm 1\}$ the subsurface $h_i^\epsilon(\Phi_k^\epsilon)$ is isotopic in \tilde{F} to $\Phi_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{L}} \Phi_j^{(-1)^i\epsilon}$.*

Proof. We have $h_i^\epsilon(\Phi_k^\epsilon) \subset h_i^\epsilon(\Phi_i^\epsilon) = \Phi_i^{(-1)^{i+1}\epsilon}$. On the other hand it follows from Proposition 5.3.4 that $h_i^\epsilon(\Phi_k^\epsilon)$ is isotopic in \tilde{F} to a subsurface of $\Phi_j^{(-1)^i\epsilon}$. Hence by Definition 4.3 the subsurface $h_i^\epsilon(\Phi_k^\epsilon)$ is isotopic to a subsurface of $\Phi_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{L}} \Phi_j^{(-1)^i\epsilon}$.

To complete the proof of the proposition, it now suffices by Lemma 4.1(2) to show that the large surface $\Phi_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{L}} \Phi_j^{(-1)^i\epsilon}$ is homeomorphic to a π_1 -injective subsurface of Φ_k^ϵ and hence of $h_i^\epsilon(\Phi_k^\epsilon)$. To prove this, note that $\Phi_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{L}} \Phi_j^{(-1)^i\epsilon}$ is isotopic to a subsurface A of $\Phi_i^{(-1)^{i+1}\epsilon}$. By Proposition 5.2.8 there is a reduced homotopy of length i whose time-0 map is the inclusion $A \rightarrow \tilde{F}$ and whose time-1 map is homotopic to $h_i^{(-1)^{i+1}\epsilon}: A \rightarrow \tilde{F}$. By reversing the time variable we obtain a homotopy H such that H_0 is homotopic in \tilde{F} to $h_i^{(-1)^{i+1}\epsilon}: A \rightarrow \tilde{F}$, and H_1 is the inclusion $A \rightarrow \tilde{F}$. Since A is isotopic to a subsurface of $\Phi_j^{(-1)^i\epsilon}$ there is also a reduced homotopy H'' of length j starting on the $(-1)^i\epsilon$ side whose time-0 map is the inclusion $A \rightarrow \tilde{F}$. The composition of H and H' is a reduced homotopy of length k starting on the ϵ side and having time-0 map homotopic to $h_i^{(-1)^{i+1}\epsilon} | A: A \rightarrow \tilde{F}$.

In particular, by Proposition 5.2.8 and Lemma 4.1, $h_i^{(-1)^{i+1}\epsilon}(A)$ is isotopic to a subsurface of Φ_k^ϵ . □

One of the main results of this section is that Φ_{2k+1}^ϵ admits a free involution. The proof of this fact is based on our next lemma.

Lemma 5.3.6. *The subsurface $h_k^\epsilon(\Phi_{2k+1}^\epsilon)$ is isotopic in \tilde{F} to a subsurface A of $\Phi_1^{(-1)^k\epsilon}$ with the property that $\tau_{(-1)^k\epsilon}(A)$ is isotopic to A in $\Phi_1^{(-1)^k\epsilon}$.*

Proof. By Proposition 5.3.5 we have that $h_k^\epsilon(\Phi_{2k+1}^\epsilon)$ is isotopic to $\Phi_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{L}} \Phi_{k+1}^{(-1)^k\epsilon}$. In particular, $h_k^\epsilon(\Phi_{2k+1}^\epsilon)$ is isotopic to a subsurface A of $\Phi_{k+1}^{(-1)^k\epsilon} \subset \Phi_1^{(-1)^k\epsilon}$. Since $\tau_{(-1)^k\epsilon}(A) = h_1^{(-1)^k\epsilon}(A) \subset h_1^{(-1)^k\epsilon}(\Phi_{k+1}^{(-1)^k\epsilon})$, Proposition 5.3.4 implies that $\tau_{(-1)^k\epsilon}(A)$ is isotopic to a subsurface of $\Phi_k^{(-1)^{k+1}\epsilon}$. On the other hand, since A is isotopic to a subsurface of $\Phi_k^{(-1)^{k+1}\epsilon}$ we know that the inclusion $A \rightarrow \tilde{F}$ is the time-0 map of a reduced homotopy H'' of length k starting on the $(-1)^{k+1}\epsilon$ side. Since $A \subset \Phi_1^{(-1)^{k+1}\epsilon}$, by reversing the time variable in the basic homotopy provided by Lemma 5.2.7 we obtain a basic homotopy H' whose time-0 map is the inclusion $\tau_{(-1)^k\epsilon}|_A$ and whose time-1 map is the inclusion $A \rightarrow \tilde{F}$. The composition of H' and H'' is a reduced homotopy of length $k + 1$ starting on the $(-1)^k\epsilon$ side whose time-0 map is $\tau_{(-1)^k\epsilon}|_A$. It follows from Proposition 5.2.8 that $\tau_{(-1)^k\epsilon}(A)$ is homotopic into $\Phi_{k+1}^{(-1)^k\epsilon}$. By Definition 4.3 we have that $\tau_{(-1)^k\epsilon}(A)$ is homotopic into $\Phi_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{L}} \Phi_{k+1}^{(-1)^k\epsilon}$ which in turn is isotopic to A in \tilde{F} . By Lemma 4.1(2) and Proposition 4.4, $\tau_{(-1)^k\epsilon}(A)$ is isotopic to A in $\Phi_1^{(-1)^k\epsilon}$. □

Proposition 5.3.7. *The surface $h_k^\epsilon(\Phi_{2k+1}^\epsilon)$ is isotopic in \tilde{F} to a subsurface of $\Phi_1^{(-1)^k\epsilon}$ which is invariant under the free involution $\tau_{(-1)^k\epsilon}$. In particular, Φ_{2k+1}^ϵ admits a free involution.*

Proof. This is an immediate consequence of Lemmas 5.3.6 and 4.5. □

Corollary 5.3.8. *For each odd integer $k > 0$, the Euler characteristic $\chi(\Phi_k^\epsilon)$ is even.* □

Proposition 5.3.9. *If Φ_k^ϵ and Φ_{k+2}^ϵ are isotopic in \tilde{F} for a given $k \geq 0$, then either $\Phi_k^\epsilon = \emptyset$ or \tilde{F} is a semi-fiber.*

Proof. In this proof all isotopies will be understood to take place in \tilde{F} unless specified otherwise.

First we claim that (1) Φ_k^ϵ is isotopic to Φ_m^ϵ for all $m \geq k$. Since $\Phi_{m-1}^\epsilon \supset \Phi_m^\epsilon \supset \Phi_{m+1}^\epsilon$, and Φ_m^ϵ is π_1 -injective, it suffices to consider the case where $m - k$ is even. The case $m = k + 2$ holds by hypothesis. Thus we need only show that if $m - k \geq 2$ is even and Φ_m^ϵ is isotopic to Φ_{m-2}^ϵ , then Φ_{m+2}^ϵ is isotopic to Φ_m^ϵ . By Proposition 5.3.5 we have that $h_2^\epsilon(\Phi_{m+2}^\epsilon)$ and $h_2^\epsilon(\Phi_m^\epsilon)$ are respectively isotopic to $\Phi_2^{-\epsilon} \wedge_{\mathcal{L}} \Phi_m^\epsilon$ and $\Phi_2^{-\epsilon} \wedge_{\mathcal{L}} \Phi_{m-2}^\epsilon$. These two surfaces are isotopic by the induction hypothesis. It follows that Φ_{m+2}^ϵ is isotopic to Φ_m^ϵ . Claim (1) follows.

Next we claim that (1') $\Phi_m^{-\epsilon}$ is isotopic to $\Phi_{k+1}^{-\epsilon}$ for all $m \geq k + 1$. By Proposition 5.3.5 we have for any $m > k + 1$ that $h_1^{-\epsilon}(\Phi_{m+1}^{-\epsilon})$ is isotopic to $\Phi_1^{-\epsilon} \wedge_{\mathcal{L}} \Phi_m^\epsilon$, while

$h_1^{-\epsilon}(\Phi_{k+1}^{-\epsilon})$ is isotopic to $\Phi_1^{-\epsilon} \wedge_{\mathcal{L}} \Phi_k^\epsilon$. These two surfaces are isotopic by (1), so (1') follows.

Next we claim that (2) $h_j^\epsilon(\Phi_{k+j}^\epsilon)$ is isotopic to Φ_k^ϵ for every even integer $j \geq 0$. By Proposition 5.3.5 we have that $h_j^\epsilon(\Phi_{k+j}^\epsilon)$ is isotopic to $\Phi_j^{-\epsilon} \wedge_{\mathcal{L}} \Phi_k^\epsilon$. In particular $h_j^\epsilon(\Phi_{k+j}^\epsilon)$ is isotopic to a subsurface of Φ_k^ϵ . Now since Φ_{k+j}^ϵ is isotopic to Φ_k^ϵ by (1), Lemma 4.1(2) implies that $h_j^\epsilon(\Phi_{k+j}^\epsilon)$ is isotopic to Φ_k^ϵ .

A similar argument using (1') shows that (2') $h_j^{-\epsilon}(\Phi_{k+1+j}^{-\epsilon})$ is isotopic to $\Phi_{k+1}^{-\epsilon}$ for all $j \geq 0$.

More generally we claim that (3) if j is even and $l \geq \max(k, j)$, then $h_j^\epsilon(\Phi_l^\epsilon)$ is isotopic to Φ_k^ϵ . To show this we first note that by (1), Φ_l^ϵ is isotopic in \tilde{F} to Φ_{k+j}^ϵ and so by Proposition 4.4 Φ_l^ϵ is isotopic to Φ_{k+j}^ϵ in Φ_j^ϵ . Hence $h_j^\epsilon(\Phi_l^\epsilon)$ is isotopic in \tilde{F} to $h_j^\epsilon(\Phi_{k+j}^\epsilon)$, which we have already shown is isotopic to Φ_k^ϵ .

In the same way, using (2'), we see that (3') if j is even and $l \geq \max(k + 1, j)$, then $h_j^{-\epsilon}(\Phi_l^{-\epsilon})$ is isotopic to $\Phi_{k+1}^{-\epsilon}$.

We claim that (4) for all $j \geq 0$ the surface Φ_k^ϵ is isotopic to a subsurface of $\Phi_j^{-\epsilon}$ and that (4') $\Phi_{k+1}^{-\epsilon}$ is isotopic to a subsurface of Φ_j^ϵ . Since the $\Phi_j^{\pm\epsilon}$ are nested up to isotopy, we need only prove this for even j . By (2) we have that $h_j^\epsilon(\Phi_{k+j}^\epsilon)$ is isotopic to Φ_k^ϵ . Lemma 5.3.5 implies that $h_j^\epsilon(\Phi_{k+j}^\epsilon)$ is isotopic to $\Phi_j^{-\epsilon} \wedge_{\mathcal{L}} \Phi_k^\epsilon$. The fact that Φ_k^ϵ is isotopic to $\Phi_j^{-\epsilon} \wedge_{\mathcal{L}} \Phi_k^\epsilon$ implies that Φ_k^ϵ is isotopic to a subsurface of $\Phi_j^{-\epsilon}$, as asserted by (4). A similar argument using (2') proves (4').

We next claim that (5) if j is odd, then $h_j^\epsilon(\Phi_k^\epsilon)$ is isotopic to $\Phi_{k+1}^{-\epsilon}$ and (5') if j is odd, then $h_j^{-\epsilon}(\Phi_{k+1}^{-\epsilon})$ is isotopic to Φ_k^ϵ . First by (1) we have that $h_j^\epsilon(\Phi_k^\epsilon)$ is isotopic to $h_j^\epsilon(\Phi_{k+1+j}^\epsilon)$ which, by Proposition 5.3.5, is isotopic to $\Phi_j^\epsilon \wedge_{\mathcal{L}} \Phi_{k+1}^{-\epsilon}$. Claim (4') implies that this essential intersection is isotopic to $\Phi_{k+1}^{-\epsilon}$. The proof of (5') is similar but uses (1') and (4) in place of (1) and (4').

Now fix an even integer $m > k$. By Proposition 5.3.7 we have that $h_m^\epsilon(\Phi_{2m+1}^\epsilon)$ is isotopic to a τ_ϵ -invariant subsurface B_ϵ of Φ_1^ϵ . By (3) we have that Φ_k^ϵ is isotopic to $h_m^\epsilon(\Phi_{2m+1}^\epsilon)$ and hence to B_ϵ . Similarly, using (3'), we see that $\Phi_{k+1}^{-\epsilon}$ is isotopic to a $\tau_{-\epsilon}$ -invariant subsurface $B_{-\epsilon}$ of $\Phi_1^{-\epsilon}$. Moreover, since $\tau_\epsilon = h_1^\epsilon$, we have that Φ_k^ϵ is isotopic to $\tau_\epsilon(\Phi_k^\epsilon) = h_1^\epsilon(\Phi_k^\epsilon)$ which in turn is isotopic to $\Phi_{k+1}^{-\epsilon}$ by (5).

Thus we have defined surfaces $B_\epsilon \subset \Phi_1^\epsilon$ and $B_{-\epsilon} \subset \Phi_1^{-\epsilon}$ which are invariant under τ_ϵ and $\tau_{-\epsilon}$, respectively, and are both isotopic to Φ_k^ϵ . By Subsection 5.2.1 it follows that there exist I -pairs $(E_\epsilon, B_\epsilon) \subset (M_{\tilde{F}}^\epsilon, \tilde{F})$ whose associated ∂I -subbundles are both isotopic to the subsurface Φ_k^ϵ of \tilde{F} . After modifying these I -pairs by isotopies we obtain a semi-fibered submanifold $N = E_+ \cup E_-$ contained in M whose semi-fiber B is isotopic to the large subsurface Φ_k^ϵ of \tilde{F} . We may take N to be contained in $\text{int } M$.

We are now ready to show that if Φ_k^ϵ is non-empty, then \tilde{F} is a semi-fiber. First we argue that each component of ∂N is a π_1 -injective torus in M . Since N has a large semi-fiber, it is clear that each component of ∂N is π_1 -injective in N . It therefore suffices to show that N is π_1 -injective in M . A homotopically non-trivial loop in N which is contained in B is homotopically non-trivial in M because B is π_1 -injective in \tilde{F} . Now consider a loop α in N which is not homotopic to a loop in B . After modifying α by a free homotopy we may take it to be a composition of paths $\alpha_1, \dots, \alpha_{2n}$ for some $n > 0$ such that each α_i is a path in $E_{(-1)^i}$ which has its

endpoints in B and is not fixed-endpoint homotopic in N to a path in B . The map of pairs $\alpha_i: (I, \partial I) \rightarrow (E_{(-1)^i}, B_{(-1)^i})$ must be homotopic to a homeomorphism onto a fiber. Since the I -bundles E_+ and E_- are essential in $M_{\tilde{F}}$ the path α_i is not fixed-endpoint homotopic in M to a path in \tilde{F} . It follows that N is π_1 -injective in M .

Since M is a simple knot manifold, every component of ∂N is boundary parallel. Furthermore, since N has a large semi-fiber, it cannot be homeomorphic to $S^1 \times S^1 \times I$. Thus $C = \overline{M - N}$ is a collar on ∂M . The surface $A = \tilde{F} - B$ is a π_1 -injective subsurface of \tilde{F} without disk component which is properly embedded in C . In particular A is π_1 -injective in C and hence each component of A is an annulus. Furthermore, by [Wa], either A has a boundary parallel component or A is vertical in the sense that it is mapped by some homeomorphism of C onto $S^1 \times S^1 \times I$ which maps A to $X \times S^1 \times I$, where X is a finite subset of S^1 . Assume that A has a boundary parallel component A_0 . Then $A_0 \subset \tilde{F}$ is isotopic relative to ∂A_0 to an annulus A'_0 in ∂N . But the torus ∂N is a union of essential annuli which are components of the frontiers of the I -pairs (E_ϵ, B_ϵ) . Thus the inclusion map of the annulus A'_0 can be regarded as a reduced homotopy between the inclusion maps of the two boundary components of A_0 . In particular, A'_0 is not homotopic into \tilde{F} . This is a contradiction, hence A is vertical. It follows easily that the semi-fibration of N can be extended over C to obtain a semi-fibration of M with semi-fiber \tilde{F} . \square

5.4. Bounding the length of a reduced homotopy.

Theorem 5.4.1. *Let F be a connected essential surface in a simple knot manifold M . Suppose that F is not a semi-fiber. Let g and m denote respectively the genus and number of boundary components of F . Then any reduced homotopy in the pair (M, F) having a large time-0 map has length at most $8g + 3m - 8$.*

For the proof of this theorem we will need the following construction.

5.4.2. Suppose that F is any connected, non-separating, essential surface in M , and let \tilde{F} denote the boundary of a regular neighborhood N of F . It is clear that \tilde{F} has a unique transverse orientation such that \tilde{F} is a splitting surface and $M_{(\tilde{F})^+} = N$. We shall call \tilde{F} , equipped with this transverse orientation, a *splitting surface associated to F* .

If F is any connected, separating, essential surface in M , we refer to F itself, equipped with either transverse orientation, as a *splitting surface associated to F* .

5.4.3.

Proof of Theorem 5.4.1. Let \tilde{F} be a splitting surface associated to F . Since F is not a semi-fiber, it is clear that \tilde{F} is not a semi-fiber. We define the subsurfaces Φ_k^ϵ for $k \geq 0$ and $\epsilon \in \{\pm 1\}$ as in Subsection 5.2. Let H be a reduced homotopy of length l in the pair (M, F) starting on the ϵ side. Let us set $\tilde{l} = l$ if F separates M , and $\tilde{l} = 2l$ if F does not separate M . Then the homotopy H determines a reduced homotopy \tilde{H} of length \tilde{l} in the pair (M, \tilde{F}) such that \tilde{H}_0 is large. This is obvious if F separates; if F does not separate, it follows from the fact that the two components of \tilde{F} cobound a product. Let \tilde{g} and \tilde{m} denote, respectively, the total genus and number of boundary components of \tilde{F} . We have $\tilde{g} = g$ and $\tilde{m} = m$ in the separating case, and $\tilde{g} = 2g$ and $\tilde{m} = 2m$ in the non-separating case. Hence

it suffices to show that the length \tilde{l} of \tilde{H} is at most $8\tilde{g} + 3\tilde{m} - 8$ in the separating case, and is at most $8\tilde{g} + 3\tilde{m} - 16$ in the non-separating case.

Set $n = \lceil \frac{\tilde{l}+1}{2} \rceil$, and consider the subsurfaces

$$\Phi_1^\epsilon \supset \Phi_3^\epsilon \supset \dots \supset \Phi_{2n-1}^\epsilon \supset \Phi_{2n+1}^\epsilon$$

of \tilde{F} . Since the reduced homotopy \tilde{H} has length $\tilde{l} \geq 2n - 1$, it follows from Proposition 5.2.8 that $\Phi_{2n-1}^\epsilon \neq \emptyset$. Since \tilde{F} is not a semi-fiber, it now follows from Proposition 5.3.9 that Φ_{2i-1}^ϵ is not a regular neighborhood of Φ_{2i+1}^ϵ for $i = 1, \dots, n$. Furthermore, by Corollary 5.3.8, each of these surfaces has even Euler characteristic. Using these facts, we will show that $n \leq 4\tilde{g} + 3\tilde{m}/2 - 4$ in the separating case, and that $n \leq 4\tilde{g} + 3\tilde{m}/2 - 8$ in the non-separating case; this implies the desired conclusion, since $\tilde{l} \leq 2n$.

If A is any large subsurface of \tilde{F} , then we will set $c(A) = \text{genus}(A) - 3\chi(A)/2 - |A|$. Note that $c(A)$ is always non-negative, and is an integer if A has even Euler characteristic. We have $c(\tilde{F}) = 4\tilde{g} + 3\tilde{m}/2 - 4$ in the separating case, and $c(\tilde{F}) = 4\tilde{g} + 3\tilde{m}/2 - 8$ in the non-separating case. Hence it suffices to show that $n \leq c(\tilde{F})$. Thus the proof reduces to the following general claim: if A and B are large subsurfaces of \tilde{F} , each of which has even Euler characteristic, and if B is contained in the interior of A , then $c(B) < c(A)$ unless A is a regular neighborhood of B .

To prove the claim, it suffices to show that if A_0 is a component of A , and if we set $B_0 = B \cap A_0$, then $c(B_0) < c(A_0)$ unless A_0 is a regular neighborhood of B_0 . Note that we have $\text{genus}(B_0) \leq \text{genus}(A_0)$ and, since A and B are large, $\chi(B_0) \geq \chi(A_0)$. Thus we need only consider the two cases where $B_0 = \emptyset$ and where B_0 is connected. The case $B_0 = \emptyset$ is easy because $c(A) > 0$ for any non-empty large subsurface A . For the case where B_0 is connected we may assume that $\text{genus}(B_0) = \text{genus}(A_0)$ and $\chi(B_0) = \chi(A_0)$, and we must show that A_0 is a regular neighborhood of B_0 . Since A and B are large, no component of $\overline{A_0 - B_0}$ is a disk. Thus the condition $\chi(B_0) = \chi(A_0)$ implies that each component of $\overline{A_0 - B_0}$ is an annulus. None of these annuli can separate A_0 since B_0 is connected. On the other hand, since $\text{genus}(B_0) = \text{genus}(A_0)$ there cannot exist a simple closed curve in A_0 which has non-zero intersection number with a core curve of an annulus component of $\overline{A_0 - B_0}$. It follows that each component of $\overline{A_0 - B_0}$ is a collar on a boundary component of A_0 and hence that A_0 is a regular neighborhood of B_0 . This completes the proof of the claim, and of the theorem. \square

6. BOUNDARY SLOPES OF ESSENTIAL SURFACES AND SINGULAR SURFACES

Most of the work in this section is devoted to proving Theorem 6.2.1, which is a refinement of Theorem 5.4.1 and gives a bound on the length of a reduced homotopy whose time-0 map is an essential path. Combining Theorem 6.2.1 with the results in Section 3 we obtain a proof of Theorem 6.2.2 and its Corollaries 6.2.3, 6.2.4 and 6.2.5. These results give bounds on $\Delta(\alpha, \beta)$, where β is a boundary slope and α is either another boundary slope, a very small filling slope or a Seifert-fibered filling slope.

We will need the following definition in this section.

Definition 6.0.1. Let \tilde{F} be a splitting surface in a simple knot manifold M . We say that \tilde{F} admits a long rectangle if there exists a reduced homotopy $H : I \times I \rightarrow$

M in the pair (M, \tilde{F}) having length at least $|\partial\tilde{F}|$ in the pair (M, \tilde{F}) such that $H_t(\partial I) \subset \partial M$ for all $t \in I$ and H_0 is an essential path.

6.1. Reduced homotopies and outer subsurfaces.

6.1.1. Hypotheses. Throughout Subsection 6.1 we will assume that M is a simple knot manifold and that \tilde{F} is a splitting surface in M which admits a long rectangle.

We will define $\Phi_{\pm 1}$ and $\tau_{\pm 1}$ as in Subsection 5.2. For every $k \geq 0$ we fix subsurfaces $\Phi_k^{\pm 1}$ of \tilde{F} for which the conclusions of Proposition 5.2.8 hold and homeomorphisms $h_k^{\pm 1}$ for which the conclusions of Proposition 5.3.1 hold.

Lemma 6.1.2. *For each $\epsilon \in \{\pm 1\}$, every component of $\partial\tilde{F}$ is isotopic in \tilde{F} to a unique boundary component of Φ_1^ϵ . Furthermore, if c and c' are components of $\partial\tilde{F}$ which cobound an annulus component of $M_{\tilde{F}}^\epsilon \cap \partial M$, then the boundary components of Φ_1^ϵ which are isotopic to c and c' are interchanged by τ_ϵ .*

Proof. Set $m = |\partial\tilde{F}|$. The existence of a long rectangle means that there is a reduced homotopy H of length m , such that $H_t(\partial I) \subset \partial M$ for all $t \in I$ and $f = H_0$ is an essential path. As in Subsection 3.4 we extend f to an admissible pair of glasses $\hat{f} : \Gamma \rightarrow \tilde{F}$, and extend H to a length- m reduced homotopy \hat{H} with $\hat{H}_0 = \hat{f}$. By construction the homotopy \hat{H} has the property that for each of the ‘‘rims’’ \bar{l}_i , we have $\hat{H}_t(\bar{l}_i) \subset \partial M$ for all $t \in [0, 1]$.

Write \hat{H} as a composition of essential basic homotopies $\hat{H}^1, \dots, \hat{H}^m$. Because the \hat{H}^i are essential homotopies, \hat{H}^i maps $\bar{l}_1 \times I$ to an annulus component A_i of $M_{\tilde{F}} \cap \partial M$ and maps the two components of $\bar{l}_1 \times \partial I$ to distinct components of ∂A_i . Since \hat{H} is reduced, the annuli A_i and A_{i+1} are on opposite sides of their common boundary component $\hat{H}_1^i(\bar{l}_1) = \hat{H}_0^{i+1}(\bar{l}_1)$ for each $i = 1, \dots, m - 1$. Since m is the number of components of $\tilde{F} \cap \partial M$, it follows that the annuli A_i are distinct and that every annulus component of $M_{\tilde{F}} \cap \partial M$ appears as one of the A_i . If we set $A_0 = A_m$, then for each component c of $\partial\tilde{F}$ there is some i with $0 \leq i < m$ such that c is the common boundary curve of the two annuli A_i and A_{i+1} , one of which is contained in $M_{\tilde{F}}^+$ and the other in $M_{\tilde{F}}^-$.

To prove the first assertion of the lemma let c be a component of $\partial\tilde{F}$ and let $\epsilon \in \{\pm 1\}$ be given. The curve c is a boundary component of some annulus $A_j \subset M_{\tilde{F}}^\epsilon \cap \partial M$. Lemma 5.2.6 implies that \hat{H}_0^j is homotopic to a map from Γ to Φ_1^ϵ . In particular c is homotopic in \tilde{F} to a (singular) curve in Φ_1^ϵ . Since c is a boundary component of \tilde{F} , it follows that c is homotopic to a boundary component of Φ_1^ϵ .

To prove the second assertion, suppose that c and c' are boundary curves of \tilde{F} which cobound an annulus component A of $M_{\tilde{F}}^\epsilon \cap \partial M$. Then we have $A = A_j$ for some j . Let γ be the boundary component of Φ_1^ϵ which is homotopic to c . Lemma 5.2.6 implies that \hat{H}_0^j is homotopic to a map $g : \Gamma \rightarrow \Phi_1^\epsilon$ such that $g(\bar{l}_1) = \gamma$. Applying Lemma 5.2.7 to the homotopy H^j , with g in place of f and Γ in place of K , we conclude that $c' = \hat{H}_1^j(\bar{l}_1)$ is homotopic in \tilde{F} to $\tau_\epsilon(\gamma)$. The assertion follows immediately. \square

Lemma 6.1.3. *If $\epsilon \in \{\pm 1\}$ and if γ is a simple closed curve in Φ_k^ϵ which is isotopic in \tilde{F} to a component of $\partial\tilde{F}$, then $h_k^\epsilon(\gamma)$ is also isotopic to some component of $\partial\tilde{F}$.*

Proof. For $k = 0$ the assertion is trivial. To prove the lemma for $k = 1$, we may assume that γ is a component of $\partial\Phi_k^\epsilon$. Let c denote the component of $\partial\tilde{F}$ which is

isotopic in \tilde{F} to γ , and let A denote the annulus component of $M_{\tilde{F}}^\epsilon \cap \partial M$ having c as a boundary curve. If c' denotes the other boundary curve of A , then it follows from Lemma 6.1.2 that c' is isotopic in \tilde{F} to a boundary component γ' of Φ_1^ϵ and that $h_1^\epsilon(\gamma) = \tau_\epsilon(\gamma) = \gamma'$. This proves the assertion in this case.

Now assume that $k > 1$ and that the assertion holds with k replaced by $k - 1$, both for $\epsilon = 1$ and $\epsilon = -1$. Suppose we are given $\epsilon \in \{\pm 1\}$ and a simple closed curve $\gamma \subset \Phi_k^\epsilon \subset \Phi_{k-1}^\epsilon$ which is isotopic in \tilde{F} to a component of $\partial \tilde{F}$. We will apply Proposition 5.3.4 with $i = k - 1$ and $j = 1$. According to Proposition 5.3.4, the map $h_{k-1}^\epsilon|_{\Phi_k^\epsilon}$ is homotopic to a map $g_{k-1}^\epsilon : \Phi_{k-1}^\epsilon \rightarrow \Phi_1^{-\epsilon}$ such that h_k^ϵ is homotopic to $h_1^{(-1)^{k-1}\epsilon} \circ g_{k-1}^\epsilon$. Now $g_{k-1}^\epsilon(\gamma)$ is homotopic to $h_{k-1}^\epsilon(\gamma)$ which, by the induction hypothesis, is homotopic to some component of $\partial \tilde{F}$. By the case $k = 1$ of the proposition we know that $h_1^{(-1)^{k-1}\epsilon}(h_{k-1}^\epsilon(\gamma))$ is homotopic to a component of $\partial \tilde{F}$. Since h_k^ϵ is homotopic to $h_1^{(-1)^{k-1}\epsilon} \circ g_{k-1}^\epsilon$ this shows that $h_k^\epsilon(\gamma)$ is homotopic to a component of $\partial \tilde{F}$. \square

Recall from Subsection 4.6 that if A is a subsurface of a compact orientable surface S , then the outer part of A is denoted \dot{A} .

Lemma 6.1.4. *For either $\epsilon \in \{\pm 1\}$ and for any large subsurface A of Φ_k^ϵ , the outer part of $h_k^\epsilon(A)$ is $h_k^\epsilon(\dot{A})$.*

Proof. Set $B = h_k^\epsilon(A)$. It follows from Lemma 6.1.3 that $h_k^\epsilon(\dot{A}) \subset \dot{B}$. Let $g : \Phi_k^{(-1)^{k+1}\epsilon} \rightarrow \Phi_k^\epsilon$ denote the inverse of h_k^ϵ , so that $g(B) = A$. According to Proposition 5.3.3 the map g is isotopic to $h_k^{(-1)^{k+1}\epsilon}$ as a map from $\Phi_k^{(-1)^{k+1}\epsilon}$ to Φ_k^ϵ . It therefore follows from Lemma 6.1.2 that $g(\dot{B}) \subset \dot{A}$, i.e. that $\dot{B} \subset h_k^\epsilon(\dot{A})$. \square

6.1.5. We now consider the outer parts of the surfaces Φ_k^ϵ which, according to our conventions, are denoted $\dot{\Phi}_k^\epsilon$. Note that since

$$\tilde{F} = \Phi_0^\epsilon \supset \Phi_1^\epsilon \supset \Phi_2^\epsilon \supset \dots$$

for $\epsilon \in \{\pm 1\}$, it follows from Subsection 4.6 that

$$\tilde{F} = \dot{\Phi}_0^\epsilon \supset \dot{\Phi}_1^\epsilon \supset \dot{\Phi}_2^\epsilon \supset \dots$$

It follows from Lemma 6.1.4 that h_k^ϵ restricts to a homeomorphism from $\dot{\Phi}_k^\epsilon$ to $\dot{\Phi}_k^{(-1)^{k+1}\epsilon}$. This homeomorphism will be denoted by \dot{h}_k^ϵ . In particular the involution $\tau_\epsilon = h_1^\epsilon$ of Φ_1^ϵ restricts to an involution $\dot{\tau}_\epsilon = \dot{h}_1^\epsilon$ of $\dot{\Phi}_1^\epsilon$. It also follows from Lemma 6.1.4 that if A is any large subsurface of Φ_k^ϵ , then $\dot{h}_k^\epsilon(\dot{A})$ is the outer part of $h_k^\epsilon(A)$. Note also that, according to Proposition 5.3.1, if \tilde{F} is given a consistent orientation, $\dot{h}_k^\epsilon : \dot{\Phi}_k^\epsilon \rightarrow \tilde{F}$ is orientation reversing if k is odd and orientation preserving if k is even.

The following six results, 6.1.6–6.1.11, are analogues of 5.3.4–5.3.9. (Of course these results, unlike their counterparts in Section 4, depend on the hypothesis stated at the beginning of the section that \tilde{F} admits a long rectangle.)

Proposition 6.1.6. *Let i and j be non-negative integers, and set $k = i + j$. Then for each $\epsilon \in \{\pm 1\}$, the map $\dot{h}_i^\epsilon|_{\dot{\Phi}_k^\epsilon}$ is homotopic in \tilde{F} to an embedding $\dot{g}_i^\epsilon : \dot{\Phi}_k^\epsilon \rightarrow \dot{\Phi}_j^{(-1)^i\epsilon}$ such that $\dot{h}_j^{(-1)^i\epsilon} \circ \dot{g}_i^\epsilon$ is homotopic in \tilde{F} to \dot{h}_k^ϵ .*

Proof. By Proposition 5.3.4 we have that $h_i^\epsilon | \Phi_k^\epsilon$ is homotopic in \tilde{F} to an embedding $g_i^\epsilon: \Phi_k^\epsilon \rightarrow \Phi_j^{(-1)^i \epsilon}$ such that $h_j^{(-1)^i \epsilon} \circ g_i^\epsilon$ is homotopic in \tilde{F} to h_k^ϵ . Set $\dot{g}_i^\epsilon = g_i^\epsilon | \dot{\Phi}_k^\epsilon$, and set $A = \dot{g}_i^\epsilon(\dot{\Phi}_k^\epsilon)$. To complete the proof it suffices to show that $A \subset \dot{\Phi}_j^{(-1)^i \epsilon}$.

Since $h_j^{(-1)^i \epsilon} \circ g_i^\epsilon$ is homotopic to h_k^ϵ , the subsurface $h_j^{(-1)^i \epsilon}(A)$ is homotopic into $h_k^\epsilon(\dot{\Phi}_k^\epsilon)$ which, by Subsection 6.1.5, is equal to $\dot{\Phi}_k^{(-1)^{k+1} \epsilon}$. In particular $h_j^{(-1)^i \epsilon}(A)$ is homotopic into $\dot{\Phi}_j^{(-1)^{k+1} \epsilon}$. Since $h_j^{(-1)^i \epsilon}(A)$ is a large subsurface of $h_j^{(-1)^i \epsilon}(\Phi_j^{(-1)^i \epsilon}) = \Phi_j^{(-1)^{k+1} \epsilon}$, and since $\dot{\Phi}_j^{(-1)^{k+1} \epsilon}$ is a union of components of $\Phi_j^{(-1)^{k+1} \epsilon}$, it follows that $h_j^{(-1)^i \epsilon}(A)$ is contained in $\dot{\Phi}_j^{(-1)^{k+1} \epsilon}$, which by Subsection 6.1.5 is equal to $h_j^{(-1)^i \epsilon}(\dot{\Phi}_j^{(-1)^i \epsilon})$. We therefore have $A \subset \dot{\Phi}_j^{(-1)^i \epsilon}$, as required. \square

Proposition 6.1.7. *Let i and j be non-negative integers, and set $k = i + j$. Then for each $\epsilon \in \{\pm 1\}$ the subsurface $\dot{h}_i^\epsilon(\dot{\Phi}_k^\epsilon)$ is isotopic in \tilde{F} to $\dot{\Phi}_i^{(-1)^{i+1} \epsilon} \wedge_{\mathcal{L}} \dot{\Phi}_j^{(-1)^i \epsilon}$.*

Proof. We may assume by Proposition 5.3.5 that $h_i^\epsilon(\Phi_k^\epsilon) = \Phi_i^{(-1)^{i+1} \epsilon} \wedge_{\mathcal{L}} \Phi_j^{(-1)^i \epsilon}$. It follows from Subsection 6.1.5 that $\dot{h}_i^\epsilon(\dot{\Phi}_k^\epsilon)$ is the outer part of $h_i^\epsilon(\Phi_k^\epsilon)$ and is therefore equal to the surface $\Phi_i^{(-1)^{i+1} \epsilon} \wedge_{\mathcal{L}} \Phi_j^{(-1)^i \epsilon}$. By Lemma 4.7 this surface is isotopic in \tilde{F} to $\dot{\Phi}_i^{(-1)^{i+1} \epsilon} \wedge_{\mathcal{L}} \dot{\Phi}_j^{(-1)^i \epsilon}$. \square

Lemma 6.1.8. *For any non-negative integer k and for each $\epsilon \in \{\pm 1\}$ the subsurface $\dot{h}_k^\epsilon(\dot{\Phi}_{2k+1}^\epsilon)$ is isotopic in \tilde{F} to a subsurface A of $\dot{\Phi}_1^{(-1)^k \epsilon}$ with the property that $\dot{\tau}_{(-1)^k \epsilon}(A)$ is a subsurface of $\dot{\Phi}_1^{(-1)^k \epsilon}$ which is isotopic to A in $\dot{\Phi}_1^{(-1)^k \epsilon}$.*

Proof. By Lemma 5.3.6 we know that $h_k^\epsilon(\Phi_{2k+1}^\epsilon)$ is isotopic in \tilde{F} to a subsurface A_0 of $\Phi_1^{(-1)^k \epsilon}$ with the property that $\tau_{(-1)^k \epsilon}(A_0)$ is isotopic to A_0 in $\Phi_1^{(-1)^k \epsilon}$. It follows from Subsection 6.1.5 that $\dot{h}_k^\epsilon(\dot{\Phi}_{2k+1}^\epsilon)$ is isotopic in \tilde{F} to \dot{A}_0 . It also follows from Subsection 6.1.5 that $\dot{\tau}_{(-1)^k \epsilon}(\dot{A}_0) = h_1^{(-1)^k \epsilon}(\dot{A}_0) = \dot{h}_1^{(-1)^k \epsilon}(\dot{A}_0)$ is equal to the outer part of $h_1^{(-1)^k \epsilon}(A_0) = \dot{\tau}_{(-1)^k \epsilon}(A_0)$. Since $\dot{\tau}_{(-1)^k \epsilon}(A_0)$ is isotopic to A_0 it follows that $\dot{\tau}_{(-1)^k \epsilon}(\dot{A}_0)$ is isotopic in \tilde{F} to \dot{A}_0 . Since the subsurfaces $\dot{\tau}_{(-1)^k \epsilon}(\dot{A}_0)$ and \dot{A}_0 of $\dot{\Phi}_1^{(-1)^k \epsilon}$ are isotopic in \tilde{F} , it follows from Lemma 4.1 that they are isotopic in $\dot{\Phi}_1^{(-1)^k \epsilon}$. Thus we may take $A = \dot{A}_0$. \square

Proposition 6.1.9. *For any non-negative integer k and for each $\epsilon \in \{\pm 1\}$ the surface $\dot{h}_k^\epsilon(\dot{\Phi}_{2k+1}^\epsilon)$ is isotopic in \tilde{F} to a subsurface of $\dot{\Phi}_1^{(-1)^k \epsilon}$ which is invariant under the free involution $\dot{\tau}_{(-1)^k \epsilon}$. In particular, $\dot{\Phi}_{2k+1}^\epsilon$ admits a free involution.*

Proof. This is an immediate consequence of Lemmas 6.1.8 and 4.5. \square

Corollary 6.1.10. *For each $\epsilon \in \{\pm 1\}$ and each odd integer $k > 0$, the Euler characteristic $\chi(\dot{\Phi}_k^\epsilon)$ is even. \square*

Proposition 6.1.11. *Let k be a non-negative integer and let $\epsilon \in \{\pm 1\}$ be given. If $\dot{\Phi}_k^\epsilon$ and $\dot{\Phi}_{k+2}^\epsilon$ are isotopic in \tilde{F} , then either $\dot{\Phi}_k^\epsilon = \emptyset$ or \tilde{F} is a semi-fiber.*

Proof. This is formally identical with the proof of Proposition 5.3.9. All occurrences of Φ , h , τ and $\wedge_{\mathcal{L}}$ are replaced by $\dot{\Phi}$, \dot{h} , $\dot{\tau}$ and $\dot{\wedge}_{\mathcal{L}}$, respectively. References to

Propositions 5.3.5 and 5.3.7 are replaced by references to Proposition 6.1.7 and 6.1.9. □

6.2. The distance bounds. The next result is a strengthened version of Theorem 5.4.1 that applies to a reduced homotopy whose time-0 map is an essential path.

Theorem 6.2.1. *Let F be a connected essential surface in a simple knot manifold M . Suppose that F is not a semi-fiber. Set $g = \text{genus}(F)$ and $m = |\partial F|$. Let H be any reduced homotopy in the pair (M, F) such that H_0 is an essential path in F and $H_t(\partial I) \subset \partial M$ for each $t \in I$. Then the length of H is at most $4g + 3m - 4$.*

Proof. The proof will be similar to that of Theorem 5.4.1. Let \tilde{F} be a splitting surface associated to F . Since F is not a semi-fiber, it follows that \tilde{F} is not a semi-fiber.

Let l denote the length of H . We may assume $l > m$. Set $\tilde{l} = l$ if F is separating and $\tilde{l} = 2l$ if F is non-separating. As in the proof of Theorem 5.4.1, the homotopy H determines a homotopy \tilde{H} of length \tilde{l} in the pair (M, \tilde{F}) such that \tilde{H}_0 is an essential path. Let \tilde{g} and \tilde{m} denote, respectively, the total genus and number of boundary components of \tilde{F} . We have $\tilde{m} = m$ and $\tilde{g} = g$ in the separating case and $\tilde{m} = 2m, \tilde{g} = 2g$ in the non-separating case. It therefore suffices to prove that $\tilde{l} \leq 4\tilde{g} + 3\tilde{m} - 4$ if F is separating and $\tilde{l} \leq 4\tilde{g} + 3\tilde{m} - 8$ if F is non-separating.

Since $l > m$ we also have $\tilde{l} > \tilde{m}$. In particular this means that \tilde{F} admits a long rectangle and hence that the hypotheses stated in Subsection 6.1.1 hold. We define the subsurfaces $\Phi_k^{\pm 1}$ and $\dot{\Phi}_k^{\pm 1}$ for $k \geq 0$ as in Subsections 6.1.1 and 6.1.5.

Let us say that a subsurface A of \tilde{F} is *allowable* if A is a large subsurface with even Euler characteristic and if A is an outer subsurface (see Subsection 4.6). If A is any large subsurface of \tilde{F} , let $\nu(A)$ denote the number of components of $\partial\tilde{F}$ which are homotopic into A . Note that $\nu(A) > 0$ for any non-empty allowable subsurface A . We set

$$c(A) = \text{genus}(A) - \frac{\chi(A)}{2} - |A| + \nu(A) = 2 \text{genus}(A) + \frac{|\partial A|}{2} - 2|A| + \nu(A).$$

Note that $c(A)$ is non-negative and integer-valued if A is allowable. Moreover, $c(A) > 0$ if A is non-empty and allowable.

Set $n = \lceil \frac{\tilde{l}+1}{2} \rceil$ and define $\epsilon \in \{\pm 1\}$ by the condition that the homotopy \tilde{H} starts on the ϵ -side. Consider the subsurfaces

$$\dot{\Phi}_1^\epsilon \supset \dot{\Phi}_3^\epsilon \supset \dots \supset \dot{\Phi}_{2n-1}^\epsilon \supset \dot{\Phi}_{2n+1}^\epsilon.$$

Since the hypotheses stated in Subsection 6.1.1 hold, Corollary 6.1.10 implies that each of these surfaces has even Euler characteristic, and, in view of the definition of the $\dot{\Phi}_k^\epsilon$, it follows that each of these surfaces is allowable. On the other hand, since the reduced homotopy \tilde{H} has length $\tilde{l} \geq 2n - 1$, it follows from Subsection 3.4 and Proposition 5.2.8 that there is an admissible pair of glasses $\gamma : \Gamma \rightarrow \tilde{F}$ which is homotopic in \tilde{F} to a map from Γ to Φ_{2n-1}^ϵ . In particular there is a map $\alpha : S^1 \rightarrow \partial\tilde{F}$ which is homotopic in \tilde{F} to a map from S^1 to a component A of Φ_{2n-1}^ϵ . It follows that A must be an outer component of Φ_{2n-1}^ϵ , and hence that $\dot{\Phi}_{2n-1}^\epsilon \neq \emptyset$. Since \tilde{F} is not a semi-fiber and since the hypotheses stated in Subsection 6.1.1 hold, we may apply Proposition 6.1.11 to conclude that $\dot{\Phi}_{2i-1}^\epsilon$ is not a regular neighborhood of $\dot{\Phi}_{2i+1}^\epsilon$ for $i = 1, \dots, n$. We will show that in this situation $n \leq 2\tilde{g} + 3\tilde{m}/2 - 2$ if

F is separating and $n \leq 2\tilde{g} + 3\tilde{m}/2 - 4$ if F is non-separating. Since $\tilde{l} \leq 2n$ this will imply the theorem.

We have $c(\tilde{F}) = 2\tilde{g} + 3\tilde{m}/2 - 2$ if F is separating and $c(\tilde{F}) = 2\tilde{g} + 3\tilde{m}/2 - 4$ if F is non-separating. Hence it will suffice to show that if A and B are two allowable subsurfaces with $B \subset \text{int } A$, then $c(B) < c(A)$ unless A is a regular neighborhood of B .

As in the proof of Theorem 5.4.1 it suffices to show, for a component A_0 of A and the subsurface $B_0 = B \cap A_0$, that $c(B_0) < c(A_0)$ if A_0 is not a regular neighborhood of B_0 . We have that $\text{genus}(B_0) \leq \text{genus}(A_0)$, that $\chi(B_0) \geq \chi(A_0)$, and $\nu(B_0) \leq \nu(A_0)$. Thus we need only consider the two cases where $|B_0| \leq |A_0| = 1$, i.e. where B_0 is empty and where B_0 is connected. The case $B_0 = \emptyset$ is easy since $A_0 \neq \emptyset$ implies $c(A_0) > 0$. For the case where B_0 is connected we observe that if $c(B_0) = c(A_0)$, then we have $\text{genus}(B_0) = \text{genus}(A_0)$ and $\chi(B_0) = \chi(A_0)$; it then follows as in the proof of Theorem 5.4.1 that A_0 is a regular neighborhood of B_0 . □

We are now ready to state and prove one of the main results of this paper. Recall that the function $N(s, n, v)$ was defined in Subsection 3.7.

Theorem 6.2.2. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface with boundary slope β which is not a semi-fiber. Let (S, X, h) be a singular surface which is well positioned with respect to F and has boundary slope α . Set $s = \text{genus } S$, $n = |\partial S - X|$, $v = |X|$, $g = \text{genus } F$ and $m = |\partial F|$. Then*

$$\Delta(\alpha, \beta) \leq \left(\frac{4g - 3}{m} + 3 \right) N(s, n, v).$$

Proof. According to Proposition 3.9, there exists an essential homotopy $H : I \times I \rightarrow M$ having length

$$(1) \quad l \geq \frac{m\Delta(\alpha, \beta)}{N(s, n, v)} - 1,$$

such that H_0 is an essential path in F and $H_t(\partial I) \subset \partial M$ for all $t \in I$. By Theorem 6.2.1 we have that

$$(2) \quad l \leq 4g + 3m - 4.$$

The conclusion follows from the inequalities (1) and (2). □

Corollary 6.2.3. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface with boundary slope β which is not a semi-fiber. Set $g = \text{genus } F$ and $m = |\partial F|$. Let α be a slope in ∂M . If $M(\alpha)$ is very small, or more generally if $F \subset M \subset M(\alpha)$ is not π_1 -injective in $M(\alpha)$, then*

$$\Delta(\alpha, \beta) \leq \frac{20g - 15}{m} + 15.$$

Proof. We invoke Corollary 2.3 to obtain a singular surface (S, X, h) , well positioned with respect to F , such that $\text{genus } S = 0$ and $|X| = 1$. The conclusion now follows from Theorem 6.2.2 because for any $v \geq 1$ we have $N(0, 1, v) \leq 5$. □

Corollary 6.2.4. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface with boundary slope β which is not a semi-fiber. Let α be a slope*

in ∂M . Set $g = \text{genus } F$ and $m = |\partial F|$. If $M(\alpha)$ is a Seifert fibered space or if there exists a π_1 -injective map from $S^1 \times S^1$ to M , then

$$\Delta(\alpha, \beta) \leq \frac{24g - 18}{m} + 18.$$

Proof. We invoke Corollary 2.6 to obtain a singular surface (S, X, h) , well positioned with respect to F , such that either $\text{genus } S = 0$ and $|X| = 1$, or $\text{genus } S = 1$ and $|X| = 0$. The conclusion now follows from Theorem 6.2.2 because for any $v \geq 1$ we have $N(0, 1, v) \leq 5$ and $N(1, 0, v) = 6$. □

Corollary 6.2.5. *Let M be a simple knot manifold. Suppose, for $i = 1, 2$, that $F_i \subset M$ is an essential bounded surface of genus g_i with boundary slope β_i . Let $m_i = |\partial F_i|$. If F_1 is not a semi-fiber, then we have*

$$\Delta(\beta_1, \beta_2) \leq \left(\frac{4g_1 - 3}{m_1} + 3 \right) \left(\left\lceil \frac{12g_2 - 12}{m_2} \right\rceil + 6 \right).$$

Proof. We apply Proposition 2.1 with $F = F_1$ and $S = F_2$. This gives a singular surface $(F_2, \partial F_2, h)$ which is well positioned with respect to F_1 . Theorem 6.2.2 then implies that

$$\Delta(\beta_1, \beta_2) \leq \left(\frac{4g_1 - 3}{m_1} + 3 \right) N(g_2, 0, m_2).$$

Note that since M is a simple knot manifold, the surface F_2 cannot be a disk or an annulus. It then follows from Subsection 3.7 that

$$N(s, n, v) = \left\lceil \frac{12g_2 - 12}{m_2} \right\rceil + 6.$$

□

Ian Agol has informed us that a slightly stronger estimate follows from the techniques in his paper [A]. By combining his Theorem 5.1 with the proof of his Theorem 8.1 he can show under the hypotheses of Corollary 6.2.5 that

$$\Delta(\beta_1, \beta_2) \leq \frac{36}{3.35} \left(\frac{2g_1 - 2}{m_1} + 1 \right) \left(\frac{2g_2 - 2}{m_2} + 1 \right).$$

In particular the coefficient of $g_1 g_2 / m_1 m_2$ is less than 43 for this estimate, while in the estimate provided by Corollary 6.2.5 the corresponding coefficient is 48. Agol’s methods depend on the rigorous computational results of Cao and Meyerhoff [CM].

Corollary 6.2.6. *Let M be a simple knot manifold, and let $F \subset M$ be an essential bounded surface with boundary slope β which is not a semi-fiber. Set $g = \text{genus } F$ and $m = |\partial F|$. If α is the boundary slope of an essential planar surface in M , then*

$$\Delta(\alpha, \beta) \leq \frac{20g - 15}{m} + 15.$$

Proof. If $M(\alpha)$ is reducible, then there is an essential planar surface F_2 with boundary slope α . The result follows from Corollary 6.2.5 by taking $F = F_1$, $\beta = \beta_1$, and $\alpha = \beta_2$. □

Still another corollary to Theorem 6.2.2 can be obtained by using Corollary 2.5. The reader is invited to formulate the statement.

7. TIGHT SURFACES

The goal of this section is to prove Theorem 7.4.2, which provides a major improvement on conclusion of Theorem 6.2.1 in the special case where F is planar, i.e. $g = 0$. This leads to corresponding improvements to the corollaries of the previous section in cases where the planarity assumption hold.

The techniques used in this section make use of some variants of the surfaces $\dot{\Phi}_k^\epsilon$ which are denoted $\check{\Phi}_k^\epsilon$. We start with some preliminaries which are needed for the definition of these surfaces.

7.1. Perfect surfaces. In this subsection S will denote a compact orientable surface of negative Euler characteristic. If A is a subsurface of S we will denote the frontier of A by $Fr A$.

Definition 7.1.1. A subsurface A of S will be said to be *perfect* if

- (i) A is π_1 -injective;
- (ii) A contains ∂S ; and
- (iii) every component of A contains a component of ∂S .

Thus if A is a perfect subsurface of S then each component of A is either a large subsurface of S which contains a component of ∂S or a regular neighborhood of a component of ∂S .

Suppose that A is a large outer subsurface of a compact orientable surface S . Let A' denote a subsurface in the non-ambient isotopy class of A such that for every component C of $\partial A'$, either $C \subset \partial S$, or $C \subset int S$ and C is not parallel to any component of ∂S . The surface A' is unique up to ambient isotopy. We define a *perfection* of A , denoted $\mathcal{P}(A)$, to be a surface of the form $A' \cup N$, where N is a regular neighborhood of the union of all components of ∂S which are not contained in $\partial A'$, and $N \cap A' = \emptyset$. Note that $\mathcal{P}(A)$ is a perfect surface and that the ambient isotopy class of $\mathcal{P}(A)$ is uniquely determined by the non-ambient isotopy class of A . Moreover, if c is a component of ∂S and if C is the component containing c , then no other component of $\mathcal{P}(A)$ contains a curve isotopic to c .

7.1.2. There is an obvious inverse operation to perfection: if B is a perfect subsurface of S , then $\mathcal{L}(B)$ is a large outer subsurface of S . It is clear that if A is any large outer subsurface of S , then $\mathcal{L}(\mathcal{P}(A))$ is (non-ambiently) isotopic to A , and that if B is any perfect subsurface of S , then B is ambiently isotopic to $\mathcal{P}(\mathcal{L}(B))$. Thus we have a natural bijective correspondence between non-ambient isotopy classes of large outer subsurfaces of S and ambient isotopy classes of perfect subsurfaces of S .

The following lemma will be needed in Subsection 7.2.

Lemma 7.1.3. *Let P be a perfect subsurface of S and suppose that τ is a free involution of P . Suppose that $A \subset P$ is a large outer subsurface of S which is invariant under τ . Then A has a perfection which is contained in P and invariant under τ .*

Proof. By replacing A with a slightly smaller τ -invariant surface we may assume that A is contained in $int S$. Let A' be the union of A with all of the annuli in S which have one boundary component in ∂A and one boundary component in ∂S . Since P is perfect, A is contained in P and invariant under τ . Thus $\partial S - \partial A'$ is also invariant under τ . We define the required perfection of A to be the union of A' with a suitably small τ -invariant regular neighborhood of $\partial S - \partial A'$. \square

7.1.4. If A and B are two perfect subsurfaces of S , then we define the *perfect intersection* of A and B , denoted $A \wedge_{\mathcal{P}} B$, to be $\mathcal{P}(\mathcal{L}(A) \wedge_{\mathcal{L}} \mathcal{L}(B))$. Observe that a perfect subsurface of S is homotopic into $A \wedge_{\mathcal{P}} B$ if and only if it is homotopic into both A and B . It follows from this together with Lemma 4.1, that $A \wedge_{\mathcal{P}} B$ is isotopic to $B \wedge_{\mathcal{P}} A$ and that $(A \wedge_{\mathcal{P}} B) \wedge_{\mathcal{P}} C$ is isotopic to $A \wedge_{\mathcal{P}} (B \wedge_{\mathcal{P}} C)$.

Now let A and B be large outer subsurfaces of S . It follows from the definition of perfect intersection and the bijective correspondence described in Definition 7.1.1 that

$$\mathcal{P}(A) \wedge_{\mathcal{P}} \mathcal{P}(B) = \mathcal{P}(A \wedge_{\mathcal{L}} B).$$

Proposition 7.1.5. *Let P and Q be perfect surfaces of S . Then there exist (perfect) surfaces P_1 and Q_1 which are ambiently isotopic to P and Q respectively, such that the frontiers of P_1 and Q_1 meet transversely and $P \wedge_{\mathcal{P}} Q$ is ambiently isotopic to the union of all components of $P_1 \cap Q_1$ which meet ∂S .*

Proof. Set $A = \mathcal{L}(P)$ and $B = \mathcal{L}(Q)$. According to Proposition 4.2, A and B are non-ambiently isotopic to surfaces $A_0 \subset \text{int } S$ and $B_0 \subset \text{int } S$ such that ∂A_0 and ∂B_0 meet transversely and $\mathcal{L}(A_0 \cap B_0)$ is isotopic to $A \wedge_{\mathcal{L}} B$. Let A_1 be the union of A_0 with all of the annular components of $S - A_0$ which meet ∂S . It is clear that A_1 is ambiently isotopic to A . In the same way, using B_0 , we define a subsurface B_1 which is ambiently isotopic to B . We claim that $\mathcal{L}(A_1 \cap B_1)$ is isotopic to $A \wedge_{\mathcal{L}} B$. According to Proposition 4.2 and Definition 4.3 it suffices to show that property (*) of Proposition 4.2 holds with C replaced by $\mathcal{L}(A_1 \cap B_1)$. The “only if” part of (*) is clear because A_1 is isotopic to A and B_1 is isotopic to B . Since the “if” part of Proposition 4.2 holds with C replaced by $\mathcal{L}(A_0 \cap B_0)$, the claim will follow once we show that $\mathcal{L}(A_0 \cap B_0) \subset \mathcal{L}(A_1 \cap B_1)$. Since $A_0 \cap B_0 \subset A_1 \cap B_1$, it suffices to show that $A_1 \cap B_1$ is π_1 -injective. But since $\chi(S) < 0$, any homotopically trivial simple closed curve $\gamma \subset A_1 \cap B_1$ bounds a unique disk D in S ; since A_1 and B_1 are π_1 -injective we must have $D \subset A_1$ and $D \subset B_1$ and hence $D \subset A_1 \cap B_1$. This proves the claim.

Thus we may take $A \wedge_{\mathcal{L}} B$ to be equal to $\mathcal{L}(A_1 \cap B_1)$. Let W denote the union of the large components of $A_1 \cap B_1$ that meet ∂S . We next assert that W is $A \wedge_{\mathcal{L}} B$. To prove this it suffices to show that every large outer component X of $A_1 \cap B_1$ contains a component of ∂S . By the definition of an outer component (see Subsection 4.6), X contains a closed curve $\gamma \subset \text{int } S$ which is the frontier of an annulus $\alpha \subset S$. Since $\gamma \subset A_1$ and $\gamma \subset B_1$, it follows from the construction of A_1 and B_1 that α is contained in both A_1 and B_1 , and hence in X . In particular, X contains a component of ∂S as required.

Now let N be regular neighborhood of ∂S . We may assume N to be chosen so that each component of N is disjoint from the frontiers of A_1 and B_1 . We set $P_1 = A_1 \cup N$ and $Q_1 = B_1 \cup N$. It is clear that P_1 and Q_1 are isotopic to P and Q , respectively. It is also clear that the union Z of the components of $P_1 \cap Q_1$ which meet ∂S is equal to $W \cup N$. Since W is $A \wedge_{\mathcal{L}} B$, we have that $Z = \mathcal{P}(W) = \mathcal{P}(A \wedge_{\mathcal{L}} B)$. But by definition we have that $P \wedge_{\mathcal{P}} Q = \mathcal{P}(A \wedge_{\mathcal{L}} B)$. This completes the proof. \square

7.1.6. Suppose that P and Q are perfect subsurfaces of S . Let C be a component of the perfect intersection $P \wedge_{\mathcal{P}} Q$. Since C is isotopic to a subsurface of P , there must be a component P_0 of P such that C is isotopic to a subsurface of P_0 . We will say in this situation that C is *isotopically contained in P_0* . Let c be a component of

∂S which is contained in C . Then, since there is a unique component of P which contains a curve isotopic to c , it follows that P_0 is the unique component of P which contains a surface isotopic to C . Thus each component of $P \wedge_{\mathcal{P}} Q$ is isotopically contained in a unique component of P .

Definition 7.1.7. Let $A \subset S$ be a perfect surface. A component A_0 of A said to be *tight* if A_0 is planar and the frontier of A_0 in S is a simple closed curve. We define the *size* of a tight component A_0 of A to be the number of components of ∂S which are contained in A_0 . We will denote the size of A_0 by $s(A_0)$.

Proposition 7.1.8. *Let P and Q be perfect subsurfaces of S and let P_0 be a tight component of P . Assume that every tight component of Q has size at least $s(P_0)$. Then every component of $P \wedge_{\mathcal{P}} Q$ which is isotopically contained in P_0 is tight and has size at most $s(P_0)$. Furthermore if P_0 contains only one component of $P \wedge_{\mathcal{P}} Q$ then this component is isotopic to P_0 .*

Proof. By Proposition 7.1.5 we may assume that P and Q have been chosen within their isotopy classes so that the frontiers of P and Q meet transversely and $Z = P \wedge_{\mathcal{P}} Q$ is the union of all components of $P \cap Q$ which meet ∂S .

Consider first the case in which P_0 contains at least one component of $Fr Q$. Note that since Q is perfect, the components of $Fr Q$ are homotopically non-trivial simple closed curves in S . Since P_0 is planar and has connected frontier, every homotopically non-trivial simple closed curve γ in $int P_0$ is the frontier in S of a unique subsurface W_γ of P_0 ; the non-triviality of γ implies that W_γ is not a disk and hence that $W_\gamma \cap \partial S \neq \emptyset$. Among all components of $Fr Q$ contained in P_0 we choose one, γ_0 , such that W_{γ_0} is minimal with respect to inclusion. The minimality implies that W_{γ_0} is either a component of Q or of $\overline{S - Q}$. But since Q is perfect, we have $\partial S \subset Q$ and hence $W_{\gamma_0} \cap Q \supset W_{\gamma_0} \cap \partial S \neq \emptyset$. Hence W_{γ_0} must be a component of Q . Since W_{γ_0} is contained in the planar surface P_0 and has connected frontier, it is in fact a tight component of Q with $s(W_{\gamma_0}) \leq s(P_0)$. On the other hand the hypothesis of the proposition implies that $s(W_{\gamma_0}) \geq s(P_0)$. It now follows that P_0 is a regular neighborhood of W_{γ_0} . Clearly W_{γ_0} is a component of $P \cap Q$ and hence of Z . Since the annulus $\overline{P_0 - W_{\gamma_0}}$ is disjoint from ∂S , it follows that W_{γ_0} is the only component of $P_0 \cap Q$ which meets ∂S . Hence W_{γ_0} is the only component of Z which is contained in P_0 . Since W_{γ_0} is isotopic to its regular neighborhood P_0 , both conclusions of the proposition are established in this case.

There remains the case in which each component of $P_0 \cap Fr Q$ is a properly embedded arc in P_0 having both endpoints on $Fr P_0$. It follows that any component of $P_0 \cap Q$ is a planar surface whose frontier in S is a simple closed curve. In particular, if C is a component of $P_0 \cap Q$ which contains a component of ∂S , then C is a tight component of Z . It is also clear that $s(C) \leq s(P_0)$. To prove the last assertion of the proposition in this case, assume that C is the only tight component of Z which is contained in P_0 . Then the frontier in P_0 of C is a collection of properly embedded arcs which are parallel to subarcs of $Fr P_0$. It then follows that C is isotopic to P_0 . \square

Proposition 7.1.9. *Suppose that S is planar and let $P \neq S$ be a perfect subsurface of S . Then P has a tight component.*

Proof. Since $P \neq S$ we have $Fr P \neq \emptyset$. Since P is perfect, each component of $Fr P$ is a homotopically non-trivial curve in S and hence is the frontier of two planar

subsurfaces of S , neither of which is a disk. Among all subsurfaces A of S such that $Fr A$ consists of a single component of $Fr S$ we choose one, say A_0 , which is minimal with respect to inclusion. Since A_0 is not a disk, we have $A_0 \cap \partial S \neq \emptyset$. The minimality implies that either A_0 is a component of P or of $\overline{S - P}$. But since P is perfect, we have $\partial S \subset P$ and hence $A_0 \cap P \supset A_0 \cap \partial S \neq \emptyset$. Thus A_0 is a component of P and by definition is tight. \square

We record here a simple lemma that will be needed in the next subsection.

Lemma 7.1.10. *Let A be an oriented annulus, and let α be a component of ∂A . Let f and g be two embeddings of A into an orientable surface F . Suppose that $f(\alpha) = g(\alpha) = c$, where c is a component of ∂F , and that f and g carry the orientation of A to the same orientation of F . Then f and g are homotopic.* \square

7.2. Reduced homotopies and perfect subsurfaces.

7.2.1. Throughout Subsection 7.2 we will assume that M is a simple knot manifold and that \tilde{F} is a splitting surface in M which admits a long rectangle. Since this is the same assumption that was made in Proposition 6.1.1, the results of Subsection 6.1 may be applied in this subsection.

We will fix $\check{\Phi}_k^{\pm 1}, \check{h}_k^{\pm 1}$ and $\check{\tau}_{\pm 1}$ as in Subsection 6.1.5. Recall that the surfaces $\check{\Phi}_k^\epsilon$ are only defined up to non-ambient isotopy. Here we suppose each surface $\check{\Phi}_k^\epsilon$ to have been normalized within its non-ambient isotopy class so that if C is a boundary component of $\check{\Phi}_k^\epsilon$, then either $C \subset \partial \tilde{F}$, or $C \subset \text{int } \tilde{F}$ and C is not parallel to any component of $\partial \tilde{F}$. (It is clear that the surfaces $\check{\Phi}_k^\epsilon$ can be chosen to have this property in addition to having the nestedness property stated in Subsection 6.1.5.)

By definition $\check{\Phi}_k^\epsilon$ is a large outer subsurface for each $\epsilon \in \{\pm 1\}$ and $k \geq 0$. Using the notation of Definition 7.1.1 we set

$$\check{\check{\Phi}}_k^\epsilon = \mathcal{P}(\check{\Phi}_k^\epsilon).$$

Because of the way that the surfaces $\check{\Phi}_k^\epsilon$ have been normalized, $\mathcal{P}(\check{\Phi}_k^\epsilon)$ is the disjoint union of $\check{\Phi}_k^\epsilon$ with \mathcal{A}_k^ϵ , where \mathcal{A}_k^ϵ is a regular neighborhood of the union of all components of $\partial \tilde{F}$ which are not contained in $\check{\Phi}_k^{\pm 1}$.

We may assume that the regular neighborhoods \mathcal{A}_k^ϵ have been chosen so that $\check{\check{\Phi}}_k^\epsilon \supset \mathcal{A}_{k+1}^\epsilon$. This means that for each $\epsilon \in \{\pm 1\}$ we have

$$\tilde{F} = \check{\check{\Phi}}_0^\epsilon \supset \check{\check{\Phi}}_1^\epsilon \supset \check{\check{\Phi}}_2^\epsilon \supset \dots$$

Note also that by Subsection 7.1.2 we have $\mathcal{L}(\check{\check{\Phi}}_k^\epsilon) = \check{\Phi}_k^\epsilon$ for each $\epsilon \in \{\pm 1\}$ and each $k \geq 0$.

We denote by m the number of boundary components of \tilde{F} . Since \tilde{F} is a splitting surface the integer m is even. We index the components of $\partial \tilde{F}$ as c_t , where t ranges over $\mathbb{Z}/m\mathbb{Z}$. If q is an integer we will denote the image of q in $\mathbb{Z}/m\mathbb{Z}$ by \bar{q} .

We assume that the indexing of components of $\partial \tilde{F}$ has been done in such a way that for each $t \in \mathbb{Z}/m\mathbb{Z}$ the curves c_t and c_{t+1} cobound an annulus $R_t \subset \partial M$ whose interior is disjoint from $\partial \tilde{F}$. We may assume further that the indexing is done in such a way that $R_{\bar{q}} \subset M_{\tilde{F}}^+$ for every even integer q and $R_{\bar{q}} \subset M_{\tilde{F}}^-$ for every odd integer q .

7.2.2. For every integer $k \geq 0$ and $\epsilon \in \{\pm 1\}$ we define a permutation σ_k^ϵ of $\mathbb{Z}/m\mathbb{Z}$ by

$$\sigma_k^\epsilon(\bar{q}) = \overline{q + (-1)^q \epsilon k}.$$

(Since m is even, the coefficient $(-1)^q$ is determined by the congruence class \bar{q} .)

We observe that if i and j are non-negative integers with $i + j = k$, then for each $\epsilon \in \{\pm 1\}$ we have

$$(7.2.2.1) \quad \sigma_k^\epsilon = \sigma_j^{(-1)^i \epsilon} \circ \sigma_i^\epsilon.$$

We also observe that for each $k \geq 0$ and each $\epsilon \in \{\pm 1\}$ we have

$$(7.2.2.2) \quad (\sigma_k^\epsilon)^{-1} = \sigma_k^{(-1)^k \epsilon}.$$

From (1) and (2) it follows that for each $k \geq 0$ and each $\epsilon \in \{\pm 1\}$ we have

$$(7.2.2.3) \quad \sigma_{2k+1}^\epsilon = (\sigma_k^\epsilon)^{-1} \circ \sigma_1^{(-1)^k \epsilon} \circ \sigma_k^\epsilon.$$

It is clear from (7.2.2.3) that σ_k^ϵ is a free involution if k is odd.

Lemma 7.2.3. *Let k be a positive integer and fix $\epsilon \in \{\pm 1\}$. If a component c_t of $\partial\tilde{F}$ is contained in $\tilde{\Phi}_k^\epsilon$ for some $t \in \mathbb{Z}/m\mathbb{Z}$, then $h_k^\epsilon(c_t) = c_{\sigma_k^\epsilon(t)}$.*

Proof. The lemma is trivial in the case $k = 0$.

Consider the case $k = 1$. By Lemma 6.1.2, together with our normalization of $\tilde{\Phi}_1^\epsilon$, we know that every component of $\partial\tilde{F}$ is contained in $\tilde{\Phi}_1^\epsilon$ and that $h_1^\epsilon = \tau_\epsilon$ interchanges two components c and c' of $\partial\tilde{F}$ if and only if c and c' cobound an annulus component of $M_{\tilde{F}}^\epsilon \cap M$. The definition of σ_1^ϵ thus implies that for every $t \in \mathbb{Z}/m\mathbb{Z}$ we have $h_1^\epsilon(c_t) = \tau_\epsilon(c_t) = c_{\sigma_1^\epsilon(t)}$.

Now, arguing inductively, we assume that $k > 1$, that c_t is a component of $\partial\tilde{F}$ contained in $\tilde{\Phi}_k^\epsilon \subset \tilde{\Phi}_{k-1}^\epsilon$ and that $h_{k-1}^\epsilon(c_t) = c_{\sigma_{k-1}^\epsilon(t)}$. Applying Proposition 6.1.6 with $i = k - 1$ and $j = 1$ we see $h_{k-1}^\epsilon|_{\tilde{\Phi}_k^\epsilon}$ is homotopic in \tilde{F} to an embedding $\dot{g}_{k-1}^\epsilon : \tilde{\Phi}_k^\epsilon \rightarrow \tilde{\Phi}_1^{(-1)^{k-1}\epsilon}$ such that h_k^ϵ is homotopic to $h_1^{(-1)^{k-1}\epsilon} \circ \dot{g}_{k-1}^\epsilon$. Since $h_{k-1}^\epsilon(c_t) = c_{\sigma_{k-1}^\epsilon(t)}$, the curve $\dot{g}_{k-1}^\epsilon(c_t) \subset \tilde{\Phi}_1^{(-1)^{k-1}\epsilon}$ is homotopic in \tilde{F} to the boundary component $c_{\sigma_{k-1}^\epsilon(t)}$ of \tilde{F} . It follows from the normalization of $\tilde{\Phi}_1^{-\epsilon}$ in Subsection 7.2.1 that $c_{\sigma_{k-1}^\epsilon(t)}$ is a boundary component of $\Phi_1^{(-1)^{k-1}\epsilon}$, and that $\dot{g}_{k-1}^\epsilon(c_t)$ is homotopic in $\Phi_1^{(-1)^{k-1}\epsilon}$ to $c_{\sigma_{k-1}^\epsilon(t)}$. Hence $h_k^\epsilon(c_t)$ is homotopic in \tilde{F} to $h_1^{(-1)^{k-1}\epsilon}(c_{\sigma_{k-1}^\epsilon(t)})$ which by the case $k = 1$ of the lemma is equal to

$$c_{\sigma_1^{(-1)^{k-1}\epsilon} \circ \sigma_{k-1}^\epsilon(t)} = c_{\sigma_k^\epsilon(t)}.$$

Since the boundary component $h_k^\epsilon(c_t)$ of $h_k^\epsilon(\tilde{\Phi}_k^\epsilon) = \tilde{\Phi}_k^{(-1)^{k+1}\epsilon}$ is homotopic to the component $c_{\sigma_k^\epsilon(t)}$ of $\partial\tilde{F}$, it follows from the normalization of $\tilde{\Phi}_k^{(-1)^{k+1}\epsilon}$ that $h_k^\epsilon(c_t) = c_{\sigma_k^\epsilon(t)}$. □

Lemma 7.2.4. *For each $\epsilon \in \{\pm 1\}$ and each $k \geq 0$, there exists a homeomorphism $\check{h}_k^\epsilon : \check{\Phi}_k^\epsilon \rightarrow \check{\Phi}_k^{(-1)^{k+1}\epsilon}$ such that*

- (1) *the restriction of \check{h}_k^ϵ to $\mathcal{L}(\check{\Phi}_k^\epsilon) = \dot{\Phi}_k^\epsilon$ is \dot{h}_k^ϵ ;*
- (2) *if \tilde{F} is given a consistent orientation, $\check{h}_k^\epsilon : \check{\Phi}_k^\epsilon \rightarrow \check{\Phi}_k^{(-1)^{k+1}\epsilon}$ reverses orientation if k is odd and preserves orientation if k is even; and*

(3) for each $t \in \mathbb{Z}/m\mathbb{Z}$ we have $\check{h}_k^\epsilon(c_t) = c_{\sigma_k^\epsilon(t)}$.

The homeomorphism \check{h}_k^ϵ is determined up to isotopy by the properties (1)-(3). Furthermore we may choose \check{h}_1^ϵ within its isotopy class so that it is a free involution.

Proof. Fix an orientation of $\check{\Phi}_k^\epsilon$ which is induced from a consistent orientation of \tilde{F} . By Lemma 7.2.3 we know that if $c_t \subset \check{\Phi}_k^\epsilon$, then $\dot{h}_k^\epsilon(c_t) = c_{\sigma_k^\epsilon(t)}$. In particular, the correspondence $c_t \rightarrow c_{\sigma_k^\epsilon(t)}$ restricts to a bijection between the components of $\partial\tilde{F} \cap \check{\Phi}_k^\epsilon$ and those of $\partial\tilde{F} \cap \check{\Phi}_k^{(-1)^{k+1}\epsilon}$. It therefore also restricts to a bijection between the components of $\partial\tilde{F} - \partial\check{\Phi}_k^\epsilon$ and those of $\partial\tilde{F} - \partial\check{\Phi}_k^{(-1)^{k+1}\epsilon}$. Now $\check{\Phi}_k^\epsilon$ is the union of $\check{\Phi}_k^\epsilon$ with the regular neighborhood \mathcal{A}_k^ϵ of $\partial\tilde{F} - \partial\check{\Phi}_k^\epsilon$, and $\check{\Phi}_k^{(-1)^{k+1}\epsilon}$ is the union of $\check{\Phi}_k^{(-1)^{k+1}\epsilon}$ with the regular neighborhood $\mathcal{A}_{k+1}^{(-1)^{k+1}\epsilon}$ of $\partial\tilde{F} - \partial\check{\Phi}_k^{(-1)^{k+1}\epsilon}$. Let f_k^ϵ be a homeomorphism from \mathcal{A}_k^ϵ to $\mathcal{A}_{k+1}^{(-1)^{k+1}\epsilon}$ which maps each component c_t of $\partial\tilde{F} \cap \mathcal{A}_k^\epsilon$ to the component $c_{\sigma_k^\epsilon(t)}$ of $\partial\tilde{F} \cap \mathcal{A}_{k+1}^{(-1)^{k+1}\epsilon}$. Since each component of \mathcal{A}_k^ϵ is an annulus we may choose f_k^ϵ to be an orientation-reversing embedding of \mathcal{A}_k^ϵ into \tilde{F} if k is odd, and an orientation-preserving embedding if k is even. These conditions determine f_k up to isotopy. We define \check{h}_k^ϵ to be the homeomorphism whose restriction to $\check{\Phi}_k^\epsilon$ is \dot{h}_k^ϵ and whose restriction to \mathcal{A}_k^ϵ is f_k . Conditions (1) and (3) hold by construction. To see that condition (2) holds it suffices to observe that by Subsection 6.1.5 the embedding $\dot{h}_k^\epsilon : \check{\Phi}_k^\epsilon \rightarrow \tilde{F}$ reverses orientation if k is odd and preserves orientation if k is even, and that f_k^ϵ has the same property by construction.

Since we have observed that f_k^ϵ is determined up to isotopy by its stated properties, it follows that \check{h}_k^ϵ is determined up to isotopy by conditions (1)-(3). Finally, since σ_1^ϵ is a free involution it is clear that we may choose f_1^ϵ within its isotopy class so that it is a free involution. Since \dot{h}_1^ϵ is a free involution by Subsection 6.1.5 it follows that \check{h}_1^ϵ is a free involution. □

7.2.5. For the rest of Subsection 7.2 we will fix homeomorphisms \check{h}_k^ϵ satisfying the conclusions of Lemma 7.2.4. The free involution \check{h}_1^ϵ will sometimes be denoted $\check{\tau}_\epsilon$. Note that $\check{\tau}_\epsilon$ is an extension of the free involution $\check{\tau}_\epsilon$ defined in Subsection 6.1.5.

Lemma 7.2.6. *Let k and i be integers with $k \geq i \geq 0$. Then $\check{h}_i^\epsilon(\check{\Phi}_k^\epsilon)$ is ambiently isotopic to $\mathcal{P}(\dot{h}_i^\epsilon(\check{\Phi}_k^\epsilon))$.*

Proof. Since $\check{\Phi}_k^\epsilon$ and $\check{\Phi}_i^\epsilon$ are perfect surfaces, and since $\check{h}_i^\epsilon : \check{\Phi}_i^\epsilon \rightarrow \tilde{F}$ is an embedding which maps $\partial\tilde{F}$ onto $\partial\tilde{F}$ (see Lemma 7.2.3), it follows that $\check{h}_i^\epsilon(\check{\Phi}_k^\epsilon)$ is a perfect subsurface of \tilde{F} . On the other hand, by Subsections 7.1.2 and 7.2.1 we have $\check{\Phi}_k^\epsilon = \mathcal{L}(\check{\Phi}_k^\epsilon)$. Since \check{h}_i^ϵ is a homeomorphism, $\dot{h}_i^\epsilon(\check{\Phi}_k^\epsilon) = \check{h}_i^\epsilon(\check{\Phi}_k^\epsilon) = \mathcal{L}(\check{h}_i^\epsilon(\check{\Phi}_k^\epsilon))$. Since $\check{h}_i^\epsilon(\check{\Phi}_k^\epsilon)$ is perfect, it follows from Subsection 7.1.2 that $\dot{h}_i^\epsilon(\check{\Phi}_k^\epsilon)$ is ambiently isotopic to $\mathcal{P}(\check{h}_i^\epsilon(\check{\Phi}_k^\epsilon))$. □

The next four results, Propositions 7.2.7 – 7.2.10, are analogues for the surfaces $\check{\Phi}_k^\epsilon$ of Propositions 6.1.6, 6.1.7, 6.1.9 and 6.1.11.

Proposition 7.2.7. *Let i and j be non-negative integers, and set $k = i + j$. Then for each $\epsilon \in \{\pm 1\}$, the map $\check{h}_i^\epsilon|_{\check{\Phi}_k^\epsilon}$ is homotopic in \tilde{F} , rel $\partial\tilde{F}$, to an embedding $\check{g}_i^\epsilon : \check{\Phi}_k^\epsilon \rightarrow \check{\Phi}_j^{(-1)^i\epsilon}$ such that $\check{h}_j^{(-1)^i\epsilon} \circ \check{g}_i^\epsilon$ is homotopic in \tilde{F} to \check{h}_k^ϵ .*

Proof. Let $\dot{g}_i^\epsilon: \dot{\Phi}_k^\epsilon \rightarrow \dot{\Phi}_j^{(-1)^i\epsilon}$ be given by Proposition 6.1.6. Let c_t be a boundary component of \tilde{F} that is contained in $\dot{\Phi}_k^\epsilon$. We have $\dot{h}_i^\epsilon(c_t) = c_{\sigma_i^\epsilon(t)}$. Since \dot{g}_i^ϵ is homotopic to \dot{h}_i^ϵ , the map $\dot{g}_i^\epsilon|_{c_t}: c_t \rightarrow \dot{\Phi}_j^{(-1)^i\epsilon}$ is homotopic in \tilde{F} to $\dot{h}_i^\epsilon|_{c_t}$. Because of the way that the surface $\dot{\Phi}_j^{(-1)^i\epsilon}$ has been normalized, this means that $c_{\sigma_i^\epsilon(t)}$ is a boundary curve of $\dot{\Phi}_j^{(-1)^i\epsilon}$ and that $\dot{g}_i^\epsilon|_{c_t}$ is isotopic to $\dot{h}_i^\epsilon|_{c_t}$ in $\dot{\Phi}_j^{(-1)^i\epsilon}$. Therefore, after modifying \dot{g}_i^ϵ by a non-ambient isotopy, we may assume that, for each c_t contained in $\partial\dot{\Phi}_k^\epsilon$, we have $\dot{g}_i^\epsilon(c_t) = c_{\sigma_i^\epsilon(t)}$ and $\dot{g}_i^\epsilon|_{c_t} = \dot{h}_i^\epsilon|_{c_t}$. Since the maps \dot{g}_i^ϵ and \dot{h}_i^ϵ are homotopic and agree on $\partial\tilde{F} \cap \dot{\Phi}_k^\epsilon$, they are homotopic rel $\partial\tilde{F}$.

The homeomorphism \check{h}_i^ϵ maps \mathcal{A}_k^ϵ to a regular neighborhood of a collection of boundary curves of \tilde{F} . Since \dot{g}_i^ϵ agrees with \check{h}_i^ϵ on $\dot{\Phi}_k^\epsilon \cap \partial\tilde{F}$, each boundary component of $\check{h}_i^\epsilon(\mathcal{A}_k^\epsilon) \cap \partial\tilde{F}$ is disjoint from the image of \dot{g}_i^ϵ . Thus $\check{h}_i^\epsilon|_{\mathcal{A}_k^\epsilon}$ is isotopic rel $\partial\tilde{F}$ to an embedding $f: \mathcal{A}_k^\epsilon \rightarrow \dot{\Phi}_j^{(-1)^i\epsilon}$ whose image is disjoint from the image of \dot{g}_i^ϵ .

We define \check{g}_i^ϵ so that $\check{g}_i^\epsilon|_{\mathcal{A}_k^\epsilon} = f$ and $\check{g}_i^\epsilon|_{\dot{\Phi}_k^\epsilon} = \dot{g}_i^\epsilon$. Then \check{g}_i^ϵ is homotopic rel $\partial\tilde{F}$ to $\check{h}_i^\epsilon|_{\dot{\Phi}_k^\epsilon}$. Moreover we have $\check{g}_i^\epsilon(c_t) = c_{\sigma_i^\epsilon(t)}$ for every $t \in \mathbb{Z}/m\mathbb{Z}$. Since $\sigma_k^\epsilon = \sigma_j^{(-1)^i\epsilon} \circ \sigma_i^\epsilon$ by (7.2.2.1), we have $\check{h}_j^{(-1)^i\epsilon} \circ \check{g}_i^\epsilon(c_t) = \check{h}_k^\epsilon(c_t)$ for every $t \in \mathbb{Z}/m\mathbb{Z}$.

Let \tilde{F} be given a consistent orientation. Since the embeddings \check{g}_i^ϵ and $\check{h}_i^\epsilon|_{\dot{\Phi}_k^\epsilon}$ of $\dot{\Phi}_k^\epsilon$ into \tilde{F} are homotopic rel $\partial\tilde{F}$, they both reverse orientation if i is odd and preserve orientation if i is even. In particular, since $i + j = k$, the embeddings $\check{h}_j^{(-1)^i\epsilon} \circ \check{g}_i^\epsilon|_{\mathcal{A}_k^\epsilon}$ and $\check{h}_k^\epsilon|_{\mathcal{A}_k^\epsilon}$ are either both orientation preserving or both orientation reversing. Applying Lemma 7.1.10 to the restrictions of $\check{h}_j^{(-1)^i\epsilon} \circ \check{g}_i^\epsilon$ and \check{h}_k^ϵ to each component of \mathcal{A}_k^ϵ we conclude that $\check{h}_j^{(-1)^i\epsilon} \circ \check{g}_i^\epsilon|_{\mathcal{A}_k^\epsilon}$ is homotopic to $\check{h}_k^\epsilon|_{\mathcal{A}_k^\epsilon}$. On the other hand, according to Proposition 6.1.6, $\dot{h}_j^{(-1)^i\epsilon} \circ \dot{g}_i^\epsilon$ is homotopic to \dot{h}_k^ϵ . Hence $\check{h}_j^{(-1)^i\epsilon} \circ \check{g}_i^\epsilon$ is homotopic to \check{h}_k^ϵ . □

Proposition 7.2.8. *Let i and j be non-negative integers, and set $k = i + j$. Then for each $\epsilon \in \{\pm 1\}$ the subsurface $\check{h}_i^\epsilon(\dot{\Phi}_k^\epsilon)$ is ambiently isotopic in \tilde{F} to the perfect intersection $\check{\Phi}_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_j^{(-1)^i\epsilon}$.*

Proof. By definition we have

$$\check{\Phi}_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_j^{(-1)^i\epsilon} = \mathcal{P} \left(\mathcal{L}(\check{\Phi}_i^{(-1)^{i+1}\epsilon}) \wedge_{\mathcal{L}} \mathcal{L}(\check{\Phi}_j^{(-1)^i\epsilon}) \right) = \mathcal{P}(\dot{\Phi}_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{L}} \dot{\Phi}_j^{(-1)^i\epsilon}).$$

Combining this with Proposition 6.1.7 we conclude that $\check{\Phi}_i^{(-1)^{i+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_j^{(-1)^i\epsilon}$ is equal to $\mathcal{P}(\dot{h}_i^\epsilon(\dot{\Phi}_k^\epsilon))$ which, according to Lemma 7.2.6, is ambiently isotopic to $\check{h}_i^\epsilon(\dot{\Phi}_k^\epsilon)$. □

Proposition 7.2.9. *For any non-negative integer k and for each $\epsilon \in \{\pm 1\}$ the surface $\check{h}_k^\epsilon(\dot{\Phi}_{2k+1}^\epsilon)$ is ambiently isotopic in \tilde{F} to a subsurface of $\check{\Phi}_1^{(-1)^k\epsilon}$ which is invariant under the free involution $\check{\tau}_{(-1)^k\epsilon}$. In particular, $\check{\Phi}_{2k+1}^\epsilon$ admits a free involution which maps c_t to $c_{\sigma_{2k+1}^\epsilon(t)}$ for each $t \in \mathbb{Z}/m\mathbb{Z}$, and is orientation-reversing as an embedding of $\check{\Phi}_{2k+1}^\epsilon$ into \tilde{F} , if \tilde{F} is given a consistent orientation.*

Proof. According to Proposition 6.1.9 there is a subsurface A of $\check{\Phi}_1^{(-1)^k\epsilon} \subset \check{\Phi}_1^{(-1)^k\epsilon}$ which is invariant under $\check{\tau}_{(-1)^k\epsilon} = \check{\tau}_{(-1)^k\epsilon}|_{\dot{\Phi}_1^{(-1)^k\epsilon}}$ and isotopic to $\dot{h}_k^\epsilon(\dot{\Phi}_{2k+1}^\epsilon)$. We

apply Lemma 7.1.3, taking $S = \tilde{F}$, $P = \check{\Phi}_1^{(-1)^k \epsilon}$, and $\tau = \check{\tau}_{(-1)^k \epsilon}$. We conclude that A has a perfection $Q \subset \check{\Phi}_1^{(-1)^k \epsilon}$ which is invariant under $\check{\tau}_{(-1)^k \epsilon}$. Since Q is a perfection of $\check{h}_k^\epsilon(\check{\Phi}_{2k+1}^\epsilon)$, it follows from Lemma 7.2.6 that Q is ambiently isotopic to $\check{h}_k^\epsilon(\check{\Phi}_{2k+1}^\epsilon)$. This completes the proof of the first assertion.

Let $h : \check{\Phi}_{2k+1}^\epsilon \rightarrow \tilde{F}$ be an embedding which is ambiently isotopic to $\check{h}_k^\epsilon|_{\check{\Phi}_{2k+1}^\epsilon}$ and maps $\check{\Phi}_{2k+1}^\epsilon$ onto Q . We define a free involution τ of $\check{\Phi}_{2k+1}^\epsilon$ by $\tau = h^{-1} \circ \check{\tau}_{(-1)^k \epsilon} \circ h$. Thus $\tau(c_t) = c_s$ where $s = (\sigma_k^\epsilon)^{-1} \circ \sigma_1^{(-1)^k \epsilon} \circ \sigma_k^\epsilon(t)$. It follows from (7.2.2.1) that $s = \sigma_{2k+1}^\epsilon(t)$.

Let \tilde{F} be given a consistent orientation. Lemma 7.2.4 implies that h preserves orientation if k is odd, that h reverses orientation if k is even, and that $\check{\tau}_{(-1)^k \epsilon}$ reverses orientation. It follows that τ is orientation-reversing as an embedding of $\check{\Phi}_{2k+1}^\epsilon$ into \tilde{F} . □

Proposition 7.2.10. *Let k be a non-negative integer and let $\epsilon \in \{\pm 1\}$ be given. If $\check{\Phi}_k^\epsilon$ and $\check{\Phi}_{k+2}^\epsilon$ are isotopic in \tilde{F} , then either $\check{\Phi}_k^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$ or \tilde{F} is a semi-fiber.*

Proof. By definition we have that $\check{\Phi}_k^\epsilon = \mathcal{P}(\check{\Phi}_k^\epsilon)$ and $\check{\Phi}_{k+2}^\epsilon = \mathcal{P}(\check{\Phi}_{k+2}^\epsilon)$. Thus it follows from Subsection 7.1.2 that $\check{\Phi}_k^\epsilon$ is isotopic to $\check{\Phi}_{k+2}^\epsilon$ if and only if $\check{\Phi}_k^\epsilon$ is isotopic to $\check{\Phi}_{k+2}^\epsilon$, and that $\check{\Phi}_k^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$ if and only if $\check{\Phi}_k^\epsilon$ is empty. The result therefore follows from Proposition 6.1.11. □

7.3. Very tight surfaces. In this subsection we assume that M is a simple knot manifold, and that \tilde{F} is a splitting surface for M which admits a long rectangle.

For each integer $k \geq 0$ and each $\epsilon \in \{\pm 1\}$ we will define the perfect subsurfaces $\check{\Phi}_k^\epsilon = \mathcal{A}_k^\epsilon \cup \check{\Phi}_k^\epsilon$, with $\tilde{F} = \check{\Phi}_0^\epsilon \supset \check{\Phi}_1^\epsilon \supset \check{\Phi}_2^\epsilon \supset \dots$, as in Subsection 7.2.

We set $m = |\partial\tilde{F}|$ and we assume that the components of $\partial\tilde{F}$ have been indexed by elements of $\mathbb{Z}/m\mathbb{Z}$ as described in Subsection 7.2. We also define the permutations σ_k^ϵ as in Subsection 7.2, and for each integer $k \geq 0$ and $\epsilon \in \{\pm 1\}$ we fix a homeomorphism \check{h}_k^ϵ satisfying the conclusions of Lemma 7.2.4.

For $\epsilon \in \{\pm 1\}$ we denote by \mathcal{T}^ϵ the set of tight components of $\check{\Phi}_1^\epsilon$. We define s_0 to be the infimum of $s(C)$ as C ranges over $\mathcal{T}^+ \cup \mathcal{T}^-$. Thus, if $\mathcal{T}^+ = \mathcal{T}^- = \emptyset$, then $s_0 = +\infty$ and otherwise s_0 is a strictly positive integer. We will say that a component of a perfect subsurface of \tilde{F} is *very tight* if it is tight and has size at most s_0 . (In particular, if $\mathcal{T}^+ = \mathcal{T}^- = \emptyset$, then any tight component of a perfect subsurface is very tight.)

If A is a perfect subsurface of \tilde{F} , then we define $VT(A)$ to be the union of the very tight components of A .

Lemma 7.3.1. *If $\epsilon \in \{\pm 1\}$ and $k > 0$ is odd, then $|VT(\check{\Phi}_k^\epsilon)|$ is even.*

Proof. We give $\check{\Phi}_k^\epsilon$ the orientation inherited from a consistent orientation of \tilde{F} . Since k is odd, Proposition 7.2.9 implies that the surface $\check{\Phi}_k^\epsilon$ admits an orientation-reversing free involution τ which permutes the components of $\partial\tilde{F}$. It follows that if T is a very tight component of $\check{\Phi}_k^\epsilon$, then $\tau(T)$ is also a very tight component of $\check{\Phi}_k^\epsilon$, and that τ maps the (connected) frontier of T to the frontier of $\tau(T)$. Since a free orientation-reversing involution of an oriented surface cannot leave any boundary

component invariant, we conclude that no tight component of $\check{\Phi}_k^\epsilon$ can be invariant under τ . Thus the number of tight components must be even. \square

Lemma 7.3.2. *Let $\epsilon \in \{\pm 1\}$ and let k be a non-negative integer. Let T be a very tight component of $\check{\Phi}_k^\epsilon$. Then every component of $\check{\Phi}_{k+1}^\epsilon$ which is contained in T is very tight. Moreover if T contains exactly one component X of $\check{\Phi}_{k+1}^\epsilon$, then T' is ambiently isotopic to T .*

Proof. Since $\partial\tilde{F} \subset \check{\Phi}_k^\epsilon$ is invariant under the homeomorphism \check{h}_k^ϵ , the component $\check{h}_k^\epsilon(T)$ of $\check{\Phi}_k^{(-1)^{k+1}\epsilon}$ is very tight. According to Proposition 7.2.8, $\check{h}_k^\epsilon(\check{\Phi}_{k+1}^\epsilon)$ is ambiently isotopic to the perfect intersection $\check{\Phi}_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_1^{-\epsilon}$.

Thus if X is a component of $\check{\Phi}_{k+1}^\epsilon$ which is contained in T , then $\check{h}_k^\epsilon(X)$ is ambiently isotopic to a component Y of $\check{\Phi}_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_1^{-\epsilon}$. Note that Y is isotopically contained in $\check{h}_k^\epsilon(T)$. According to the definition of s_0 , every tight component of $\check{\Phi}_1^{-\epsilon}$ has size at least s_0 , and $s(T) \leq s_0$ by the definition of a very tight subsurface. Applying Proposition 7.1.8 with $P = \check{\Phi}_k^{(-1)^{k+1}\epsilon}$, $P_0 = \check{h}_k^\epsilon(T)$, and $Q = \check{\Phi}_1^{-\epsilon}$, we conclude that if a component of $\check{\Phi}_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_1^{-\epsilon}$ is isotopically contained in $\check{h}_k^\epsilon(T)$, then it is tight of size at most $s(T)$, and therefore is very tight. This shows that Y is very tight.

Now suppose that T contains exactly one component X of $\check{\Phi}_{k+1}^\epsilon$. Again $\check{h}_k^\epsilon(X)$ is ambiently isotopic to a component Y of $\check{\Phi}_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_1^{-\epsilon}$. Since $X = \check{\Phi}_{k+1}^\epsilon \cap T$, and since $\partial\tilde{F} \subset \check{\Phi}_{k+1}^\epsilon$, we have $T \cap \partial\tilde{F} = X \cap \partial\tilde{F}$. Since $\partial\tilde{F}$ is invariant under the homeomorphism \check{h}_k^ϵ , we have $\check{h}_k^\epsilon(T) \cap \partial\tilde{F} = \check{h}_k^\epsilon(X) \cap \partial\tilde{F} = Y \cap \partial\tilde{F}$. But any component of $\check{\Phi}_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_1^{-\epsilon}$ which is isotopically contained in $\check{h}_k^\epsilon(T)$ must contain some component of $\check{h}_k^\epsilon(T) \cap \partial\tilde{F} \subset Y$. Thus Y is the only component of $\check{\Phi}_k^{(-1)^{k+1}\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_1^{-\epsilon}$ which is isotopically contained in $\check{h}_k^\epsilon(T)$. Proposition 7.1.8 now implies that $\check{h}_k^\epsilon(T)$ is ambiently isotopic to Y , and hence to $\check{h}_k^\epsilon(X)$. Applying the inverse of the homeomorphism \check{h}_k^ϵ , we conclude that X is ambiently isotopic to T . \square

Lemma 7.3.3. *Let $\epsilon \in \{\pm 1\}$ be given and let $l \geq k \geq 0$ be integers. Then each very tight component of $\check{\Phi}_k^\epsilon$ contains at least one very tight component of $\check{\Phi}_l^\epsilon$. In particular $|VT(\check{\Phi}_l^\epsilon)| \geq |VT(\check{\Phi}_k^\epsilon)|$.*

Proof. It suffices to consider the case $l = k + 1$. Since $\check{\Phi}_k^\epsilon \supset \check{\Phi}_{k+1}^\epsilon \supset \partial\tilde{F}$, and since each component of $\check{\Phi}_k^\epsilon$ meets $\partial\tilde{F}$, each component of $\check{\Phi}_k^\epsilon$ must contain at least one component of $\check{\Phi}_{k+1}^\epsilon$. The assertion therefore follows from Lemma 7.3.2. \square

Lemma 7.3.4. *Let $\epsilon \in \{\pm 1\}$ be given and let $l \geq k$ be non-negative integers. If $|VT(\check{\Phi}_l^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)|$, then $VT(\check{\Phi}_l^\epsilon)$ is isotopic to $VT(\check{\Phi}_k^\epsilon)$.*

Proof. If $l > k$ and $|VT(\check{\Phi}_l^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)|$, then by Lemma 7.3.3 we have

$$|VT(\check{\Phi}_k^\epsilon)| = |VT(\check{\Phi}_{k+1}^\epsilon)| = \dots = |VT(\check{\Phi}_l^\epsilon)|.$$

It thus suffices to show that if $|VT(\check{\Phi}_{k+1}^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)|$, then $VT(\check{\Phi}_{k+1}^\epsilon)$ is isotopic to $VT(\check{\Phi}_k^\epsilon)$.

By Lemma 7.3.3, if $|VT(\check{\Phi}_{k+1}^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)|$, then each very tight component of $\check{\Phi}_k^\epsilon$ contains exactly one very tight component of $\check{\Phi}_{k+1}^\epsilon$, and each very tight component of $\check{\Phi}_{k+1}^\epsilon$ is contained in a very tight component of $\check{\Phi}_k^\epsilon$. Thus Lemma 7.3.2 implies that $VT(\check{\Phi}_{k+1}^\epsilon)$ is isotopic to $VT(\check{\Phi}_k^\epsilon)$. \square

Lemma 7.3.5. *Let $\epsilon \in \{\pm 1\}$ and $t \in \mathbb{Z}/m\mathbb{Z}$ be given, and let $k \geq 0$ be an integer. If $c_{\sigma_2^\epsilon(t)}$ is contained in $VT(\check{\Phi}_k^\epsilon)$, then c_t is contained in $VT(\check{\Phi}_{k+2}^\epsilon)$.*

Proof. Let C be the component of $\check{\Phi}_{k+2}^\epsilon$ which contains c_t . Then $\check{h}_2^\epsilon(C)$ is the component of $\check{h}_2^\epsilon(\Phi_{k+2}^\epsilon)$ which contains $c_{\sigma_2^\epsilon(t)}$. Since the embedding \check{h}_2^ϵ maps $\partial\tilde{F}$ to $\partial\tilde{F}$, the subsurface C is very tight if and only if $\check{h}_2^\epsilon(C)$ is very tight. According to Proposition 7.2.8, $\check{h}_2^\epsilon(\Phi_{k+2}^\epsilon)$ is isotopic to the perfect intersection $\check{\Phi}_2^{-\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_k^\epsilon$. By Subsection 7.1.6 $\check{h}_2^\epsilon(C)$ is isotopically contained in a unique component C' of $\check{\Phi}_k^\epsilon$, which must be the component of $\check{\Phi}_k^\epsilon$ that contains $c_{\sigma_2^\epsilon(t)}$. Thus C' is very tight. By Proposition 7.1.8, every component of $\check{\Phi}_2^{-\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_k^\epsilon$ which is contained in C' is very tight. This shows that $\check{h}_2^\epsilon(C)$ is very tight, as required. \square

Lemma 7.3.6. *Let $\epsilon \in \{\pm 1\}$ be given and let $k > 0$ be an odd integer. If $|VT(\check{\Phi}_{k+2}^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)| > 0$, then $\check{\Phi}_{k+2}^\epsilon$ is ambiently isotopic to $\check{\Phi}_k^\epsilon$.*

Proof. Assume that $|VT(\check{\Phi}_{k+2}^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)| > 0$.

By Lemma 7.3.4 we have that $VT(\check{\Phi}_{k+2}^\epsilon)$ is isotopic to $VT(\check{\Phi}_k^\epsilon)$. By Lemma 7.3.5 this implies that if $c_{\sigma_2^\epsilon(t)}$ is contained in $VT(\check{\Phi}_k^\epsilon)$, then so is c_t . Since $VT(\check{\Phi}_k^\epsilon) \neq \emptyset$ it follows that either $c_{\bar{q}} \subset VT(\check{\Phi}_k^\epsilon)$ for every even integer q , or else $c_{\bar{q}} \subset VT(\check{\Phi}_k^\epsilon)$ for every odd integer q . But $VT(\check{\Phi}_k^\epsilon)$ is invariant under the free involution τ_k^ϵ , which maps each boundary curve $c_{\bar{q}}$ to a boundary curve $c_{\bar{r}}$, where q and r have opposite parity. Thus every boundary component of \tilde{F} is contained in $VT(\check{\Phi}_k^\epsilon)$. Since every component of $\check{\Phi}_k^\epsilon$ contains a component of $\partial\tilde{F}$, it follows that $VT(\check{\Phi}_k^\epsilon) = \check{\Phi}_k^\epsilon$. Since $\check{\Phi}_{k+2}^\epsilon \subset \check{\Phi}_k^\epsilon$, and since Lemma 7.3.2 implies that every component of $\check{\Phi}_{k+2}^\epsilon$ which is contained in a tight component of $\check{\Phi}_k^\epsilon$ is tight, we conclude that $VT(\check{\Phi}_{k+2}^\epsilon) = \check{\Phi}_{k+2}^\epsilon$. Hence $\check{\Phi}_k^\epsilon$ is ambiently isotopic to $\check{\Phi}_{k+2}^\epsilon$. \square

Lemma 7.3.7. *Suppose that \tilde{F} is not a semi-fiber. Let $\epsilon \in \{\pm 1\}$ be given and let $k > 0$ be an odd integer. If $|VT(\check{\Phi}_{k+2}^\epsilon)| = |VT(\check{\Phi}_k^\epsilon)| > 0$, then $\check{\Phi}_k^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$.*

Proof. This is an immediate consequence of Proposition 7.2.10 and Lemma 7.3.6. \square

Proposition 7.3.8. *Suppose that \tilde{F} is not a semi-fiber. Let $p > 0$ be an odd integer and suppose that either $\check{\Phi}_p^+$ or $\check{\Phi}_p^-$ has a tight component. Then either $\check{\Phi}_{p+m-2}^+$ or $\check{\Phi}_{p+m-2}^-$ is a regular neighborhood of $\partial\tilde{F}$.*

Proof. We can assume without loss of generality that p is the smallest odd integer such that either $\check{\Phi}_p^+$ or $\check{\Phi}_p^-$ has a tight component. We claim that either $\check{\Phi}_p^+$ or $\check{\Phi}_p^-$ has a very tight component. If $p = 1$, then, by the definition of s_0 , either $\check{\Phi}_1^+$ or $\check{\Phi}_1^-$ has a component of size s_0 , which is very tight by the definition of a very tight

component. If $p > 1$, then $s_0 = \infty$ and any tight component is very tight, so the claim is true in this case as well.

Now fix $\epsilon \in \{\pm 1\}$ such that $\check{\Phi}_p^\epsilon$ has a very tight component. It follows from Lemma 7.3.1 that $|VT(\check{\Phi}_p^\epsilon)| \geq 2$. We will show that $\check{\Phi}_{p+m-2}^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$. If there is an even integer k with $0 < k < m-2$ such that $\check{\Phi}_{p+k}^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$, then the conclusion holds because $\partial\tilde{F} \subset \check{\Phi}_{p+m-2}^\epsilon \subset \check{\Phi}_{p+k}^\epsilon$.

Now suppose that there is no even integer k with $0 < k < m-2$ such that $\check{\Phi}_{p+k}^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$. Since \tilde{F} is not a semi-fiber, for all even k with $0 < k < m-2$ we have that $|VT(\check{\Phi}_{p+k+2}^\epsilon)| > |VT(\check{\Phi}_{p+k}^\epsilon)|$ by Lemma 7.3.3 and Lemma 7.3.7, and hence, by Lemma 7.3.1, that $|VT(\check{\Phi}_{p+k+2}^\epsilon)| \geq |VT(\check{\Phi}_{p+k}^\epsilon)| + 2$. Since $|VT(\check{\Phi}_p^\epsilon)| \geq 2$ it follows that $|VT(\check{\Phi}_{p+m-2}^\epsilon)| \geq m$.

In particular $\check{\Phi}_{p+m-2}^\epsilon$ has at least m tight components. Each tight component has size at least 1, and the sum of the sizes is at most $m = |\partial\tilde{F}|$. Thus $\check{\Phi}_{p+m-2}^\epsilon$ has m tight components of size exactly 1, which are therefore regular neighborhoods of components of $\partial\tilde{F}$. Since $\check{\Phi}_{p+m-2}^\epsilon$ is perfect it must be a regular neighborhood of $\partial\tilde{F}$. □

Corollary 7.3.9. *Suppose that \tilde{F} is not a semi-fiber. Let $p > 0$ be an odd integer and suppose that either $\check{\Phi}_p^+$ or $\check{\Phi}_p^-$ has a tight component. Then both $\check{\Phi}_{p+m-1}^+$ and $\check{\Phi}_{p+m-1}^-$ are regular neighborhoods of $\partial\tilde{F}$.*

Proof. By Proposition 7.3.8 we know that, for some $\epsilon \in \{\pm 1\}$, $\check{\Phi}_{p+m-2}^\epsilon$ is a regular neighborhood of $\partial\tilde{F}$. Since the $\check{\Phi}_k^\epsilon$ are nested perfect surfaces, $\check{\Phi}_{p+m-1}^\epsilon$ is also a regular neighborhood of $\partial\tilde{F}$. By Proposition 7.2.8 the subsurface $\check{\Phi}_{p+m-1}^{-\epsilon}$ is mapped homeomorphically by $\check{h}_1^{-\epsilon}$ to $\check{\Phi}_1^{-\epsilon} \wedge_{\mathcal{P}} \check{\Phi}_{p+m-2}^\epsilon$, which is isotopically contained in $\check{\Phi}_{p+m-2}^\epsilon$. Since $\partial\tilde{F}$ is invariant under $\check{h}_1^{-\epsilon}$ it follows that $\check{\Phi}_{p+m-1}^{-\epsilon}$ is a regular neighborhood of $\partial\tilde{F}$. □

7.4. Planar essential surfaces and their boundary slopes.

Theorem 7.4.1. *Let F be an essential planar surface in a simple knot manifold M . Suppose that F is not a semi-fiber. Set $m = |\partial F|$ and let H be any reduced homotopy in the pair (M, F) such that H_0 is an essential path in F and $H_t(\partial I) \subset \partial M$ for each $t \in I$. Then the length of H is at most $m - 1$.*

Proof. We shall assume that the length of H is at least m and derive a contradiction.

Let \tilde{F} be the splitting surface associated to F (see Subsection 5.4.2). Set $\tilde{m} = |\partial\tilde{F}|$, so $\tilde{m} = m$ if F is separating and $\tilde{m} = 2m$ if F is non-separating. The homotopy H determines a reduced homotopy \tilde{H} in the pair (M, \tilde{F}) of length at least \tilde{m} such that \tilde{H}_0 is an essential path in \tilde{F} and $\tilde{H}_t(\partial I) \subset \partial M$ for each $t \in I$. In particular, \tilde{F} admits a long rectangle. Thus the assumptions of Subsections 6.1 and 7.2 hold in our situation and we may use the notation and apply the results from those subsections.

Since the surface F is not a semi-fiber, it follows that \tilde{F} is also not a semi-fiber and hence, by Proposition 5.3.9, that there exists $\epsilon \in \{\pm 1\}$ such that \tilde{F} is not a regular neighborhood of Φ_1^ϵ . This implies that $\check{\Phi}_1^\epsilon$ is a proper subsurface of \tilde{F} . Thus Proposition 7.1.9 implies that $\check{\Phi}_1^\epsilon$ has a tight component. We conclude from

Proposition 7.3.8 that $\check{\Phi}_m^+$ and $\check{\Phi}_m^-$ are regular neighborhoods of $\partial\tilde{F}$. Hence $\dot{\Phi}_m^+$ and $\dot{\Phi}_m^-$ are empty.

On the other hand, since the reduced homotopy \tilde{H} has length at least \tilde{m} , it follows from Subsection 3.4 and Proposition 5.2.8 that there is an admissible pair of glasses $\gamma : \Gamma \rightarrow \tilde{F}$ which is homotopic in \tilde{F} to a map from Γ to Φ_m^ϵ . In particular there is a map $\alpha : S^1 \rightarrow \partial\tilde{F}$ which is homotopic in \tilde{F} to a map from S^1 to a component A of Φ_m^ϵ . It follows that A must be an outer component of Φ_m^ϵ , and hence that $\dot{\Phi}_m^\epsilon \neq \emptyset$. This contradiction completes the proof. \square

Theorem 7.4.2. *Let M be a simple knot manifold and let $F \subset M$ be an essential planar surface with boundary slope β which is not a semi-fiber. Let (S, X, h) be a singular surface which is well positioned with respect to F and has boundary slope α . Set $s = \text{genus } S$, $n = |\partial S - X|$, $v = |X|$. Then*

$$\Delta(\alpha, \beta) \leq N(s, n, v).$$

Proof. Set $m = |\partial F|$. According to Proposition 3.9, there exists an essential homotopy $H : I \times I \rightarrow M$ having length

$$(1) \quad l \geq \frac{m\Delta(\alpha, \beta)}{N(s, n, v)} - 1,$$

such that H_0 is an essential path in F and $H_t(\partial I) \subset \partial M$ for all $t \in I$. By Theorem 7.4.1 we have that

$$(2) \quad l \leq m - 1.$$

The conclusion follows from inequalities (1) and (2). \square

Corollary 7.4.3. *Let M be a simple knot manifold, and let $F \subset M$ be an essential planar surface with boundary slope β which is not a semi-fiber. Let α be a slope in ∂M . If $M(\alpha)$ is very small, or more generally if $F \subset M \subset M(\alpha)$ is not π_1 -injective in $M(\alpha)$, then*

$$\Delta(\alpha, \beta) \leq 5.$$

Proof. We invoke Corollary 2.3 to obtain a singular surface (S, X, h) , well positioned with respect to F , such that *genus* $S = 0$ and $|X| = 1$. The conclusion now follows from Theorem 7.4.2 because for any $v \geq 1$ we have $N(0, 1, v) \leq 5$. \square

Corollary 7.4.4. *Let M be a simple knot manifold. Suppose that $M(\beta)$ is a reducible manifold which is not homeomorphic to $S^1 \times S^2$ or $P^3 \# P^3$ and that $M(\alpha)$ is very small. Then*

$$\Delta(\alpha, \beta) \leq 5.$$

Proof. Since $M(\beta)$ is reducible, M contains an essential planar surface F with boundary slope β . If F is a semi-fiber, then $M(\beta)$ is homeomorphic to either $S^1 \times S^2$ or $P^3 \# P^3$. Thus the corollary follows from Corollary 7.4.3. \square

Corollary 7.4.5. *Let M be a simple knot manifold, and let $F \subset M$ be an essential planar surface with boundary slope β which is not a semi-fiber. Let α be a slope in ∂M . If $M(\alpha)$ is a Seifert fibered space or if there exists a π_1 -injective map from $S^1 \times S^1$ to $M(\alpha)$, then*

$$\Delta(\alpha, \beta) \leq 6.$$

Proof. We invoke Corollary 2.6 to obtain a singular surface (S, X, h) , well positioned with respect to F , such that either $\text{genus } S = 0$ and $|X| = 1$, or $\text{genus } S = 1$ and $|X| = 0$. The conclusion now follows from Theorem 7.4.2 because for any $v \geq 1$ we have $N(0, 1, v) \leq 5$ and $N(1, 0, v) = 6$. \square

Corollary 7.4.6. *Let M be a simple knot manifold. Suppose that $M(\beta)$ is a reducible manifold which is not homeomorphic to $S^1 \times S^2$ or $P^3 \# P^3$ and that $M(\alpha)$ is Seifert fibered. Then*

$$\Delta(\alpha, \beta) \leq 6.$$

Proof. As in the proof of Corollary 7.4.4 we apply Corollary 7.4.5 to the planar surface obtained by intersecting a reducing sphere for $M(\beta)$ with M . \square

The following corollary to Theorem 7.4.2 is a special case of a result of Gordon and Litherland [GLi, Proposition 6.1], which has the same upper bound, but with a strict inequality and without the assumption that the essential planar surface is not a semi-fiber.

Corollary 7.4.7. *Let M be a simple knot manifold, and let $F \subset M$ be an essential planar surface with boundary slope β which is not a semi-fiber. Suppose that $S \subset M$ is an essential bounded surface of genus g with boundary slope α . Set $m = |\partial S|$. Then we have*

$$\Delta(\alpha, \beta) \leq \left\lceil \frac{12g - 12}{m} \right\rceil + 6.$$

Proof. We apply Proposition 2.1 to obtain a singular surface $(S', \partial S', h)$ which is well positioned with respect to F . Theorem 7.4.2 then implies that

$$\Delta(\alpha, \beta) \leq N(g, 0, m).$$

Note that since M is a simple knot manifold, the surface S' cannot be a disk or an annulus. It then follows from Subsection 3.7 that

$$N(s, n, v) = \left\lceil \frac{12g - 12}{m} \right\rceil + 6.$$

\square

8. SEIFERT FIBERED SURGERIES

According to Corollary 7.4.6, if M is a simple knot manifold and if α and β are slopes such that $M(\alpha)$ is Seifert fibered while $M(\beta)$ is reducible but is not $S^1 \times S^2$ or $P^3 \# P^3$, then $\Delta(\alpha, \beta) \leq 6$. In fact we know of no examples where $\Delta(\alpha, \beta) > 3$. In this section, building on Corollary 7.4.6, we prove a result, Proposition 8.4, which gives restrictions on the possible Seifert fibrations of $M(\alpha)$ in the cases where $\Delta(\alpha, \beta) > 3$, which shows that this situation is not generic. The proof uses the character variety of M and some observations from algebraic number theory. We will see that in the generic situation, 3 is an upper bound for the distance between α and β . A similar result, Proposition 8.7 applies to the case where $M(\alpha)$ is a Seifert fibered space that contains an incompressible torus, $M(\alpha)$ is Seifert fibered and $\Delta(\alpha, \beta) > 5$. Here, in place of Corollary 7.4.6 we use a theorem of Agol [A] and Lackenby [La] which implies that $\Delta(\alpha, \beta) \leq 10$ in this situation.

For any integer $n \geq 1$, we set $\zeta_n = e^{\frac{2\pi i}{n}}$.

Lemma 8.1. *Let $m, n \geq 1$ be integers. If $\zeta_n + \bar{\zeta}_n \in \mathbb{Q}(\zeta_m)$, then one of the following three conditions holds:*

- (i) $n \in \{1, 2, 3, 4, 6\}$.
- (ii) n divides m .
- (iii) $\frac{n}{2}$ is an odd integer dividing m .

Proof. Without loss of generality we take $n \notin \{1, 2, 3, 4, 6\}$, so $\zeta_n + \bar{\zeta}_n \notin \mathbb{Q}$. Let $d = \gcd(n, m)$. By hypothesis

$$\zeta_n + \bar{\zeta}_n \in \mathbb{Q}(\zeta_m) \cap \mathbb{Q}(\zeta_n) = \mathbb{Q}(\zeta_d)$$

([FT, VI.2.8]) so that $\zeta_n + \bar{\zeta}_n \in \mathbb{Q}(\zeta_d)_{\mathbb{R}}$. Thus

$$\mathbb{Q}(\zeta_n)_{\mathbb{R}} = \mathbb{Q}(\zeta_n + \bar{\zeta}_n) \subset \mathbb{Q}(\zeta_d)_{\mathbb{R}}.$$

But clearly $\mathbb{Q}(\zeta_d)_{\mathbb{R}} \subset \mathbb{Q}(\zeta_n)_{\mathbb{R}}$ and therefore $\mathbb{Q}(\zeta_d)_{\mathbb{R}} = \mathbb{Q}(\zeta_n)_{\mathbb{R}}$. Since $\zeta_n + \bar{\zeta}_n \notin \mathbb{Q}$, we have $d, n > 2$. Moreover, since $[\mathbb{Q}(\zeta_k + \bar{\zeta}_k) : \mathbb{Q}] = \frac{\phi(k)}{2}$ if $k > 2$ (cf. [FT, Theorem 44]), we have $\phi(n) = \phi(d)$. Finally since $d|n$, either $d = n$ or d is odd and $2d = n$. In other words either n divides m or n is even, $\frac{n}{2}$ is odd and n divides $2m$. \square

In what follows we let

$$\Delta(a, b, c) = \langle x, y \mid x^a, y^b, (xy)^c \rangle$$

denote the (a, b, c) triangle group.

Lemma 8.2. *Let $\rho: \Delta(a, b, c) \rightarrow PSL_2(\mathbb{C})$ be a homomorphism and suppose that the image of ρ contains an element of order $n < \infty$. Then either $n \in \{1, 2, 3\}$ or n divides the least common multiple of a, b, c .*

Proof. There are matrices $A, B, C \in SL_2(\mathbb{C})$ whose orders divide $2a, 2b, 2c$, respectively, so that $\rho(x) = \pm A, \rho(y) = \pm B, \rho(xy) = \pm C$. Then $\text{trace}(A) = \zeta_{2a}^j + \bar{\zeta}_{2a}^j$, $\text{trace}(B) = \zeta_{2b}^k + \bar{\zeta}_{2b}^k$ and $\text{trace}(C) = \zeta_{2c}^l + \bar{\zeta}_{2c}^l$ for some integers j, k, l . Since the trace of any word in A, B is an integral polynomial in the traces of A, B and C [CS, proof of proposition 1.4.1], such a trace lies in the field $\mathbb{Q}(\zeta_{2a}, \zeta_{2b}, \zeta_{2c}) = \mathbb{Q}(\zeta_h)$ where $h = 2\text{lcm}(a, b, c)$ [FT, VI.2.8].

Let $W \in SL_2(\mathbb{C})$ be a matrix of order $2n$ whose image $[W]$ in $PSL(2, \mathbb{C})$ is an element of order n in the image of ρ . Then $\text{trace}(W) = \zeta_{2n}^m + \bar{\zeta}_{2n}^m$ for some m relatively prime to $2n$. Fix a word w so that the element $w(x, y) \in \Delta(a, b, c)$ satisfies $[W] = \rho(w(x, y)) = [w(A, B)]$. Then by the previous paragraph we have

$$\zeta_{2n}^m + \bar{\zeta}_{2n}^m = \text{trace}(W) \in \{\pm \text{trace}(w(A, B))\} \subset \mathbb{Q}(\zeta_h).$$

As m is relatively prime to $2n$ we have

$$\zeta_{2n} + \bar{\zeta}_{2n} \in \mathbb{Q}(\zeta_{2n}^m)_{\mathbb{R}} = \mathbb{Q}(\zeta_{2n}^m + \bar{\zeta}_{2n}^m) \subset \mathbb{Q}(\zeta_h).$$

Lemma 8.1 now yields the desired conclusion. \square

Lemma 8.3. *Let M be a simple knot manifold. Fix slopes α and β on ∂M . Suppose that $M(\beta)$ is a connected sum of two lens spaces whose fundamental groups have orders $p, q \geq 2$, and that $M(\alpha)$ is a Seifert fibered space whose base orbifold has the form $S^2(a, b, c)$ where $a, b, c \geq 2$. If $\Delta(\alpha, \beta) > 3$, then $\Delta(\alpha, \beta)$ divides $\text{lcm}(a, b, c)$.*

Proof. Fix a point on ∂M so that we have homomorphisms $H_1(\partial M) \cong \pi_1(\partial M) \rightarrow \pi_1(M)$. In this way each slope r on ∂M determines an element $\gamma(r)$ of $\pi_1(M)$ well defined up to taking an inverse.

There is a curve X_0 contained in the $PSL_2(\mathbb{C})$ -character variety of $\pi_1(M)$ containing the character of an irreducible representation and consisting of characters χ_ρ of representations $\rho: \pi_1(M) \rightarrow PSL_2(\mathbb{C})$ which factor through $\pi_1(M(\beta)) \cong \mathbb{Z}/p * \mathbb{Z}/q$ [BZ, Example 3.2]. For each slope r let $f_r: X_0 \rightarrow \mathbb{C}$ be the regular function $f_r(\chi_\rho) = \text{trace}(\rho(\gamma(r)))^2 - 4$. Evidently f_β is identically zero. We claim that for each $r \neq \beta$ and ideal point x of X_0 , f_r has a pole at x . If this were not the case, there would be a closed essential surface $S \subset M$ which remains essential in either $M(\beta)$ or $M(\alpha)$ [BZ, Proposition 4.10]. But S compresses in both $M(\beta)$ and $M(\alpha)$. This is obvious for $M(\beta)$, while if S is essential in $M(\alpha)$, then S is a fiber in some realization of $M(\alpha)$ as a surface bundle over the circle (see eg. [Ja, VI.34]) and so it is non-separating in M . But then $b_1(M) \geq 2$, contrary to the fact that $b_1(M(\beta)) = 0$. Thus S compresses in $M(\alpha)$ and therefore f_r has a pole at x .

Let r be a slope so that $\Delta(r, \beta) = 1$. From the previous paragraph there is a character $\chi_\rho \in X_0$ at which f_r takes the value $(e^{\pi i/\Delta(\alpha, \beta)} + e^{-\pi i/\Delta(\alpha, \beta)})^2$. The representation ρ may be taken to factor through $\pi_1(M(\beta))$ and to have a non-diagonalisable image (cf. the method of proof of [CGLS, Lemma 1.5.10]). Since $\Delta(\alpha, \beta) > 1$, $\rho(\gamma(r))$ has order $\Delta(\alpha, \beta)$, while by construction $\rho(\gamma(\beta)) = \pm I$. It follows that $\rho(\gamma(\alpha)) = \pm I$ and therefore ρ factors through a representation $\rho_1: \pi_1(M(\alpha)) \rightarrow PSL_2(\mathbb{C})$. In fact, ρ further factors through $\pi_1^{orb}(S^2(a, b, c)) \cong \Delta(a, b, c)$. To see this, first observe that since $b_1(M) = 1$, χ_ρ is a non-trivial character [B, Proposition 2.8] and therefore [BB, Lemma 3.1] implies that ρ factors as claimed. In conclusion we have produced a homomorphism $\Delta(a, b, c) \rightarrow PSL_2(\mathbb{C})$ which contains an element of order $\Delta(\alpha, \beta) > 3$ in its image. Apply Lemma 8.2 to see that $\Delta(\alpha, \beta)$ divides $lcm(a, b, c)$. \square

Proposition 8.4. *Let M be a simple knot manifold and fix slopes α and β on ∂M . Suppose that $M(\beta)$ is reducible, but not homeomorphic to $S^1 \times S^2$ or $P^3 \# P^3$, and that $M(\alpha)$ is a Seifert fibered manifold. If $\Delta(\alpha, \beta) > 3$, then*

- (i) $M(\beta)$ is a connected sum of two lens spaces.
- (ii) $M(\alpha)$ admits a Seifert structure whose base orbifold is the 2-sphere with exactly three exceptional fibers whose orders a, b, c are either a Platonic or hyperbolic triple.
- (iii) $\Delta(\alpha, \beta)$ is equal to 4, 5 or 6 and divides $lcm(a, b, c)$.

Proof. We first show that $\Delta(\alpha, \beta) \leq 1$ when $b_1(M) \geq 2$. In this case, according to [Ga], the slope β is the unique degenerating slope for a closed non-separating essential surface S_* (which is Thurston norm minimizing in the homology class it represents) of genus larger than 1 in M , i.e. S_* will remain incompressible in $M(\delta)$ for any slope δ except for $\delta = \beta$. Hence the irreducible manifold $M(\alpha)$ cannot be very small. If it is Seifert fibered we have $\Delta(\alpha, \beta) \leq 1$ by [BGZ, Proposition 5.1].

We may therefore assume that $b_1(M) = 1$. If $M(\alpha)$ contains an embedded incompressible torus, then $\Delta(\alpha, \beta) \leq 3$ by [O], [Wu]. If $M(\alpha)$ is geometrically atoroidal, then it admits a Seifert structure with three or fewer exceptional fibers and whose base orbifold has the 2-sphere for underlying space. When there are no more than two exceptional fibers it is known that $\Delta(\alpha, \beta) \leq 1$ [BZ, Theorem 1.2(1)], while if the base orbifold of $M(\alpha)$ has the form $S^2(a, b, c)$ where $a, b, c \geq 2$ it is known that $\Delta(\alpha, \beta) \leq 3$ if (a, b, c) is a Euclidean triple [B, Theorem C]. Thus

(ii) holds. By [CGLS, Theorem 2.0.3] $M(\beta)$ is a connected sum of two lens spaces, so (i) holds. Finally (iii) is a consequence of Corollary 7.4.6 and Lemma 8.3. \square

Corollary 8.5. *Let M be a simple knot manifold and fix slopes α and β on ∂M . If $M(\beta)$ is reducible, though not $S^1 \times S^2$ or $P^3 \# P^3$, and $M(\alpha)$ is a Seifert fibered space, then $\Delta(\alpha, \beta) \leq 5$ unless perhaps $M(\beta) \cong P^3 \# L(p, q)$ and $M(\alpha)$ is a small Seifert manifold with base orbifold $S^2(a, b, c)$ where (a, b, c) is a hyperbolic triple and 6 divides $\text{lcm}(a, b, c)$.*

Proof. The corollary follows from Theorem 7.4.6, the previous proposition and the fact that $\Delta(\alpha, \beta) \leq 5$ if (a, b, c) is a Platonic triple [BZ, Theorem 1.2(2)]. \square

There is another situation where we can use the same method to sharpen the known distance bounds.

Lemma 8.6. *Let M be a simple knot manifold and fix slopes α and β on ∂M . Suppose that $M(\beta)$ is a Seifert fibered manifold which contains an embedded incompressible torus and that $M(\alpha)$ admits a Seifert fibration whose base orbifold has the form $S^2(a, b, c)$, where $a, b, c \geq 2$. If $\Delta(\alpha, \beta) > 5$, then $\Delta(\alpha, \beta)$ divides $\text{lcm}(a, b, c)$.*

Proof. By [BGZ, Theorems 1.1 and 1.7] we may assume that $b_1(M) = 1$ and that $M(\beta)$ has base orbifold a Klein bottle, $S^2(2, 2, 2, 2)$, or $P^2(p, q)$ for some integers $p, q \geq 2$. In each case there is a curve $X_0 \subset X(\pi_1(M))$ containing the character of an irreducible representation and consisting of characters of representations $\rho: \pi_1(M) \rightarrow PSL_2(\mathbb{C})$ which factor through $\pi_1(M(\beta))$ [BZ, Lemma 8.7]. If for some slope $r \neq \beta$ on ∂M and ideal point x of X_0 , f_r is finite at x , then there is a closed, essential surface $S \subset M$ which is incompressible in at least one of $M(\beta)$ and $M(\alpha)$ [BZ, Proposition 4.10]. It was shown in [BZ, Claim, page 786] that S compresses in $M(\beta)$, so it must be essential in $M(\alpha)$. But this would imply that $b_1(M) \geq 2$, contrary to our assumptions (cf. the proof of Lemma 8.3). Thus for each slope $r \neq \beta$ on ∂M , the function f_r has a pole at each ideal point x of X_0 . We now proceed as in the last paragraph of the proof of Lemma 8.3 to see that $\Delta(\alpha, \beta)$ divides $\text{lcm}(a, b, c)$. \square

Proposition 8.7. *Let M be a simple knot manifold and fix slopes α and β on ∂M . Suppose that $M(\beta)$ is a Seifert fibered manifold that contains an embedded incompressible torus, but is not homeomorphic to the union of two twisted I -bundles over Klein bottles, and that $M(\alpha)$ is a Seifert fibered manifold. If $\Delta(\alpha, \beta) > 5$, then*

(i) $M(\beta)$ admits a Seifert fibration over P^2 with exactly two exceptional fibers whose orders are p and q for some integers $p > q \geq 2$.

(ii) $M(\alpha)$ admits a Seifert fibration over the 2-sphere with exactly three exceptional fibers whose orders a, b, c form either a hyperbolic triple or the Euclidean triple 2, 3, 6.

(iii) $\Delta(\alpha, \beta) \in \{6, 7, 8, 9, 10\}$ and $\Delta(\alpha, \beta)$ divides $\text{lcm}(a, b, c)$.

Proof. By [BGZ, Theorems 1.1 and 1.7] we may assume that $b_1(M) = 1$ and that $M(\beta)$ has base orbifold of the form K , the Klein bottle, $S^2(2, 2, 2, 2)$, or $P^2(p, q)$ for some integers $p, q \geq 2$. Since $M(\beta)$ is not the union of two twisted I -bundles over the Klein bottle, its base orbifold must be of the form $P^2(p, q)$ for some integers $p > q \geq 2$. Thus (i) holds.

Next observe that if $M(\alpha)$ contains an incompressible torus, then it is shown in [Go2] that $\Delta(\alpha, \beta) \leq 5$. Thus $M(\alpha)$ admits a Seifert structure whose base orbifold \mathcal{B} is a 2-sphere with three or fewer cone points. Theorem 1.5 of [BZ] shows that $\mathcal{B} = S^2(a, b, c)$, where (a, b, c) is a Euclidean or hyperbolic triple. The former possibility is ruled out as in the proof of Theorem C of [B] unless a, b, c is the Euclidean triple 2, 3, 6. Finally by [A] or [La], $\Delta(\alpha, \beta) \in \{6, 7, 8, 9, 10\}$ and the previous lemma shows that it divides $lcm(a, b, c)$. \square

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